SYSMAC

Smart Active Parts

REFERENCE MANUAL

OMRON

How to use Smart Active Parts

Notice

OMRON products are manufactured for use according to proper procedures by a qualified operator and only for the purposes described in this manual.

The following conventions are used to indicate and classify precautions in this manual. Always heed the information provided with them. Failure to heed precautions can result in injury to people or damage to property.

OMRON Product References

All OMRON products are capitalized in this manual. The word "Unit" is also capitalized when it refers to an OMRON product, regardless of whether or not it appears in the proper name of the product.

The abbreviation "Ch," which appears in some displays and on some OMRON products, often means "word" and is abbreviated "Wd" in documentation in this sense.

The abbreviation "PLC" means Programmable Controller.

The abbreviation "host" means a controller, such as an IBM PC/AT or compatible computer, that controls a PT (Programmable Terminal).

Visual Aids

The following headings appear in the left column of the manual to help you locate different types of information.

Note	Indicates information of particular interest for efficient and convenient operation of the product.
Reference	Indicates supplementary information on related topics that may be of interest to the user.
1, 2, 3	1. Indicates lists of one sort or another, such as procedures, checklists, etc.
CS1G-CPU@@-VI	Boxes in model numbers indicate variable characters. For example, "CS1G-CPU@@-EV1" indicates the following models: CS1G-CPU42-EV1, CS1G-CPU43-EV1, CS1G-CPU44-EV1, and CS1G-CPU45-EV1.

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No patent liability is assumed with respect to the use of the information contained herein. Moreover, because OMRON is constantly striving to improve its high-quality products, the information contained in this manual is subject to change without notice. Every precaution has been taken in the preparation of this manual. Nevertheless, OMRON assumes no responsibility for errors or omissions. Neither is any liability assumed for damages resulting from the use of the information contained in this publication.

Intended Audience

This manual is intended for the following personnel, who must also have knowledge of electrical systems (an electrical engineer or the equivalent).

- Personnel in charge of introducing FA systems into production facilities.
- Personnel in charge of designing FA systems.
- Personnel in charge of installing and connecting FA systems.
- Personnel in charge of managing FA systems and facilities.

General Precautions

- The user must operate the product according to the performance specifications described in the operation manuals.
- Do not use the PT touch switch input functions for applications where danger to human life or serious property damage is possible, or for emergency switch applications.
- Before using the product under conditions which are not described in the manual or applying the product to nuclear control systems, railroad systems, aviation systems, vehicles, combustion systems, medical equipment, amusement machines, safety equipment, and other systems, machines and equipment that may have a serious influence on lives and property if used improperly, consult your OMRON representative.
- Make sure that the ratings and performance characteristics of the product are sufficient for the systems, machines, and equipment, and be sure to provide the systems, machines, and equipment with double safety mechanisms.
- This manual provides information for connecting and setting up an NS-series PT. Be sure to read this manual before attempting to use the PT and keep this manual close at hand for reference during installation and operation.

Safety Precautions

∕ MARNING

Do not attempt to take the Unit apart and do not touch any internal parts while the power is being supplied. Doing either of these may result in electrical shock.



Operating Environment Precautions

- 1. Do not install the Unit in the following places:
 - · Locations subject to direct sunlight
 - Locations subject to temperatures or humidity outside the range specified in the specifications
 - Locations subject to condensation as the result of severe changes in temperature
 - Locations subject to corrosive or flammable gases
 - Locations subject to dust (especially iron dust) or salts
 - Locations subject to exposure to water, oil, or chemicals
 - Locations subject to shock or vibration
- 2. Take appropriate and sufficient countermeasures when installing systems in the following locations:
 - Locations subject to static electricity or other forms of noise
 - Locations subject to strong electromagnetic fields
 - Locations subject to possible exposure to radioactivity
 - Locations close to power supplies

Application Precautions

- 1. When unpacking the Units, check carefully for any external scratches or other damage. Also, shake the Units gently and check for any abnormal sound.
- 2. The mounting panel must be between 1.6 and 4.8 mm thick. Tighten the Mounting Brackets evenly to a torque of between 0.5 and 0.6 N·m to maintain water and dust resistance. Make sure the panel is not dirty or warped and that it is strong enough to hold the Units.
- 3. Do not let metal particles enter the Units when preparing the panel.
- 4. If conformance to EC Directives (Low Voltage Directive) is required, use reinforced insulation for the power supplies.
- 5. Do not connect an AC power supply to the power terminals.
- 6. Use a DC power supply with minimal fluctuation voltage.

Rated power supply voltage: 24 VDC

(Allowable range: 20.4 to 27.6 VDC)

Capacity: 25 W min. (NS5: 15 W min.)

- 7. Do not perform a dielectric voltage test.
- 8. Use a twisted-pair cable with a cross-sectional area of at least 2 mm² to connect to the power terminals and always use M3.5 crimp terminals. Tighten the terminal screws to a torque of 0.8 N·m. Make sure the screws are properly tightened.
- 9. Ground the Unit correctly to prevent operational errors caused by noise.
- 10. Do not touch the surface of the circuit board or the components mounted on it with your bare hands. Discharge any static electricity from your body before handling the board.
- 11. Confirm that the current capacity of the connected device is 250 mA or less before using the 5-V power supply from pin 6 of the serial port A, B connectors. The 5-V output of the PT is 250 mA max. at 5 V \pm 5%.
- 12. Turn OFF the power supply before connecting or disconnecting cables.
- 13. Always tighten the connector screws after connecting communications cables.
- 14. The maximum tensile load for cables is 30 N. Do not apply loads greater than this.
- 15. Confirm the safety of the system before turning ON or OFF the power supply or before pressing the reset button.
- 16. The whole system may stop depending on how the power supply is turned ON or OFF. Turn ON or OFF the power supply according to the specified procedure.
- 17. Start actual system application only after sufficiently checking screen data. macros, and the operation of the program in the PC (host).
- 18. Always reset the power supply after changing switch settings.
- 19. After changing the settings of the DIP switch, always turn the power supply OFF and ON or reset the PT.
- 20. Do not perform the following operations while the Memory Card is being accessed:
 - Turning OFF the power supply to the PT
 - Pressing the PT's reset switch
 - Removing the Memory Card
 - Always following the specified procedure when removing the Memory Card.

- 21. Do not press the touch switch with a force greater than 30 N.
- 22. Confirm the safety of the system before pressing touch switches.
- 23. Do not accidentally press touch switches when the backlight is not lit or when the display does not appear.
- 24. Signals from the touch switches may not be input if the switches are pressed consecutively at high speed. Confirm each input before proceeding to the next one.
- 25. Before initializing screen data, confirm that existing data is backed up at the NS-Designer.
- 26. When changing the password with the system menu, do not reset or turn OFF the power supply until writing is finished (i.e., until the Write Button returns to its original condition). It may become impossible to manipulate screens if the password is not set correctly.
- 27. When using the device monitor, confirm the safety of the system before performing the following operations.
 - Changing monitor data
 - Changing operation modes
 - Forced setting or resetting
 - Changing present values or set values
- 28. Do not use benzene, paint thinner, or other volatile solvents, and do not use chemically treated cloths.
- 29. Dispose of any battery that has been dropped on the floor or otherwise subjected to excessive shock.
- 30. Do not attempt to disassemble, repair, or modify the Unit in any way.
- 31. Dispose of the Units and batteries according to local ordinances as they apply.
- 32. To ensure system safety, incorporate a program that periodically calls PT operation bits from the host side to check that the PT is properly operating.
- 33. Do not connect an USB connector to any device that is not applicable.
- 34. Before connecting an USB connector to a device, make sure that the device is free of damage.
- 35. When mounting the Battery, be sure to use the correct Battery and mount it correctly.

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Section 3 Precautions for Editing Smart Active Parts

Description of Smart Active Parts

- **♦** PLC
- **♦** Communication Unit
- **♦** Motion Control
- **♦** nverter
- **♦** Servo Driver
- **♦** Temperature Controller (E5ZN)

(E5□R)

(E5□N)

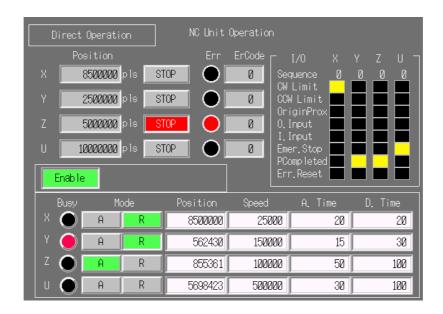
(from Ver5 or earlier)

- **♦** DRT2
- **◆ Process Controller**

Section 1 Overview

1-1 What are Smart Active Parts?

Smart Active Parts are generic name of OMRON unique libraries contained setting/monitor screens (E.g. NC Units and Temperature Controllers). Users can make setting/monitor screens simply reusing Smart Active Parts which should have created according to Units for PLC before. Since Smart Active Parts are the sophisticated libraries which include communication settings, refer to Section 3 precautions for use of Smart Active Parts.



■ Features

Smart Active Parts has the following features.

- Smart Active Parts have communication functions so that no communication programs are required (Programless communication) to communicate with units (Temperature Controller, NC Unit, DRT2 etc...).
- Smart Active Parts can be reused from the Use Library under Tools in the NS-Designer. All
 communication addresses for setting/monitor screens are automatically set just specifying Match
 No. or Unit No. of destination when reusing it. It is not necessary to check those using manuals as
 ever.
- Setting/monitor screens for NC and DRT2 can be created simply combining device libraries so that they work like the dedicated tools, such as CX-Position and Configurator, with PT.

Section 2 Procedure for Reusing Smart Active Parts

2-1 The following smart active parts are provided

New Smart Active Parts added in Ver6.0.

1. CS/CJ and CS1D CPU Unit

Error Log Monitor, CS1D Online exchange button, Online Battery change button.

2. Serial Communication board/Unit

Communication Status Display (Error Monitor), Port Settings etc.

3. Ethernet Unit/CLK Unit

Network Status (Error Monitor, Network node status) etc.

4. MC/MCH Unit

JOG Running, Search Zero position, Program running, Error Display, I/O Status Monitor, PV Monitor etc5. NC /NCF Unit

JOG Running, Direct Running, Memory Running, (Only NC), Error Display, I/O Status Monitor, PV Monitor etc.6. Servo (R88D-WT, R7D-AP)- using new SCU/SCB board.

PV Monitor, Parameter settings, Error Display, Driver info Display, I/O Status Monitor etc.

7. Device Net (DRT2-xx)

Models integrated in one SMART Active Parts.DRT2 maintenance/Status info, IN/OUT Info. Etc.

8. Temperature Controller (E5[]R, E5ZN, E5[]N)- Direct Connection with NS.

Run Monitor, PID Settings, SP settings, Alarm Settings, Input correction settings etc.

9. Invertor

Rotation Speed/Monitoring Output Frequency, Other Parameter Settings. etc.

Also includes the previous Smart Active Parts which are in Ver5.0 or earlier.

1. CJ1M

Functions for Built-in Input Setting, Origin Search and Origin Return

2. DRT2

ID16/ID16S/ID08/ID08C/HD16C/OD16/OD08/OD08C

3. DeviceNet, E5ZN

PID Setting, Commands, SP Setting, Setting Area 0, and Front Panel

Network Monitor

4. CLK Network Status Monitor and DeviceNet Status Monitor

5. NC Unit

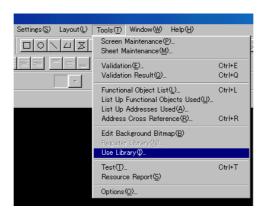
Direct Operation, JOG Operation, Origin Search, Origin Return, Teach, Changing Present Value, and Input Data Screens

2-2 How to Use Smart Active Parts

To use Smart Active Parts, select **Use** in the Use Library dialog box under **Tools** and paste the selected Smart Active Parts on the screen.

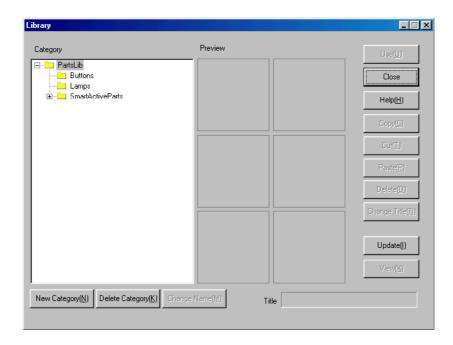
The procedure for pasting Smart Active Parts is as follows.

1. Select Tools-Use Library on the tool bar.

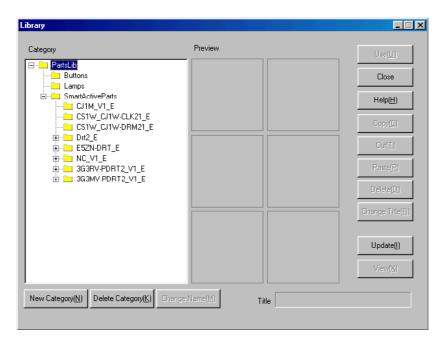


2. Select the desired Smart Active Parts

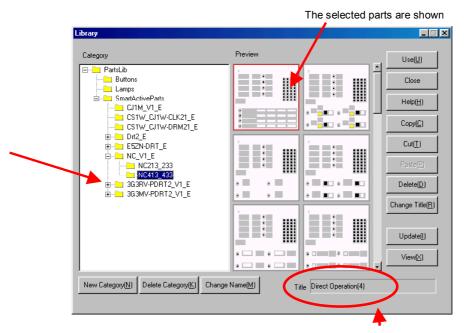
When selecting Use Library, the following Library dialog box appears.



When double clicking on the SmartActiveParts folder in the list box of Category, the installed device libraries will appear.

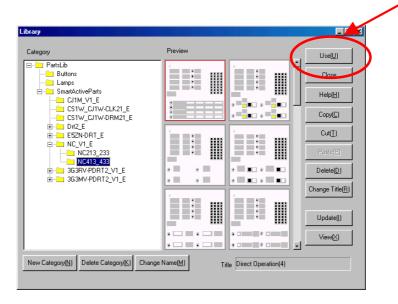


Select the desired device folder under the SmartActiveParts, and then libraries relating to the selected device will be displayed in thumbnail-size images. Click the thumbnail-size image to show the desired Smart Active Parts. The title of the selected Smart Active Parts will be shown in the title field at the bottom of the dialog.

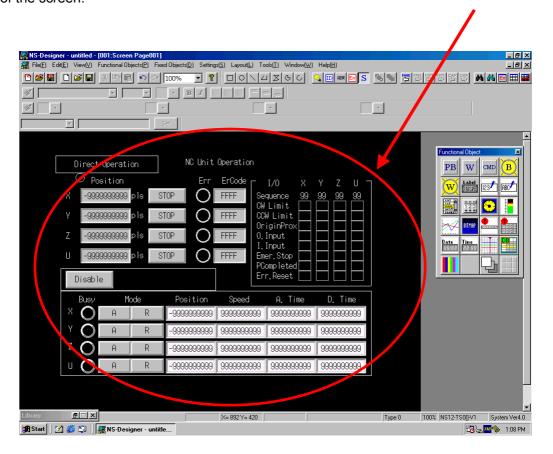


The selected title is shown

3. Select the desired library in the preview box and click the Use button at the top right of the dialog box.



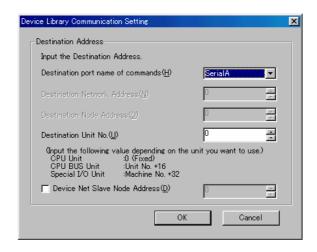
4. When clicking the Use button, the selected Smart Active Parts will be pasted on the top left of top left of the screen.



5. Communication settings

Click the Smart Active Parts after pasting it on the screen. Smart Active Parts Communication Setting dialog box appears. Make the settings for the following items.

No.	Item	Details
1	Destination port name of commands	Selects the port name of PT connected to the PLC
2	Destination Unit No.	Sets Unit No. or Match No., such as NC Unit * Make sure that the number must be 16 or higher for CPU Bus unit and 32 or higher for Special I/O unit.
3	DeviceNet/Serial/ Slave Address	e.g.) Check if the selected Smart Active Parts is DeviceNet Slave and then set the address. (In case the Smart Active Parts needs to use the serial Communication Board/Unit the "Device Net Slave address" will be for Serial Communication Board/Unit.



In a series of sharing Smart Active Parts have been completed. Refer to Section 3 precautions for use of Smart Active Parts.

Precautions for Use of Smart Active Parts

Please note that the following precautions when using Smart Active Parts.

2-3 Operation Environment

- 1. NS-Designer Ver.6.0 is required.
- 2. Project data version 5.0 or later (version shown beside the System Version in the Project Property dialog under Settings in the NS-Designer) is required for operating project (screen data).
- 3. When connecting the PLC and PT by a Serial network (1:N NT Links), set *NT/PC Link Max* on the *Settings-Host Link Port* tab Page in the CX-Programmer to a value greater than 1.

2-4 Precautions for use of Smart Active Parts

Smart Active Parts have the following restrictions unlike other functional objects, such as buttons and lamps.

- 1. Smart Active Parts cannot be copied, pasted, or cut.
 - To place the same Smart Active Parts more than one, select **Tools-Use Library** and click the desired sample.
- Screens contained Smart Active Parts cannot be duplicated or deleted in the Screen Maintenance.Delete the Smart Active Parts first and then perform screen maintenance.
- 3. For some types of Smart Active Parts, there are limits of which version to use. For example, 'Use NS system Version 5.0 or later'. In this example, the library uses functions supported from NS system Version 5.0 and will not work with former version. Refer to the manual of each Smart Active Part for more details.

Remarks

When using this Smart Active Parts, be sure to select **Setting-System Setting** in the menu bar, press the **System Memory List** on the Initial Tab Page, and select **Basic Operation** for \$SB.

Section 3 Precautions for Editing Smart Active Parts

Please note that the following precautions when using Smart Active Parts.

To edit Smart Active Parts, check the Edit Smart Active Parts in the Edit/Disp tab of Options dialog box under the Tools.

ightharpoonup Edit Smart Active Parts($\underline{\textbf{L}}$)

Enables changing objects properties embedded in Smart Active Parts, and moving them.

Smart Active Parts cannot be edited without checking it.

To edit objects grouped as Smart Active Parts, double click on the desired object. The appropriate property dialog box now can be displayed and you can edit it.

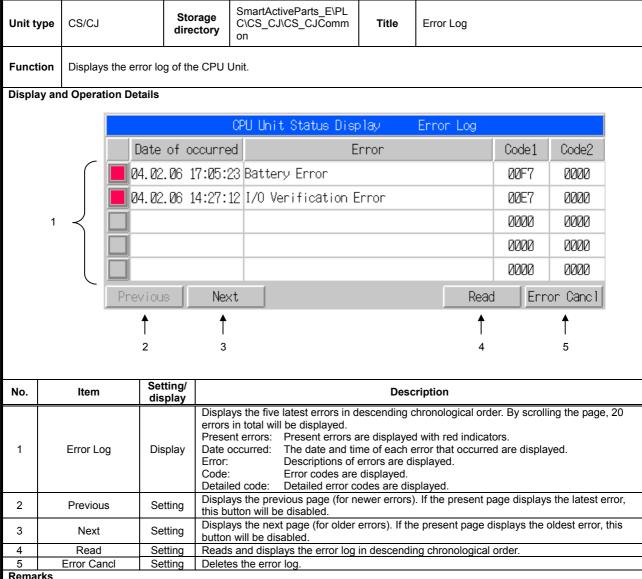
Color and text attribute set for Smart Active Parts cannot be copied.

- 1. Size, position, color and text attribute for objects grouped as Smart Active Parts can be edited.
- 2. The Expansion Tab in the Property Edit for the Smart Active Parts cannot be displayed.

PLC

1.1. CPU

1.1.1 Error Log



- When using this SMART Active Part, be sure to select Setting System Setting in the menu bar, press the System Memory List on the Initial Tab Page, and select Basic Operation for \$SB.
- Do not use the above display for the start screen.
- Use this display in system version 5 or higher version.
- This cannot be used with CSID (Redundant checkup error message cannot be displayed.)

1.1.2 Time Data

Unit type	CS/CJ	Storage directory	SmartActiveParts_E\PL C\CS_CJ\CS_CJComm on	Title	Time data		
Function	Displays time data fr	Displays time data from the CPU Unit.					
Display an	d Operation Details						

CPU Unit Statu	ıs Display	Date
1 ——Time:	04.02.12.	11:04:40
2 ——Start-up Time:	12.	09:00:13
3 — Power Interruption:	12.	21:13:03
4 ——Progam overwritten:	04.01.06.	17:33:26
5 ——Parameter overwritten:	04.01.07.	18:40:01

No.	Item	Setting/ display	Description
1	Time	Display	Displays the present time.
2	Start-up Time	Display	Displays the startup time. The year and month are always ""
3	Power Interruption	Display	Displays the time of the previous interruption. The year and month are always ""
4	Program overwritten	Display	Displays the date and time that the program was overwritten. The CS1-V1 always 0.
5	Parameter overwritten	Display	Displays the date and time that the parameter was overwritten. The CS1-V1 always 0.

- When using this SMART Active Part, be sure to select **Setting System Setting** in the menu bar, press the **System Memory List** on the Initial Tab Page, and select **Basic Operation** for \$SB.

 Do not use the above display for the start screen.

 Use this display in system version 5.

1.1.3 Cycle Time Data

Unit ty	rpe CS/CJ		rage ctory	SmartActiveParts_E\PL C\CS_CJ\CS_CJComm on	Title	Cycle time dat	a			
Functi	on Displays the cyc	Displays the cycle time of CPU Unit.								
Displa	y and Operation Det	ails								
				CPU Unit Status Dis	ply C	ydle Time				
		1 —	→ Pr	esent Cycle Time		3.3 ms				
		2 —	→ Ma	ximum Cycle Time 🏻 🗍		10.0 ms				
No.	Item	Setting/ display			Desc	cription				
1	Present Cycle Time	Display	Displa	ays the present cycle time.						
2	Maximum Cycle Time	Display	Displa	ays the maximum cycle time	9.					
Remar	ks									

1.1.4 Battery Replacement

Unit ty	rpe CS/CJ	l l	rage ctory	SmartActiveParts_E\PL C\CS_CJ\CS_CJComm on	Title	Battery replacement switch		
Functi	Function Makes battery check and replacement settings.							
Displa	y and Operation Det	ails						
	1 → Checking battery							
No.	Item	Setting/ display			Desc	ription		
1	Checking battery	Setting/ display	Batter	Makes battery check and replacement settings. Battery check in progress: Checks the battery. The button is displayed in gray. Battery replacement in progress: The battery is not checked. The button is lit in yellow.				

- When using this SMART Active Part, be sure to select **Setting System Setting** in the menu bar, press the **System Memory List** on the Initial Tab Page, and select **Basic Operation** for \$SB. Do not use the above display for the start screen.

CJ1M (from Ver5 or Earlier)

1.1.5 Settime PLC→NS

Model	CJ1M	Location	SmartActiveParts_E\PLC\ Ver5orEarlier	Title	Settime PLC→NS
Function	Sets time and date inform	nation (year, me	onth, date, time, minute, and	second) in t	he PLC to the internal clock of PT.
[Image]					
		PL	C >> NS 1		

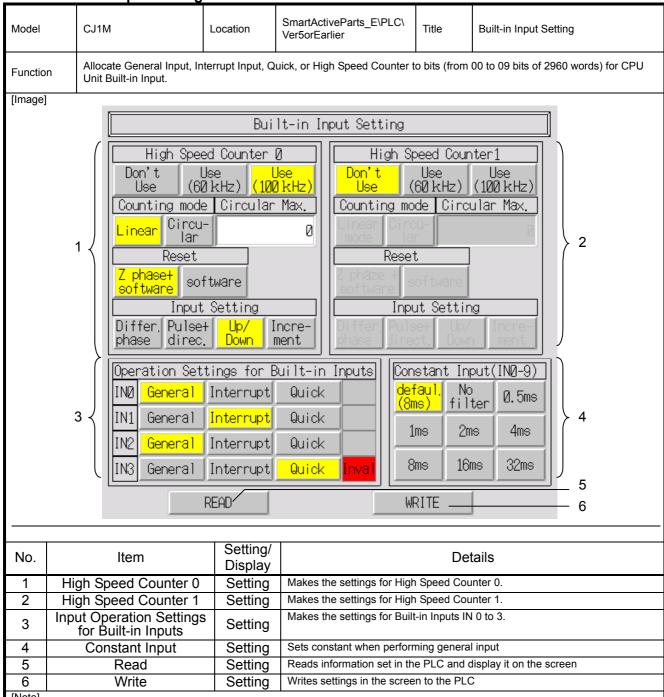
No.	Item	Setting/ Display	Details
1	PLC >> NS	Setting	Sets time and date information (year, month, date, time, minute, and second) in the PLC to the internal clock of PT. A day of the week is calculated by date information in the PT. If a day of the week and date set in the PLC are not matched, a day of the week calculated by date will be reflected to the PT so date information for PLC and PT may vary according to preset data in the PLC.
[Note]	•		

[Note] CS/CJ Series PLCs are supported.

1.1.6 Settime PLC→NS

Model	CJ1M	Location	;	SmartActiveParts_E\PLC\ Ver5orEarlier	Title	Settime PLC→NS
Function	Sets time and date in	formation (yea	ar, moi	nth, date, time, minute, and	second) in	the PT to the internal clock of PLC.
[Image]						
			NS	>>> PLC -	1	
No	Itom	Setting/			Dot	nilo.
No. 1	Item NS >> PLC	Setting/ Display Setting	Sate	time and data information (Deta	ails

Built-in Input Setting

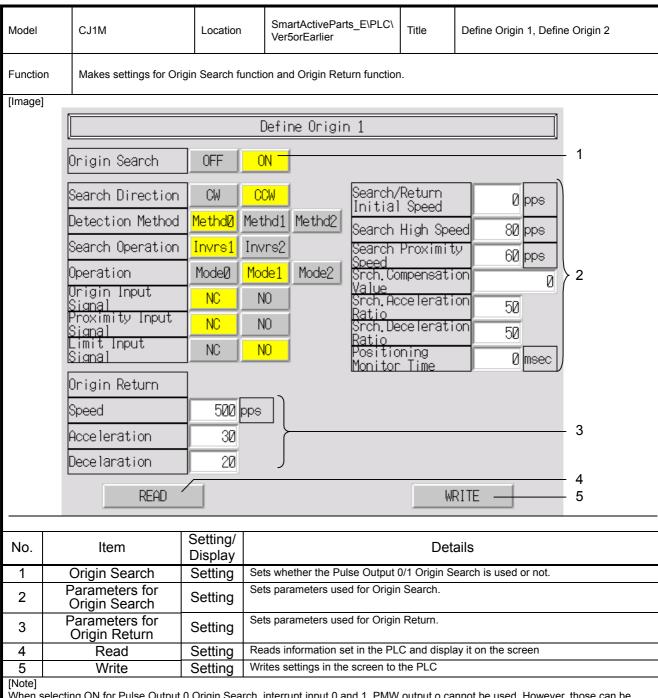


[Note]

When Z phase and software reset are selected in the Input Setting for High Speed Counter 0, Z phase (reset input) will be allocated to

When Z phase and software reset are selected in the Input Setting for High Speed Counter 1, Z phase (reset input) will be allocated IN2.

1.1.8 Define Origin 1, Define Origin 2



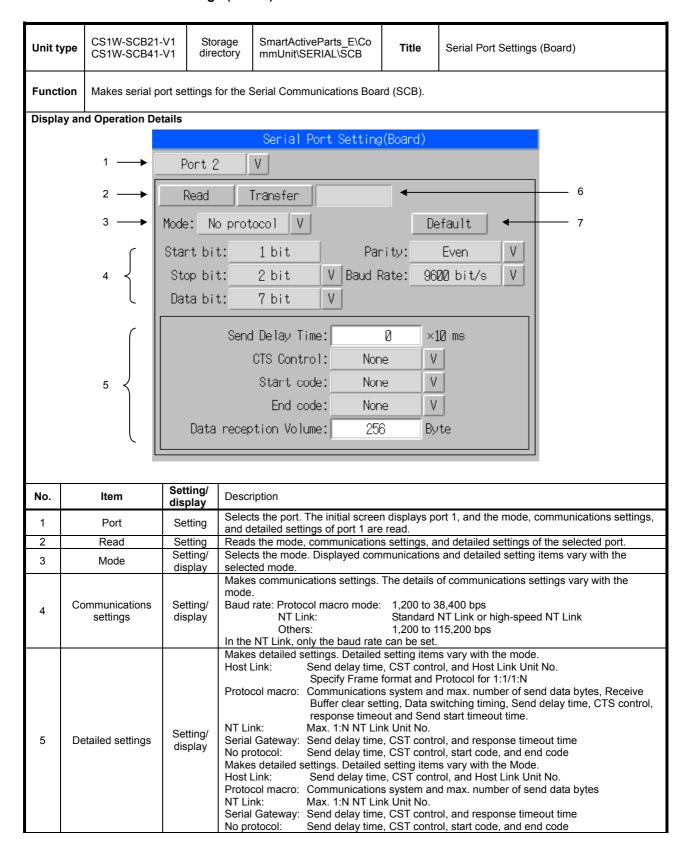
When selecting ON for Pulse Output 0 Origin Search, interrupt input 0 and 1, PMW output o cannot be used. However, those can be used for High Speed Counter 0 and 1.

When selecting ON for Pulse Output 1 Origin Search, it occupies IN2, IN3, and OUT5 besides pulse output so it cannot be used for other functions.

Communication Unit

1.1 Serial Communications

1.1.1 Serial Port Settings (Board)



Communication Unit

Remarks

- * When using this Smart Active Part, be sure to select **Setting System Setting** in the menu bar, press the **System Memory List** on the Initial Tab Page, and select **Basic Operation** for \$SB. Smart Active Parts cannot be used on the pop-up screen.
- Use this display in system version 5.
- * Do not use the above display for the start screen.
- * To restart the port, use the Smart Active Part explained in 5.2.3 Board Port Restart.
- * When the Smart Active Part is reused, no unit number designation will be required.
- Number of frame: 2.

Communications Unit

1.1.2 Serial Port Settings (Unit)

Serial Port Setting	Uni typ	L C.11VV-SCU21-	-V1 Stora		eParts_E\Co ERIAL\SCU	Title	Serial Port Unit Settings
Serial Port Setting(Unit)	Funct	ion Makes serial p	ort settings for	the Serial Comm	unications Unit	(SCU).	
No. Item Setting	Displa	y and Operation De	tails				
No. Item Setting				Serial (<u>Port Settin</u>	g(Unit)	
No. Item Setting/ display No. Item Setting/ display Send Delay Time: 0 ×100 ms CTS Control: None V Response Timeouts: 50 ×100 ms The nitial screen displays port 1, and the mode, communications settings, and detailed settings of port 1 are read. Read Setting/ Mode: Setting/ Setting/ Setting/ Gisplay Communications settings and detailed settings of the selected port. A Communications settings Setting/ Setting/ Misplay Description Description Description Description None V Response Timeouts: 50 ×100 ms Response Timeouts: 50 ×100 ms Response Timeouts: 50 ×100 ms Reads the mode, communications settings, and detailed settings of the selected port. Selects the mode, communications and detailed settings of the selected port. Selects the mode, Displayed communications and detailed settings them vary with the mode. Makes communications settings. The details of communications settings vary with the mode. Baud rate: Protocol macro mode: 1,200 to 115,200 bps NT Link: Standard NT Link or high-speed NT Link Others: 1,200 to 115,200 bps NT Link: Standard NT Link or high-speed NT Link Others: 1,200 to 115,200 bps NT Link: Standard NT Link or high-speed NT Link Unit No. Specify Frame format and Protocol for 1:1/1:N Protocol macro: Communications system and max number of send data bytes Buffer clear setting, Data switching timing, Send delay time, CTS control, and response timeout time. NT Link: Max. 1: NT Link Unit No. Serial Gateway: Send delay time, CST control, and response timeout time. NT Link: Serial Gateway: Send delay time, CST control, and response timeout time. NT Link Unit No. Serial Gateway: Send delay time, CST control, and response timeout time. Setting/ display dramsfer of Nor transfer failed). If the transfer was control, the result will be to prompt the user to restart the port, to restart the port, use the SMART Active Parts povided for this purpose separately.		1	Port 1				
No. Item Setting/ Semantial Sateway V Baud Rate: 9600 bit/s V Baud Rate: 9600		2	Read	 Transfer		_	6
Start bit: 1 bit Parity: Even V		3 -		'	J <u></u>	n	ofault 7
Send Delay Time: Send Delay Time: Send Delay Time: Description							
Send Delay Time:							
Send Delay Time:						Kale. 30	DOM DITA
No. Item Setting/ display Description			Data Dit.	Dit			
No. Item Setting/display Selects the port. The initial screen displays port 1, and the mode, communications settings, and detailed settings of port 1 are read.			(
No. Item Setting/ display Description		5					II
Port Setting Selects the port. The initial screen displays port 1, and the mode, communications settings, and detailed settings of port 1 are read.		,)	Res	sponse Timeou	ts: 5	0 ×	100 ms
Port Setting Selects the port. The initial screen displays port 1, and the mode, communications settings, and detailed settings of port 1 are read.							
Port Setting Selects the port. The initial screen displays port 1, and the mode, communications settings, and detailed settings of port 1 are read.							
1 Port Setting Selects the port. The initial screen displays port 1, and the mode, communications settings, and detailed settings of port 1 are read. 2 Read Setting Reads the mode, communications settings, and detailed settings of the selected port. 3 Mode Setting/ display Selected mode. 4 Communications settings 5 Setting/ display Communications settings Setting/ display Communications settings Setting/ display Communications settings Setting/ display Setting/ display Detailed settings Detailed settings Detailed settings Setting/ display Transfer Setting/ display Setting/ display Setting/ display Transfer Setting/ display Setting	No.	Item				Desc	ription
Read Setting Reads the mode, communications settings, and detailed settings of the selected port.	1	Port	Cotting	Selects the port. T	he initial screer	n displays po	ort 1, and the mode, communications settings,
Settings Detailed settings Transfer display selected mode. Makes communications settings. The details of communications settings vary with the mode. Baud rate: Protocol macro mode: 1,200 to 38,400 bps NT Link: Standard NT Link or high-speed NT Link Others: 1,200 to 115,200 bps In the NT Link, only the baud rate can be set. Makes detailed settings. Detailed setting items vary with the mode. Host Link: Send delay time, CST control, and Host Link Unit No. Specify Frame format and Protocol for 1:1/1:N Protocol macro: Communications system and max. number of send data bytes Buffer clear setting, Data switching timing, Send delay time, CTS control, Response timeout, and Send start timeout time. NT Link: Max. 1:N NT Link Unit No. Serial Gateway: Send delay time, CST control, and response timeout time No protocol: Send delay time, CST control, start code, and end code Transfer Setting/ display Transfer Setting/ display Transfer OK or transfer failed). If the transfer was OK, a message box will appear to prompt the user to restart the port. To restart the port, use the SMART Active Parts provided for this purpose separately.	2	Read	Setting F	Reads the mode, o	communication	s settings, a	
A Communications settings	3	Mode			Displayed com	munications	s and detailed setting items vary with the
4 Communications settings display display display Baud rate: Protocol macro mode: 1,200 to 38,400 bps NT Link: Standard NT Link or high-speed NT Link Others: 1,200 to 115,200 bps In the NT Link, only the baud rate can be set. Makes detailed settings. Detailed setting items vary with the mode. Host Link: Send delay time, CST control, and Host Link Unit No. Specify Frame format and Protocol for 1:1/1:N Protocol macro: Communications system and max. number of send data bytes Buffer clear setting, Data switching timing, Send delay time, CTS control, Response timeout, and Send start timeout time. NT Link: Max. 1:N NT Link Unit No. Serial Gateway: Send delay time, CST control, and response timeout time No protocol: Send delay time, CST control, start code, and end code Transfers the settings to the CPU Unit. After the settings are transferred, the result will be displayed (transfer OK or transfer failed). If the transfer was OK, a message box will appear to prompt the user to restart the port. To restart the port, use the SMART Active Parts provided for this purpose separately.			1	lakes communica	ations settings.	The details	of communications settings vary with the
Settings display NT Link: Standard NT Link or nign-speed NT Link Others: 1,200 to 115,200 bps In the NT Link, only the baud rate can be set. Makes detailed settings. Detailed setting items vary with the mode. Host Link: Send delay time, CST control, and Host Link Unit No. Specify Frame format and Protocol for 1:1/1:N Protocol macro: Communications system and max. number of send data bytes Buffer clear setting, Data switching timing, Send delay time, CTS control, Response timeout, and Send start timeout time. NT Link: Max. 1:N NT Link Unit No. Serial Gateway: Send delay time, CST control, and response timeout time No protocol: Send delay time, CST control, start code, and end code Transfer display display (transfer OK or transfer failed). If the transfer was OK, a message box will appear to prompt the user to restart the port. To restart the port, use the SMART Active Parts provided for this purpose separately.	4		Setting/	Baud rate: Protoco			
Makes detailed settings. Detailed setting items vary with the mode. Host Link: Send delay time, CST control, and Host Link Unit No. Specify Frame format and Protocol for 1:1/1:N Protocol macro: Communications system and max. number of send data bytes Buffer clear setting, Data switching timing, Send delay time, CTS control, Response timeout, and Send start timeout time. NT Link: Max. 1:N NT Link Unit No. Serial Gateway: Send delay time, CST control, and response timeout time No protocol: Send delay time, CST control, start code, and end code Transfer Misplay Transfer Setting/ display Transfer OK or transfer failed). If the transfer was OK, a message box will appear to prowided for this purpose separately.		settings	display				
Bettings Detailed settings Detailed settings Detailed settings Detailed settings Transfer Host Link: Send delay time, CST control, and Host Link Unit No. Specify Frame format and Protocol for 1:1/1:N Communications system and max. number of send data bytes Buffer clear setting, Data switching timing, Send delay time, CTS control, Response timeout, and Send start timeout time. Max. 1:N NT Link Unit No. Serial Gateway: Send delay time, CST control, and response timeout time No protocol: Send delay time, CST control, and response timeout time Send delay time, CST control, start code, and end code Transfers the settings to the CPU Unit. After the settings are transferred, the result will be displayed (transfer OK or transfer failed). If the transfer was OK, a message box will appear to prompt the user to restart the port. To restart the port, use the SMART Active Parts provided for this purpose separately.							
Detailed settings Setting/display Protocol macro: Communications system and max. number of send data bytes Buffer clear setting, Data switching timing, Send delay time, CTS control, Response timeout, and Send start timeout time. NT Link: Max. 1:N NT Link Unit No. Serial Gateway: Send delay time, CST control, and response timeout time No protocol: Send delay time, CST control, start code, and end code Transfer displayed (transfer OK or transfer failed). If the transfer was OK, a message box will appear to prompt the user to restart the port. To restart the port, use the SMART Active Parts provided for this purpose separately.					Send delay tir	ne, CST cor	ntrol, and Host Link Unit No.
Buffer clear setting, Data switching timing, Send delay time, CTS control, Response timeout, and Send start timeout time. NT Link: Max. 1:N NT Link Unit No. Serial Gateway: Send delay time, CST control, and response timeout time No protocol: Send delay time, CST control, start code, and end code Transfer display display display to prompt the user to restart the port. To restart the port, use the SMART Active Parts provided for this purpose separately.			Setting/	Protocol macro:	Communication	ons system a	and max. number of send data bytes
NT Link: Max. 1:N NT Link Unit No. Serial Gateway: Send delay time, CST control, and response timeout time No protocol: Send delay time, CST control, start code, and end code Transfer Setting/ display Setting/ display Transfer Was OK, a message box will appear to prompt the user to restart the port. To restart the port, use the SMART Active Parts provided for this purpose separately.	5	Detailed settings					
No protocol: Send delay time, CST control, start code, and end code Transfer Setting/ display No protocol: Send delay time, CST control, start code, and end code Transfers the settings to the CPU Unit. After the settings are transferred, the result will be displayed (transfer OK or transfer failed). If the transfer was OK, a message box will appear to prompt the user to restart the port. To restart the port, use the SMART Active Parts provided for this purpose separately.					Max. 1:N NT L	ink Unit No	
6 Transfer Setting/ displayed (transfer OK or transfer failed). If the transfer was OK, a message box will appear to prompt the user to restart the port. To restart the port, use the SMART Active Parts provided for this purpose separately.			1	lo protocol:	Send delay tin	ne, CST cor	trol, start code, and end code
display display to prompt the user to restart the port. To restart the port, use the SMART Active Parts provided for this purpose separately.		Transfer					
	0	rransier					art the port, use the SMART Active Parts
Remarks							

- * When using this Smart Active Part, be sure to select **Setting System Setting** in the menu bar, press the **System Memory List** on the Initial Tab Page, and select **Basic Operation** for \$SB. Smart Active Parts cannot be used on the popup screen.
- Use this display in system version 5.
- * Do not use the above display for the start screen.
- * To restart the port, use the Smart Active Parts explained in 5.2.3 Unit Port Restart.
- * When the Smart Active Parts is reused, the unit number designation will be required.
- * Number of frame: 2.

Port Restart (Board) 1.1.3

Unit type	CS1W-SCB21-'			Title	Port restart (Board)		
Function Restarts a port on a Serial Communications Board (SCB).							
Display a	nd Operation Det	ails					
		1	Port No. 1 V Port F	Reset Ex	Rit 3		
No.	Item	Setting/ display		Desc	ription		
No.	Item Port No.	display	Selects the port number.	Desc	ription		
No. 1 2		display Setting	Selects the port number. Restarts the selected port.	Desc	ription		

- When using this Smart Active Parts, be sure to select **Setting System Setting** in the menu bar, press the **System Memory List** on the Initial Tab Page, and select **Basic Operation** and **Date** and **Time for \$SW**. Smart Active Parts cannot be used on the populp screen.
- Do not use the above display for the start screen.

 When the Smart Active Parts is reused, no unit number designation will be required.

1.1.4 Port Restart (Unit)

Unit type	CS1W-SCU21-Y CJ1W-SCU21-Y CJ1W-SCU41-Y	/1 Sto	rage ctory	SmartActiveParts_E\Co mmUnit\SERIAL\SCU	Title	Port restart (unit)		
Function	Restarts a port on a Serial Communications Unit (SCU).							
Display a	Display and Operation Details							
Unit No. V Port No. 1 V Port Reset Exit 4								
No	Item	Setting/	Description					
No.	iteiii	display				приоп		
1 1	Unit No.	display Setting	Selec	ts the unit number of the Se		'		
1 2				ts the unit number of the Se t the port number.		'		
1	Unit No.	Setting	Selec			'		

- * When using this Smart Active Parts, be sure to select **Setting System Setting** in the menu bar, press the **System Memory List** on the Initial Tab Page, and select **Basic Operation** and **Date and Time** for \$SW. Smart Active Parts cannot be used on the popup screen.
- * Do not use the above display for the start screen.
- * When the Smart Active Parts is reused, no unit number designation will be required.

1.1.5 Protocol Transfer Enable (Board)

Unit t	CS1W-SCB21- CS1W-SCB41-		rage ctory	SmartActiveParts_E\Co mmUnit\SERIAL\SCB	Title	Protocol transfer enable (board)		
Funct	ion Enables or disa	Enables or disables protocol transfer for the Serial Communications Board (SCB).						
Displa	y and Operation De	tails						
			2	Port No. Transfer	1 V Disable			
No.	Item	Setting/ display			Desc	ription		
1	Port No.	Setting	Selec	ts the port number.				
2	Transfer	Setting	Settin		only if the po	play will be lit in yellow if transfer is enabled. It mode is set to serial gateway. An error It is a set to serial gateway.		

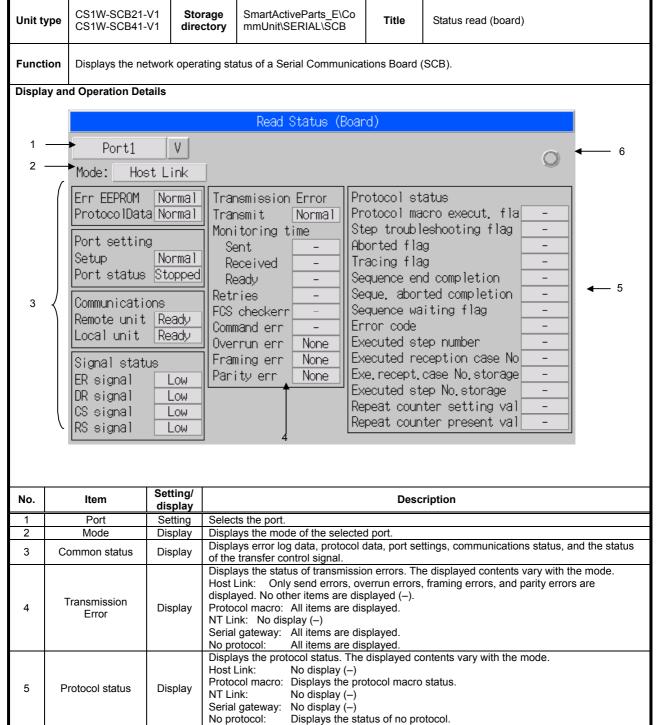
- * When using this Smart Active Parts, be sure to select **Setting System Setting** in the menu bar, press the **System Memory List** on the Initial Tab Page, and select **Basic Operation** and **Date** and **Time for \$SW**. Smart Active Parts cannot be used on the populo screen.
- * Do not use the above display for the start screen.
- * When the Smart Active Part is reused, no unit number designation will be required.

Protocol Transfer Enable (Unit) 1.1.6

Unit ty	CS1W-SCU21 CJ1W-SCU21- CJ1W-SCU41-	·V1 Sto	rage ctory	SmartActiveParts_E\Co mmUnit\SERIAL\SCU	Title	Protocol transfer enable (unit)			
Funct	ion Enables or disa	Enables or disables protocol transfer for the Serial Communications Unit (SCU).							
Displa	Display and Operation Details								
			1	→ Port No. ☐ Transfer	1 V Disable				
No.	Item	Setting/ display			Desc	ription			
1	Port No.	Setting	Selects	s the port number.					
2	Transfer	Setting	enable		possible only	play will be lit in yellow if the transfer is y if the port mode is set to serial gateway. An nodes.			
Rema	rke	I	enoi n	nessage will be displayed it	or all other H	ioues.			

- When using this Smart Active Parts, be sure to select **Setting System Setting** in the menu bar, press the **System Memory List** on the Initial Tab Page, and select **Basic Operation** and **Date** and **Time for \$SW**. Smart Active Parts cannot be used on
- Do not use the above display for the start screen.
- When the Smart Active Parts is reused, the unit number designation will be required.

1.1.7 Status Read (Board)



Remarks

6

* When using this Smart Active Parts, be sure to select **Setting** - **System Setting** in the menu bar, press the **System Memory List** on the Initial Tab Page, and select **Basic Operation** and **Date** and **Time for \$SW**. Smart Active Parts cannot be used on the popup screen.

Data other than ON/OFF data is read every second. This indicator lights yellow when data is

* Do not use the above display for the start screen.

Display

Use this display in system version 5.

Read indicator

* When the Smart Active Parts is reused, no unit number designation will be required.

read

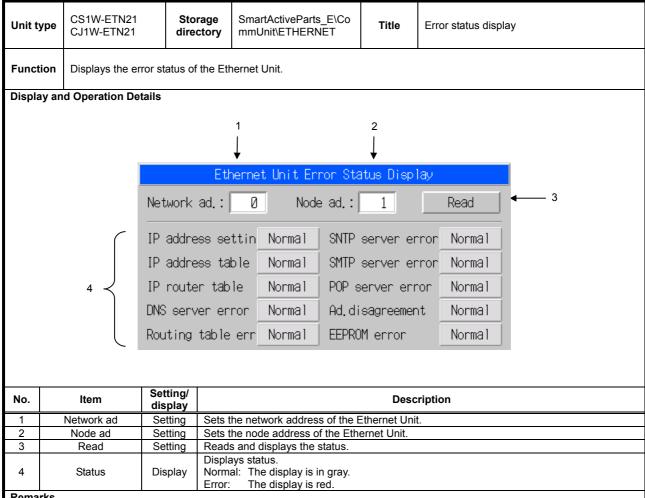
1.1.8 Status Read (Unit)

Unit ty	CS1W-SCU21- CJ1W-SCU21- CJ1W-SCU41-	V1 Sto	rage ctory	SmartActiveParts_E\Co mmUnit\SERIAL\SCU	Title	Status read (unit)			
Function	on Displays the ne	Displays the network operating status of a Serial Communications Unit (SCU).							
Displa	Display and Operation Details								
		Read Status (Unit)							
1 -	→ Port1	[V]			<u></u>				
2 -		ost Link				○ ← 6			
						-+0+			
	Err EEPROM	_			rotocol: rotocol:	atatus macro execut.flag -			
	Port setti		╣№	nitoring time	tep trouk	oleshooting flag			
	Setup	Norma	1		borted f racing f				
	Port statu	ıs Stoppe	<u>d</u>	Ready - S	equence (end completion			
3	Communicat	ions	- 11			orted completion = 5 waiting flag			
	Remote uni			mmand errE	irror code	e <u>-</u>			
			≓I₩			step number reception case No -			
	Signal sta ER signal	tus Low	- 11	rity err None E	xe_recep	t.case No.storage			
	DR signal	Low				step No.storage unter setting val -			
	CS signal RS signal	Low				unter present val -			
	no orginar	LOW		4					
No	léana	Setting/			Door	urimāli a m			
No .	Port	display	Soloo	to the port	Desc	ription			
2	Mode	Setting Display	Selects the port. Displays the mode of the selected port.						
3	Common status	Display	Displays the error log data, protocol data, port settings, communications status, and the status of the transfer control signal.						
			Displa	ays the status of transmission	n errors. Th	e displayed contents vary with the mode. rrors, framing errors, and parity errors are			
	Transmission	6: 1		displayed. No of	her items a	re displayed (–).			
4	Error	Display	NT Li	Protocol macro: All items are displayed. NT Link: No display (–)					
				gateway: All items are dis otocol: All items are dis	, ,				
				ays the protocol status. The		ontents vary with the mode.			
5	Protocol status	Display	Display Protocol macro: Dis		tocol macro	status.			
			Serial	gateway: No display (–)					
6	Read indicator	Display		otocol: Displays the sta is read every second. This in		otocol. ts yellow when data is read.			
Remar						n the many har prose the System Memory			

- When using this Smart Active Parts, be sure to select **Setting System Setting** in the menu bar, press the **System Memory List** on the Initial Tab Page, and select **Basic Operation** and **Date** and **Time for \$SW**. Smart Active Parts cannot be used on the popup screen.
- Do not use the above display for the start screen.
- Use this display in system version 5.
- When the Smart Active Part is reused, the unit number designation will be required.
- Number of frame: 2.

1.2 Ethernet

1.2.1 **Error Status Display**

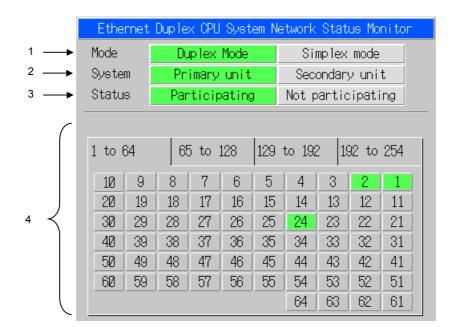


- When using this Smart Active Parts, be sure to select Setting System Setting in the menu bar, press the System Memory List on the Initial Tab Page, and select Basic Operation for \$SB. Smart Active Parts cannot be used on the popup screen.
- Do not use the above display for the start screen.
- When the Smart Active Parts is reused, set the unit number to 254.

1.2.2 Network Status Monitor

Unit type	CS1D-ETN21D	Storage directory	SmartActiveParts_E\Co mmUnit\ETHERNET	Title	Network status monitor	
Function	Displays the network status of the Ethernet Unit.					

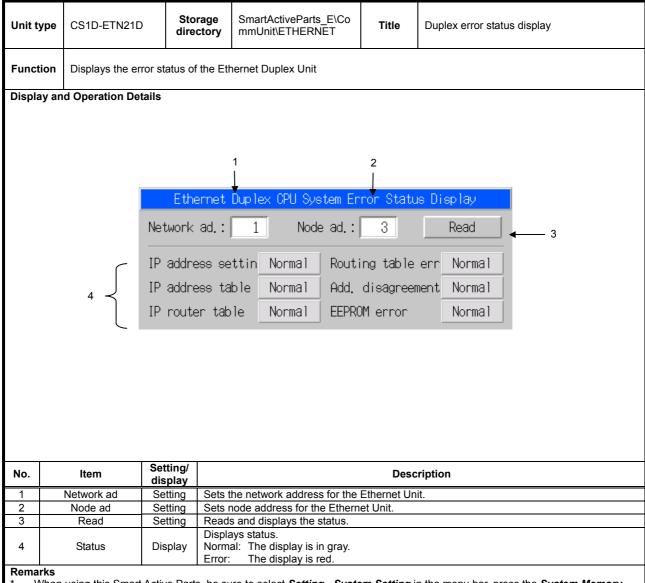
Display and Operation Details



No.	Item	Setting/ display	Description			
1	Mode	Display	Displays the mode of the local node. Duplex Mode: Displayed in green when the Unit is in Duplex Mode. Simplex Mode: Displayed in orange when the Unit is in Simplex Mode.			
2	System	Display	Displays the system of the local node only when the system is in duplex mode. Primary Unit: Displayed in green when the Unit is set as the Primary Unit. Secondary Unit: Displayed in orange when the Unit is set as the Secondary Unit.			
3	Status	Display	Displays the network status of the local node only when the system is in duplex mode. Participating: Displayed in green when the Unit is participating in the network. Not participating: Displayed in red when the Unit is separated from the network.			
4	Participation status	Display	Displays the network status of nodes 1 to 254 only when the status is participating. Participating: Numbers of nodes participating in the network are displayed in green. Not participating: Numbers of nodes separated from the network are displayed in gray.			

- * Items are refreshed every second.
- * When using this Smart Active Parts, be sure to select **Setting System Setting** in the menu bar, press the **System Memory List** on the Initial Tab Page, and select **Basic Operation** for \$SB. Smart Active Parts cannot be used on the popup screen.
- Do not use the above display for the start screen.
- Use this display in system version 5.
- * When the Smart Active Part is reused, the unit number must be specified.
- * Number of frame: 1.

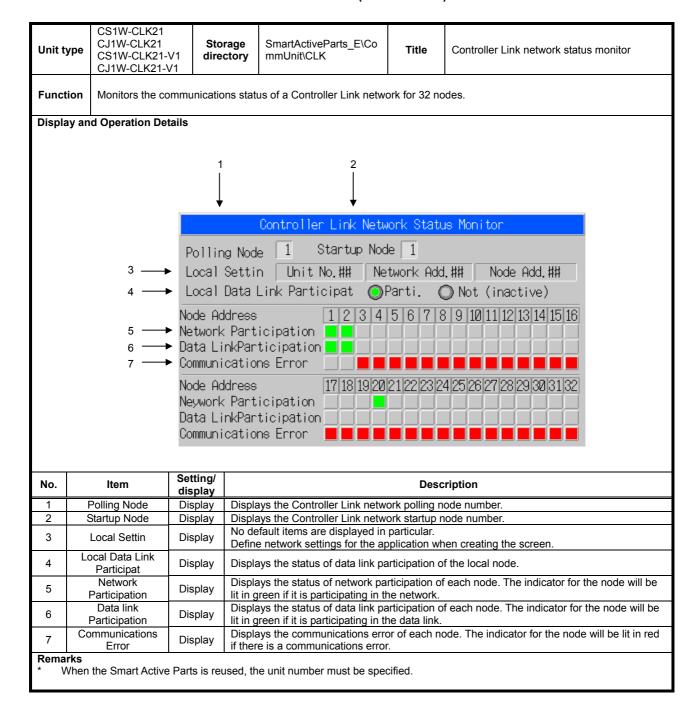
1.2.3 Duplex Error Status Display



- * When using this Smart Active Parts, be sure to select **Setting System Setting** in the menu bar, press the **System Memory List** on the Initial Tab Page, and select **Basic Operation** for \$SB. Smart Active Parts cannot be used on the popup screen.
- Do not use the above display for the start screen.
- When the Smart Active Parts is reused, set the unit number to 254.

1.3 Controller Link

1.3.1 Controller Link Network Status Monitor (for 32 Nodes)



1.3.2 Controller Link Network Station Monitor (for 62 Nodes)

Unit ty	CS1W-CLK21-		rage ctory	SmartActiveParts_E\Co mmUnit\CLK	Title	Controller Link network status monitor				
Funct	Monitors the co	mmunicatio	ns statı	us of a Controller Link netw	ork for 62 no	odes.				
Displa	y and Operation De	tails								
				4	0					
				1	2					
Controller Link Network Status Monitor										
Polling Node 1 Startup Node 1										
Ì	3 —	Local	_		twork Ado	d.## Node Add.##				
	4	Local	Data l	_inkParticipation 🗿	Parti. (Not (inactive)				
		Node Ad		1234	5 6 7 8	8 9 10 11 12 13 14 15 16				
	5 — 6 — 6		twork Participation							
	7		ata LinkParticipation							
		Node Ad	ode Address 17 18 19 20 21 22 23 24 25 26 27 28 29 30 31 32							
	Network Participation Data LinkParticipation									
				ns Error						
		Node Ad	dress	33 34 35 36	37 38 39 4	0 41 42 43 44 45 46 47 48				
				icipation						
				ticipation ns Error 						
		Node Ad	dress	49 50 51 52	53 54 55 5	6 57 58 59 60 61 62				
				icipation						
				ticipation ns Error =						
No.	Item	Setting/ display			Desc	cription				
1	Polling Node		Displa	ys the Controller Link netw	ork polling n	ode number.				
2	Startup Node	Display	Displays the Controller Link network startup node number.							
3	Local Settin	Display	Display No default items are displayed in particular. Define network settings for the application when creating the screen.							
4	Local Data Link Participation	Display	Displa	ys the status of data link pa	articipation o	of the local node.				
5	Network Participation	Display		ys the status of network pareen if it is participating in t		f each node. The indicator for the node will be				
6	Data Link Participation	Displays the status of data link participation of each node. The indicator for the node will be lit in green if it is participating in the data link.								
7	Communications Display Displays the communications error of each node. The indicator for the node will be lit in red									
	Terror Bisplay if there is a communications error. Remarks * When the Smart Active Part is reused, the unit number must be specified.									
V	men the Smart Active	e Part is reus	sea, the	unit number must be spec	illea.					

Communication Unit

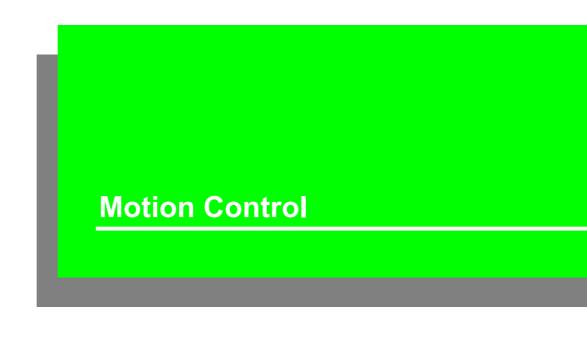
1.4 Communication Unit (Ver5orEarlier)

1.4.1 CS1W-CLK

Model		CS1W-CLK21 CJ1W-CLK21	Location	ml	nartA Jnit\\ _CJ1	er5o	Earli	er\C		Titl	е	Ne	etwo	rk St	atus	Mo	onitor	r		
Functio	n	Monitors CLK networkir	ng status.																	
[Image]																				
										1							2			
		Controller Li	nk Statu	s F	Po l	ling	, No	ode	No).[_1	Sta	art	Jp	Noc	de	No).[1		
	3	Local Settings	Unit	√o.#	#	Net	wor	k f	Add	lres	s##	No	de	Ad	dre	289	3##			
		Local Data Lin				_	● P				O N								4	
		Node Address		010			_				_			113			5 1 16	3		
	5	Network Partic	ipation	0116	72 10	۳	100	50	01	50	30 1	0 1.	1 11	1	1					
	6	Data LinkParti			+												1			
	7	Communications														Ī				
		Node Address		17[1	18 1	9120	121	22	23	24	25/2	6 27	7 28	129	37	13	132	2		
		Network Partic	ipation									_				Ť				
	Data LinkParticipation																			
	Communications Error																			
No.		Item	Setting/ Display								De	etails								
1	F	Polling Node No.	Display [Displa	ys p	olling	noc	le N	o. fc	or CL	K ne	tworl	۲.							
2	S	Startup Node No.		Displa	•	•			lo. fo	or CL	K ne	twor	k.							
3		Local Setting	Uispiay	lo iter Jser c	an n	nake	orig	inal												
4	I	Local Data Link Participation	I lieniav	Displa Partici	•			artic	ipati	ion s	tatus	eithe	er pa	artic	ipate	e (p	part.)) o	r not	
5	Network Participation Display Displays network participation status by node.																			
6	Data Link Participation Display Displays data link participation status by node. Communications Error Display Displays whether an error is being occurred by node.																			
7	Con	nmunications Error	Display [Displa	ys w	heth	er ar	err	or is	s beir	ng oc	curre	ed b	y no	de.					
[Note]																				

1.4.2 CS1W-DRM

Model	CS1W-DRM21 CJ1W-DRM21	Location	mUr	artActiv nit\Ver: 1W-DI	5orE	arlie	r\CS		Т	itle		Ne	twor	k St	atus	Mor	nitor	
Function Monitors Device network communication status when using CS1W-DRM/CJ1W-DRM21 as a master.																		
[Image]																		
			D	evid	ce I	Net	; S	tat	us									
	Node Addres	38	1/2	001	Й2	ИЗ	Й4	Й5	И6	Й7	Й8	ЙΘ	1Й	11	12	13	14	15
	1 Registered			0 0 1		00	5	3	00	01	00	00	10	11	-	10		10
	2 Normal Slav																	
	Node Addres		1	6 17	18	19	2Й	21	22	23	24	25	26	27	28	29	30	31
	Registered		1		10	10	0										00	01
	Normal Slav																	
	Node Addres		3	2 33	34	35	36	37	38	39	40	41	42	43	44	45	46	47
	Registered		Ť				3	5			٥	11	-	ľ		10	10	
	Normal Slav																	
	Node Addres		4	8 49	50	51	52	53	54	55	56	57	58	59	60	R1	62	63
	Registered			<u> </u>	<u>~</u>	<u> </u>	Ş	3	<u> </u>		~~	5		~	Ť	V-1	<u> </u>	
	Normal Slav			1														
No.	Item	Setting/										ails						
Display					Displays slave node address registered in the scan list of the master.													
1	Registered Slave Normal Slave	Display	Displa Displa	•														
2	Normal Slave	Display	เมรเกล	v< 912	ive r	ioue	: INO	. wr	IICI)	is D	emc	ı COI	mm	urnc	aie	a mo	311110	IIIV.



Motion Control

1.1 Standard Position Control Units

1.1.1 Adjust Operation

11111 Auj	ust operation				
Unit type	CS1W-NC113/133/213/233/ 413/433 CJ1W-NC113/133/213/233/4 13/433	Storage directory	SmartActiveParts_E\ Motion\NC\NC[]3	Title	Adjust Operation
Function	Performs jogging, origin search	ches, and orio	gin returns.		
Display and	Operation Details		5		
	3				
		NC Adj	ustOperation 🔻		
	Axis busy Override se	etting	Speed CME) value	
1	Disable Disable	5 %	; +JOG 500	M pu	lse/s
2	Axis 1 Decel stop		-JOG Orig.se	earch 0	rig.return
	† 4		$ \uparrow $ $ 6 $ $ \uparrow $		T 8

No.	Item	Setting/ display	Description
1	Axis busy	Display	Lights yellow when processing is being performed for the axis.
2	Axis	Setting	Sets the axis number. The setting ranges are as follows: NC1[]3: Always 1, NC2[]3: 1 to 2, NC4[]3: 1 to 4 Note: Axis 1: X Axis, Axis 2: Y Axis, Axis 3: Z Axis, Axis 4: U axis
3	Override setting	Setting	Sets an override value and enables and disables the override. (Setting range: 1 to 999)
4	Deceleration stop	Setting	When pressed, lights yellow and decelerates the motor to a stop. Jogging, origin searches, and origin returns cannot be performed during a deceleration stop.
5	Speed command value	Setting	Sets the speed. (Setting range: 1 to 500,000 pulse/s)
6	JOG operation	Setting	When held down, operates the motor in the specified direction. When released, stops motor operation.
7	Origin search	Setting	When pressed, starts an origin search operation.
8	Origin return	Setting	When pressed, starts an origin return operation.

Remarks

There are six different version of this SMART Active Part depending on the following area alStorage directorys.

NC1[]3: For DM Area alStorage directorys in words for Special I/O Units and for user-set DM Area alStorage directorys NC2[]3: For DM Area alStorage directorys in words for Special I/O Units and for user-set DM Area alStorage directorys

NC4[]3: For DM Area alStorage directorys in words for Special I/O Units and for user-set DM Area alStorage directorys

- * When using this SMART Active Part for the NC2[]3 or NC4[]3, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB. This SMART Active Part cannot be used on pop-up screens.
- * When using this SMART Active Part with user-set DM Area alStorage directorys, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Address Index** for the \$SW.
- * When using this SMART Active Part for the NC2[]3 or NC4[]3, do not use it on the initial screen.
- * When using this SMART Active Part for the NC2[]3 or NC4[]3, use system version 5 or higher.
- * When reusing SMART Active Parts, be sure to set the unit number.
- * Number of frames: NC2[]3 Part: 1 frame, NC4[]3 Part: 1 frame
- * The storage directories are as follows: Parts for DM Area alStorage directorys in words for Special I/O Units: NC\NC1[]3\SIOU DM AreaAlStorage directorys

UserSetDM_AreaAlStorage directorys: NC\NC1[]3\UserSetDM_AreaAlStorage directorys

NC2[]3: Parts for DM Area alStorage directorys in words for Special I/O Units: NC\NC2[]3\SIOU_DM_AreaAlStorage directorys

UserSetDM AreaAlStorage directorys: NC\NC2[]3\UserSetDM AreaAlStorage directorys

 $NC4[]3: Parts for DM Area alStorage directorys in words for Special I/O Units: NC\NC4[]3\SIOU_DM_AreaAlStorage directorys$

UserSetDM_AreaAlStorage directorys: NC\NC3x3\UserSetDM_AreaAlStorage directorys

1.1.2	Direct Operation								
Unit ty	CS1W-NC113/ 413/433 CJ1W-NC113/1 413/433		Storage directory	SmartActi Motion\N0	veParts_E\ C\NC[]3	Title	Direct Operation		
Functi	on Performs direct	operation us	ing an absolu	te or relativ	e movement o	command.			
Display	and Operation Deta	ails							
		3	6	;			9		
					7				
				rect Oper					
		erride sett			ed CMD valu		Accel time		
1 _	→ ◯)Disa	able_	5 % s	tart		pulse/s	2500 ms		
		,		Pos	CMD value		Decel time		
2 _	Axis 1 Decel	stop	1	ABS	1000	pulse	4000 ms		
		A							
↑ ↑									
			5	;	8		10		
		Catting							
No.	Item	Setting/ display			Desc	ription			
1	Axis busy	Display					ed for the axis.		
2	Axis	Setting			ne setting rang 3: 1 to 2, NC4		follows:		
_	7 (3)	Octaing					, Axis 4: Axis U		
3	Override setting	Setting	Sets an over 1% to 999%)		nd enables ar	nd disables	the override. (Setting rang	је:	
4	Deceleration stop	Setting	When presse	ed, lights ye			motor to a stop. Absolute ed during a deceleration sto		
5	ABS/INC	Setting	Switches the	between a	n absolute mo		mmand (ABS) and a relative		
6	Start	Setting	Starts operat			nmand sne	ecified for ABS/INC (5).		
7	Speed command value	Setting	•		range: 1 to 50	•			
8	Position command value	Setting	Sets the posi	ition. (Settin	ng range: -1,07	73,741,823	s to 1,073,741,823 pulses)		
9	Acceleration time	Setting	Sets the acceleration time. (Setting range: 0 to 250,000 ms)						
10	Deceleration time	Setting	Sets the dece	eleration tin	ne. (Setting ra	nge: 0 to 2	50,000 ms)		

Motion Control

Remarks

* There are six different version of this SMART Active Part depending on the following area alStorage directorys. NC1[]3: For DM Area alStorage directorys in words for Special I/O Units and for user-set DM Area alStorage directorys

NC2[]3: For DM Area alStorage directorys in words for Special I/O Units and for user-set DM Area alStorage directorys

NC4[]3: For DM Area alStorage directorys in words for Special I/O Units and for user-set DM Area alStorage directorys

- * When using this SMART Active Part for the NC2[]3 or NC4[]3, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB. This SMART Active Part cannot be used on pop-up screens.
- * When using this SMART Active Part with user-set DM Area alStorage directorys, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Address** Index for the \$SW.
- * When using this SMART Active Part for the NC2[]3 or NC4[]3, do not use it on the initial screen.
- * When using this SMART Active Part for the NC2[]3 or NC4[]3, use system version 5 or higher.
- When reusing SMART Active Parts, be sure to set the unit number.
- * Number of frames: NC2[]3 Part: 2 frame, NC4[]3 Part: 2 frame
- * The storage directories are as follows: Parts for DM Area alStorage directorys in words for Special I/O Units: NC\NC1\limit{II}3\SIOU DM AreaAlStorage directorys

UserSetDM AreaAlStorage directorys: NC\NC1[]3\UserSetDM AreaAlStorage directorys

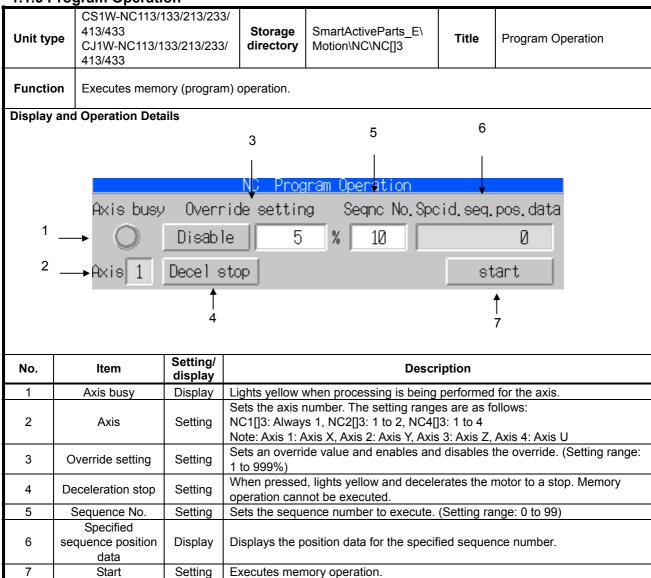
NC2[]3: Parts for DM Area alStorage directorys in words for Special I/O Units: NC\NC2[]3\SIOU_DM_AreaAlStorage directorys

UserSetDM AreaAlStorage directorys: NC\NC2[]3\UserSetDM AreaAlStorage directorys

NC4[]3: Parts for DM Area alStorage directorys in words for Special I/O Units: NC\NC4[]3\SIOU_DM_AreaAlStorage directorys

UserSetDM AreaAlStorage directorys: NC\NC3x3\UserSetDM AreaAlStorage directorys

1.1.3 Program Operation



Motion Control

Remarks

* There are six different version of this SMART Active Part depending on the following area alStorage directorys.

NC1[3: For DM Area alStorage directorys in words for Special I/O Units and for user-set DM Area alStorage directorys

NC2[]3: For DM Area alStorage directorys in words for Special I/O Units and for user-set DM Area alStorage directorys

NC4[]3: For DM Area alStorage directorys in words for Special I/O Units and for user-set DM Area alStorage directorys

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** and **Data/Time** for the \$SB. This SMART Active Part cannot be used on pop-up screens.
- * When using this SMART Active Part with user-set DM Area alStorage directorys, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Address Index** for the \$SW.
- * Do not use this SMART Active Part on the initial screen.
- Use system version 5 or higher.
- * When reusing SMART Active Parts, be sure to set the unit number.
- * Number of frames: NC2[]3 Part: 1 frame, NC4[]3 Part: 1 frame
- * The storage directories are as follows: Parts for DM Area alStorage directorys in words for Special I/O Units: NC\NC1\(\text{I}\)13\(\text{SIOU}\) DM AreaAlStorage directorys

UserSetDM_AreaAlStorage directorys: NC\NC1[]3\UserSetDM_AreaAlStorage directorys

NC2[]3: Parts for DM Area alStorage directorys in words for Special I/O Units: NC\NC2[]3\SIOU_DM_AreaAlStorage directorys

UserSetDM AreaAlStorage directorys: NC\NC2[]3\UserSetDM AreaAlStorage directorys

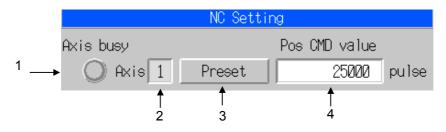
NC4[]3: Parts for DM Area alStorage directorys in words for Special I/O Units: NC\NC4[]3\SIOU_DM_AreaAlStorage directorys

UserSetDM AreaAlStorage directorys: NC\NC3x3\UserSetDM AreaAlStorage directorys

1.1.4 Setting

Unit type	CS1W-NC113/133/213/233/413 /433 CJ1W-NC113/133/213/233/413/ 433	Storage directory	SmartActiveParts_E\M otion\NC\NCxx3	Title	Setting
Function	Executes a present position prese	et.			

Display and Operation Details



No.	Item	Setting/ display	Description
1	Axis busy	Display	Lights yellow when processing is being performed for the axis.
2	Axis	Setting	Sets the axis number. The setting ranges are as follows: NC1[]3: Always 1, NC2[]3: 1 to 2, NC4[]3: 1 to 4 Note: Axis 1: Axis X, Axis 2: Axis Y, Axis 3: Axis Z, Axis 4: Axis U
3	Preset	Setting	Executes the preset.
4	Position command value	Setting	Sets the position. (Setting range: 1,073,741,823 to 1,073,741,823 pulses)

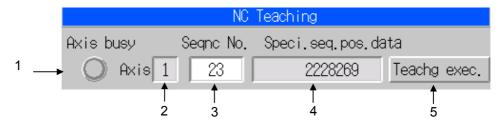
- * There are six different version of this SMART Active Part depending on the following area alStorage directorys.

 NC1[]3: For DM Area alStorage directorys in words for Special I/O Units and for user-set DM Area alStorage
 - NC1[]3: For DM Area alStorage directorys in words for Special I/O Units and for user-set DM Area alStorage directorys
 - NC2[]3: For DM Area alStorage directorys in words for Special I/O Units and for user-set DM Area alStorage directorys
 - NC4[]3: For DM Area alStorage directorys in words for Special I/O Units and for user-set DM Area alStorage directorys
- * When using this SMART Active Part for the NC2[]3 or NC4[]3, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB. This SMART Active Part cannot be used on pop-up screens.
- * When using this SMART Active Part with user-set DM Area alStorage directorys, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Address** Index for the \$SW.
- * When using this SMART Active Part for the NC2[]3 or NC4[]3, do not use it on the initial screen.
- * When using this SMART Active Part for the NC2[]3 or NC4[]3, use system version 5 or higher.
- * When reusing SMART Active Parts, be sure to set the unit number.
- * Number of frames: NC2[]3 Part: 1 frame, NC4[]3 Part: 1 frame
- * The storage directories are as follows: Parts for DM Area alStorage directorys in words for Special I/O Units: NC\NC1[]3\SIOU DM AreaAlStorage directorys
 - UserSetDM AreaAlStorage directorys: NC\NC1[]3\UserSetDM AreaAlStorage directorys
 - NC2[]3: Parts for DM Area alStorage directorys in words for Special I/O Units: NC\NC2[]3\SIOU_DM_AreaAlStorage directorys
 - UserSetDM AreaAlStorage directorys: NC\NC2[]3\UserSetDM AreaAlStorage directorys
 - NC4[]3: Parts for DM Area alStorage directorys in words for Special I/O Units: NC\NC4[]3\SIOU_DM_AreaAlStorage directorys
 - UserSetDM AreaAlStorage directorys: NC\NC3x3\UserSetDM AreaAlStorage directorys

1.1.5 Teaching

Unit type	CS1W-NC113/133/213/233/413/ 433 CJ1W-NC113/133/213/233/413/ 433	Storage directory	SmartActiveParts_E\M otion\NC\NCxx3	Title	Teaching	
Function	Performs teaching for the specified sequence.					

Display and Operation Details



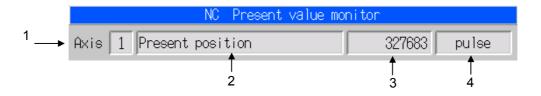
No.	Item	Setting/ display	Description
1	Axis busy	Display	Lights yellow when processing is being performed for the axis.
2	Axis	Setting	Sets the axis number. The setting ranges are as follows: NC1[]3: Always 1, NC2[]3: 1 to 2, NC4[]3: 1 to 4 Note: Axis 1: Axis X, Axis 2: Axis Y, Axis 3: Axis Z, Axis 4: Axis U
3	Sequence No.	Setting	Sets the sequence number. (Setting range: 0 to 99)
4	Specified sequence position data	Display	Displays the present position.
5	Teaching execution	Setting	Executes teaching.

- * There are six different version of this SMART Active Part depending on the following area alStorage directorys.
 - NC1[]3: For DM Area alStorage directorys in words for Special I/O Units and for user-set DM Area alStorage directorys
 - NC2[]3: For DM Area alStorage directorys in words for Special I/O Units and for user-set DM Area alStorage directorys
 - NC4[]3: For DM Area alStorage directorys in words for Special I/O Units and for user-set DM Area alStorage directorys
- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** and **Data/Time** for the \$SB. This SMART Active Part cannot be used on pop-up screens.
- * When using this SMART Active Part with user-set DM Area alStorage directorys, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Address Index** for the \$SW.
- * Do not use this SMART Active Part on the initial screen.
- Use system version 5 or higher.
- * When reusing SMART Active Parts, be sure to set the unit number.
- * Number of frames: NC2[]3 Part: 1 frame, NC4[]3 Part: 1 frame
- * The storage directories are as follows: Parts for DM Area alStorage directorys in words for Special I/O Units: NC\NC1[]3\SIOU_DM_AreaAlStorage directorys
 - UserSetDM_AreaAlStorage directorys: NC\NC1[]3\UserSetDM_AreaAlStorage directorys
 - NC2[]3: Parts for DM Area alStorage directorys in words for Special I/O Units: NC\NC2[]3\SIOU_DM_AreaAlStorage directorys
 - UserSetDM_AreaAlStorage directorys: NC\NC2[]3\UserSetDM_AreaAlStorage directorys
 - NC4[]3: Parts for DM Area alStorage directorys in words for Special I/O Units: NC\NC4[]3\SIOU_DM_AreaAlStorage directorys
 - UserSetDM_AreaAlStorage directorys: NC\NC3x3\UserSetDM_AreaAlStorage directorys

1.1.6 Present Value Monitor

Unit type	CS1W-NC113/133/213/233/413/ 433 CJ1W-NC113/133/213/233/413/ 433	Storage directory	SmartActiveParts_E\M otion\NC\NCxx3	Title	Present Value Monitor
Function	Displays the present value.				

Display and Operation Details



No.	Item	Setting/ display	Description
1	Axis	Setting	Sets the axis number. The setting ranges are as follows: NC1[]3: Always 1, NC2[]3: 1 to 2, NC4[]3: 1 to 4 Note: Axis 1: Axis X, Axis 2: Axis Y, Axis 3: Axis Z, Axis 4: Axis U
2	Monitor type	Setting	Displays the type of present value being monitored.
3	Present value	Display	Displays the present value.
4	Unit	Display	Displays the unit.

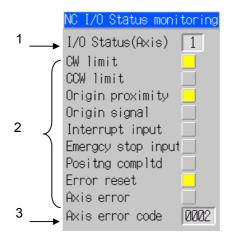
- * There are six different version of this SMART Active Part depending on the following area alStorage directorys.

 NC1[]3: For DM Area alStorage directorys in words for Special I/O Units and for user-set DM Area alStorage directorys
 - NC2[]3: For DM Area alStorage directorys in words for Special I/O Units and for user-set DM Area alStorage directorys
 - NC4[]3: For DM Area alStorage directorys in words for Special I/O Units and for user-set DM Area alStorage directorys
- * When using this SMART Active Part for the NC2[]3 or NC4[]3, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB. This SMART Active Part cannot be used on pop-up screens.
- * When using this SMART Active Part with user-set DM Area alStorage directorys, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Address Index** for the \$SW.
- * When using this SMART Active Part for the NC2[]3 or NC4[]3, do not use it on the initial screen.
- * When using this SMART Active Part for the NC2[]3 or NC4[]3, use system version 5 or higher.
- * When reusing SMART Active Parts, be sure to set the unit number.
- * Number of frames: NC2[]3 Part: 1 frame, NC4[]3 Part: 1 frame
- * The storage directories are as follows: Parts for DM Area alStorage directorys in words for Special I/O Units: NC\NC1[]3\SIOU DM AreaAlStorage directorys
 - UserSetDM_AreaAlStorage directorys: NC\NC1[]3\UserSetDM_AreaAlStorage directorys
 - NC2[]3: Parts for DM Area alStorage directorys in words for Special I/O Units: NC\NC2[]3\SIOU_DM_AreaAlStorage directorys
 - UserSetDM_AreaAlStorage directorys: NC\NC2[]3\UserSetDM_AreaAlStorage directorys
 - NC4[]3: Parts for DM Area alStorage directorys in words for Special I/O Units: NC\NC4[]3\SIOU_DM_AreaAlStorage directorys
 - UserSetDM_AreaAlStorage directorys: NC\NC3x3\UserSetDM_AreaAlStorage directorys

1.1.7 I/O Status Monitoring

Unit type	CS1W-NC113/133/213/233/413/ 433 CJ1W-NC113/133/213/233/413/ 433	Storage directory	SmartActiveParts_E\M otion\NC\NCxx3	Title	I/O Status Monitor	
Function	Displays the I/O status and error codes for each axis.					

Display and Operation Details



No.	Item Setting/ display		Description
1	Axis	Setting	Sets the axis number. The setting ranges are as follows: NC1[]3: Always 1, NC2[]3: 1 to 2, NC4[]3: 1 to 4 Note: Axis 1: Axis X, Axis 2: Axis Y, Axis 3: Axis Z, Axis 4: Axis U
2	I/O Status	Display	Displays the I/O status. The display will be lit yellow for any status signals that are ON.
3	Error code	Display	Displays any error codes that have been generated.

Remarks

- * There are three different version of this SMART Active Part depending on the model as follows: One for the NC1[]3, one for the NC2[]3, and one for the NC4[]3
- * When using this SMART Active Part for the NC2[]3 or NC4[]3, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB. This SMART Active Part cannot be used on pop-up screens.
- * When using this SMART Active Part for the NC2[]3 or NC4[]3, do not use it on the initial screen.
- * When using this SMART Active Part for the NC2[]3 or NC4[]3, use system version 5 or higher.
- * When reusing SMART Active Parts, be sure to set the unit number.
- * Number of frames: NC2[]3 Part: 1 frame, NC4[]3 Part: 1 frame
- * The storage directories are as follows: Parts for DM Area alStorage directorys in words for Special I/O Units: NC\NC1[]3\SIOU_DM_AreaAlStorage directorys

UserSetDM AreaAlStorage directorys: NC\NC1[]3\UserSetDM AreaAlStorage directorys

NC2[]3: Parts for DM Area alStorage directorys in words for Special I/O Units: NC\NC2[]3\SIOU_DM_AreaAlStorage directorys

UserSetDM AreaAlStorage directorys: NC\NC2[]3\UserSetDM AreaAlStorage directorys

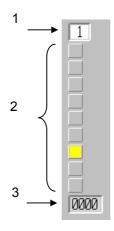
NC4[]3: Parts for DM Area alStorage directorys in words for Special I/O Units: NC\NC4[]3\SIOU_DM_AreaAlStorage directorys

UserSetDM AreaAlStorage directorys: NC\NC3x3\UserSetDM AreaAlStorage directorys

1.1.8 I/O Status Monitoring (No Name)

Unit type	CS1W-NC113/133/213/233/413/ 433 CJ1W-NC113/133/213/233/413/ 433	Storage directory	SmartActiveParts_E\M otion\NC\NCxx3	Title	I/O Status Monitor (No Name)	
Function	Displays the I/O status and error codes for each axis.					

Display and Operation Details



No.	Item	Setting/ display	Description
1	Axis	Setting	Sets the axis number. The setting ranges are as follows: NC1[]3: Always 1, NC2[]3: 1 to 2, NC4[]3: 1 to 4 Note: Axis 1: Axis X, Axis 2: Axis Y, Axis 3: Axis Z, Axis 4: Axis U
2	I/O Status	Display	Displays the I/O status. The display will be lit yellow for any status signals that are ON. The order of the status is the same as that for 2.7.7 I/O Status.
3	Error code	Display	Displays any error codes that have been generated.

Remarks

- * There are three different version of this SMART Active Part depending on the following area alStorage directorys. One for the NC1[]3, one for the NC2[]3, and one for the NC4[]3
- * When using this SMART Active Part for the NC2[]3 or NC4[]3, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB. This SMART Active Part cannot be used on pop-up screens.
- * When using this SMART Active Part for the NC2[]3 or NC4[]3, do not use it on the initial screen.
- * When using this SMART Active Part for the NC2[]3 or NC4[]3, use system version 5 or higher.
- * When reusing SMART Active Parts, be sure to set the unit number.
- * Number of frames: NC2[]3 Part: 1 frame, NC4[]3 Part: 1 frame
- * The storage directories are as follows: Parts for DM Area alStorage directorys in words for Special I/O Units: NC\NC1[]3\SIOU_DM_AreaAlStorage directorys

UserSetDM_AreaAlStorage directorys: NC\NC1[]3\UserSetDM_AreaAlStorage directorys

NC2[]3: Parts for DM Area alStorage directorys in words for Special I/O Units: NC\NC2[]3\SIOU_DM_AreaAlStorage directorys

UserSetDM_AreaAlStorage directorys: NC\NC2[]3\UserSetDM_AreaAlStorage directorys

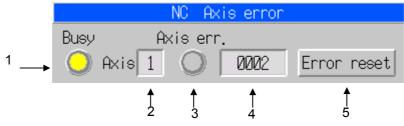
NC4[]3: Parts for DM Area alStorage directorys in words for Special I/O Units: NC\NC4[]3\SIOU_DM_AreaAlStorage directorys

UserSetDM_AreaAlStorage directorys: NC\NC3x3\UserSetDM_AreaAlStorage directorys

1.1.9 Axis Error

Unit type	CS1W-NC113/133/213/233/413/ 433 CJ1W-NC113/133/213/233/413/ 433	Storage directory	SmartActiveParts_E\Mo tion\NC\NCxx3	Title	Axis Error	
Function	Displays and resets axis errors.					

Display and Operation Details



No.	ltem	Setting/ display	Description			
1	Busy	Display	Lights yellow when processing is being performed for the axis.			
2	Axis	Setting	Sets the axis number. The setting ranges are as follows: NC1[]3: Always 1, NC2[]3: 1 to 2, NC4[]3: 1 to 4 Note: Axis 1: Axis X, Axis 2: Axis Y, Axis 3: Axis Z, Axis 4: Axis U			
3	Axis error	Display	Lights yellow when an axis error has occurred.			
4	Error code	Display	Displays any error codes that have been generated.			
5	Error reset	Setting	Resets the error.			

Remarks

- * There are three different version of this SMART Active Part depending on the following area alStorage directorys. One for the NC1[]3, one for the NC2[]3, and one for the NC4[]3
- * When using this SMART Active Part for the NC2[]3 or NC4[]3, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB. This SMART Active Part cannot be used on pop-up screens.
- * When using this SMART Active Part for the NC2[]3 or NC4[]3, do not use it on the initial screen.
- * When using this SMART Active Part for the NC2[]3 or NC4[]3, use system version 5 or higher.
- * When reusing SMART Active Parts, be sure to set the unit number.
- * Number of frames: NC2[]3 Part: 1 frame, NC4[]3 Part: 1 frame
- * The storage directories are as follows: Parts for DM Area alStorage directorys in words for Special I/O Units: NC\NC1[]3\SIOU DM AreaAlStorage directorys

UserSetDM AreaAlStorage directorys: NC\NC1[]3\UserSetDM AreaAlStorage directorys

NC2[]3: Parts for DM Area alStorage directorys in words for Special I/O Units: NC\NC2[]3\SIOU_DM_AreaAlStorage directorys

UserSetDM AreaAlStorage directorys: NC\NC2[]3\UserSetDM AreaAlStorage directorys

NC4[]3: Parts for DM Area alStorage directorys in words for Special I/O Units: NC\NC4[]3\SIOU_DM_AreaAlStorage directorys

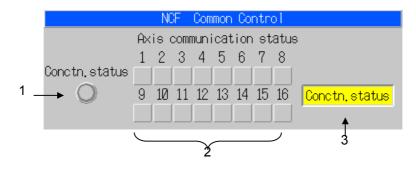
UserSetDM AreaAlStorage directorys: NC\NC3x3\UserSetDM AreaAlStorage directorys

1.2 MECHATROLINK-compatible Position Control Units

1.2.1 Common Control

Unit type	CJ1W-NCF71	Storage directory	SmartActiveParts_E\ Motion\ NCF	Title	Common Control		
Function	Establishes a co	Establishes a connection and displays the connection status and axis communications status.					

Display and Operation Details



No.	Item	Setting/ display	Description
1	Connection status	Display	Displays the connection status. If the Unit is ready to start MECHATROLINK communications, the status indicator will be lit in yellow.
2	Axis communication status	Display	Displays the communications status between the Unit and the MECHATROLINK device. The status indicator will be lit in yellow during communications.
3	Establish connection	Setting	Establishes a connection. If a button lit in yellow is pressed, communications will be disconnected and the button will turn gray.

Remarks

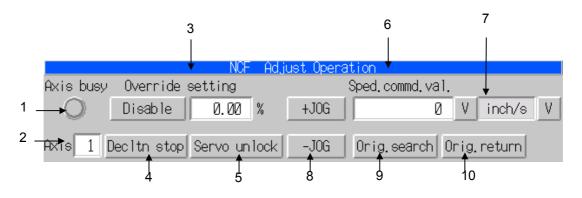
- * When reusing SMART Active Parts, be sure to set the unit number.
- * Data is saved in the following areas:

Operating output memory area in CIO Area and Operating input memory area in CIO Area: OutCIO_InCIO Operating output memory area in CIO Area and Operating input memory area in DM Area: OutCIO_InDM Operating output memory area in DM Area and Operating input memory area in CIO Area: OutDM_InCIO Operating output memory area in DM Area and Operating input memory area in DM Area: OutDM_InDM

1.2.2 Adjust Operation

Unit type	CJ1W-NCF71	Storage directory	SmartActiveParts_E\Mot ion\ NCF	Title	Adjust Operation	
Function	Performs jogging, origin searches, and origin returns.					

Display and Operation Details



No.	Item	Setting/ display	Description
1	Axis busy	Display	Lights yellow when processing is being performed for the axis.
2	Axis	Setting	Sets the axis number. (Setting range: 1 to 16)
3	Override setting	Setting	Sets an override value and enables and disables the override. (Setting range: 0.01% to 327.67%)
4	Deceleration stop	Setting	When pressed, lights yellow and decelerates the motor to a stop. Jogging, origin searches, and origin returns cannot be performed during a deceleration stop.
5	Servo Lock	Setting	Switches between servo lock and servo unlock status.
6	Speed command value	Setting	Sets the speed. The position of the decimal point can be set. The settings for the position of the decimal point are as follows: No decimal point, 0.1, 0.01, 0.001 (Setting range: 0 to 2,147,483,647 command units/s)
7	Unit	Setting	Sets the unit. The settings for the unit are as follows: mm/s, inches/s, degrees/s, or pulses/s
8	JOG operation	Setting	When held down, operates the motor in the specified direction. When released, stops motor operation.
9	Origin search	Setting	When pressed, starts an origin search operation.
10	Origin return	Setting	When pressed, starts an origin return operation.

- * There are four different version of this SMART Active Part depending on the following area alStorage directorys.

 Operating output memory area in CIO Area and Operating input memory area in CIO Area

 Operating output memory area in DM Area and Operating input memory area in CIO Area

 Operating output memory area in DM Area and Operating input memory area in CIO Area

 Operating output memory area in DM Area and Operating input memory area in DM Area
- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics**, **Data/Time**, and **Address Index** for the \$SW. This SMART Active Part cannot be used on pop-up screens.
- * Do not use this SMART Active Part on the initial screen.
- * Use system version 5 or higher.
- * When reusing SMART Active Parts, be sure to set the unit number. Also, the position of the decimal point can be set. The settings for the position of the decimal point are as follows:
- No decimal point, 0.1, 0.01, 0.001
- * Number of frames: 1 frame
- * Data is saved in the following areas:
- * Operating output memory area in CIO Area and Operating input memory area in CIO Area: OutCIO_InCIO Operating output memory area in CIO Area and Operating input memory area in DM Area: OutCIO_InDM Operating output memory area in DM Area and Operating input memory area in CIO Area: OutDM_InCIO Operating output memory area in DM Area and Operating input memory area in DM Area: OutDM InDM

1.2.3 Dire	ect Operation										
Unit type	CJ1W-NCF71		Storage directory		nartActiveF n\ NCF	Parts_E\Mot	Title	9	Direct O	peratio	n
Function	Performs direct op	Performs direct operation using an absolute or relative movement command.									
Display an	d Operation Details	3			7	8			10		
		V	NCF	Dire	ect Oper	ation					
Ĥ	xis busy Overn	ride set	ting		+	Sped. comno	d.val.		\downarrow		
1 _	Disab	le	0.00	%	Start		0	V	mm/s	٧	
						Postn.comr	nd. va l				
2 🔟	⊠is 1 Decltn	stop Se	rvo un	lock	ABS		0	V	mm	٧	
		1	† 5		†	9			11		

No.	Item	Setting/ display	Description
1	Axis busy	Display	Lights yellow when processing is being performed for the axis.
2	Axis	Setting	Sets the axis number. (Setting range: 1 to 16)
3	Override setting	Setting	Sets an override value and enables and disables the override. (Setting range: 0.01% to 327.67%)
4	Deceleration stop	Setting	When pressed, lights yellow and decelerates the motor to a stop. Absolute and relative movement commands cannot be used during a deceleration stop
5	Servo Lock	Setting	Switches between servo lock and servo unlock status.
6	ABS/INC	Setting	Switches the between an absolute movement command (ABS) and a relative movement command (INC).
7	Start	Setting	Starts operation for the movement command specified for ABS/INC (6).
8	Speed command value	Setting	Sets the speed. (Setting range: 0 to 2,147,483,647 command units/s) The position of the decimal point can be set. The settings for the position of the decimal point are as follows: No decimal point, 0.1, 0.01, 0.001
9	Position command value	Setting	Sets the position. (Setting range: 2,147,483,648 to 2,147,483,647 command units) The position of the decimal point can be set. The settings for the position of the decimal point are as follows: No decimal point, 0.1, 0.01, 0.001
10	Speed command value unit	Setting	Sets the unit for the speed command. The settings for the unit are as follows: mm/s, inches/s, degrees/s, or pulses/s
11	Position command value unit	Setting	Sets the unit for the position command. The settings for the unit are as follows: mm, inch, deg, pulse

Remarks

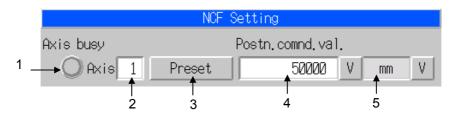
- There are four different version of this SMART Active Part depending on the following area alStorage directorys. Operating output memory area in CIO Area and Operating input memory area in CIO Area Operating output memory area in CIO Area and Operating input memory area in DM Area
 - Operating output memory area in DM Area and Operating input memory area in CIO Area
 - Operating output memory area in DM Area and Operating input memory area in DM Area
- When using this SMART Active Part, be sure to select Setting System Settings in the menu bar, press the System Memory List Button on the Initial Tab Page, and select Basics, Data/Time, and Address Index for the \$SW. This SMART Active Part cannot be used on pop-up screens.
- Do not use this SMART Active Part on the initial screen.
- Use system version 5 or higher.
- When reusing SMART Active Parts, be sure to set the unit number.
- Number of frames: 1
- Data is saved in the following areas:

Operating output memory area in CIO Area and Operating input memory area in CIO Area: OutCIO_InCIO Operating output memory area in CIO Area and Operating input memory area in DM Area: OutCIO InDM Operating output memory area in DM Area and Operating input memory area in CIO Area: OutDM_InCIO Operating output memory area in DM Area and Operating input memory area in DM Area: OutDM InDM

1.2.4 Setting

Unit type	CJ1W-NCF71	Storage directory	SmartActiveParts_E\ Motion\ NCF	Title	Setting	
Function	Executes a present position preset.					

Display and Operation Details



No.	Item	Setting/ display	Description
1	Axis busy	Display	Lights yellow when processing is being performed for the axis.
2	Axis	Setting	Sets the axis number. (Setting range: 1 to 16)
3	Preset	Setting	Executes the present position preset.
4	Position	Setting	Sets the position. (Setting range: 2,147,483,648 to 2,147,483,647 command
4	command value	Setting	units)
5	Unit	Setting	Sets the unit. The settings for the unit are as follows: mm, inch, deg, pulse

Remarks

- * There are four different version of this SMART Active Part depending on the following area alStorage directorys. Operating output memory area in CIO Area and Operating input memory area in CIO Area Operating output memory area in CIO Area and Operating input memory area in DM Area Operating output memory area in DM Area and Operating input memory area in CIO Area Operating output memory area in DM Area and Operating input memory area in DM Area
- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics**, **Data/Time**, and **Address Index** for the \$SW. This SMART Active Part cannot be used on pop-up screens.
- * Do not use this SMART Active Part on the initial screen.
- * Use system version 5 or higher.
- * When reusing SMART Active Parts, be sure to set the unit number.
- * Number of frames: 2
- * Data is saved in the following areas:

Operating output memory area in CIO Area and Operating input memory area in CIO Area: OutCIO_InCIO Operating output memory area in CIO Area and Operating input memory area in DM Area: OutCIO_InDM Operating output memory area in DM Area and Operating input memory area in CIO Area: OutDM_InCIO Operating output memory area in DM Area and Operating input memory area in DM Area: OutDM_InDM

1.2.5 Present Value Monitoring

Unit type	CJ1W-NCF71	Storage directory	SmartActiveParts_E\Mot ion\ NCF	Title	Present Value Monitor		
Function	Displays the present value of the specified monitor item.						

Display and Operation Details



No.	Item	Setting/ display	Description
1	Axis	Setting	Sets the axis number. (Setting range: 1 to 16)
2	Monitor	Setting	Sets the area to be monitored. (Setting range: 1 to 2)
3	Monitor type	Setting	Sets the type of present value to monitor. The settings for the type of present value to monitor are as follows: FB present position, Command present position, FB speed, Command speed, Position error, Torque command value
4	Present value Disp		Displays the present value of the specified monitor item.
5	Unit	Display	Sets the unit. The settings for the unit are as follows: Present position and position error: mm, inch, deg, pulse Speed: mm/s, inches/s, degrees/s, or pulses/s Torque command value: %

Remarks

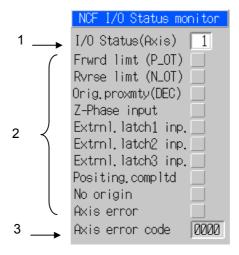
- * There are four different version of this SMART Active Part depending on the following area alStorage directorys. Operating output memory area in CIO Area and Operating input memory area in CIO Area Operating output memory area in CIO Area and Operating input memory area in DM Area Operating output memory area in DM Area and Operating input memory area in CIO Area Operating output memory area in DM Area and Operating input memory area in DM Area
- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics**, **Data/Time**, and **Address Index** for the \$SW. This SMART Active Part cannot be used on pop-up screens.
- * Do not use this SMART Active Part on the initial screen.
- * Use system version 5 or higher.
- * When reusing SMART Active Parts, be sure to set the unit number.
- * Number of frames: 4
- * Data is saved in the following areas: Operating output memory area in CIO Area and Operating input memory area in CIO Area: OutCIO_InCIO Operating output memory area in CIO Area and Operating input memory area in DM Area: OutCIO_InDM Operating output memory area in DM Area and Operating input memory area in CIO Area: OutDM_InCIO

Operating output memory area in DM Area and Operating input memory area in DM Area: OutDM_InDM

1.2.6 I/O Status Monitoring

Unit type	CJ1W-NCF71	Storage directory	SmartActiveParts_E\Motio n\ NCF	Title	I/O Status Monitor
Function	Displays the I/O status and error codes for each axis.				

Display and Operation Details



No.	Item	Setting/ display	Description
1	Axis	Setting	Sets the axis number. (Setting range: 1 to 16)
2	I/O status	Display	Displays the I/O status. The display will be lit yellow for any status signals that are ON.
3	Error code	Display	Displays any error codes that have been generated.

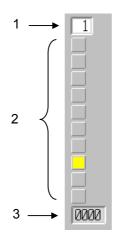
- * There are two different version of this SMART Active Part depending on the following area alStorage directorys.

 One for operating input memory area in CIO Area and one for operating input memory area in DM Area
- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics**, **Data/Time**, and **Address Index** for the \$SW. This SMART Active Part cannot be used on pop-up screens.
- * Do not use this SMART Active Part on the initial screen.
- * Use system version 5 or higher.
- * When reusing SMART Active Parts, be sure to set the unit number.
- * Number of frames: 1
- * Data is saved in the following areas:
 - Operating output memory area in CIO Area and Operating input memory area in CIO Area: OutCIO_InCIO Operating output memory area in CIO Area and Operating input memory area in DM Area: OutCIO_InDM Operating output memory area in DM Area and Operating input memory area in CIO Area: OutDM_InCIO Operating output memory area in DM Area and Operating input memory area in DM Area: OutDM_InDM

1.2.7 I/O Status Monitoring (No name)

Unit type	CJ1W-NCF71	Storage directory	SmartActiveParts_E\Motio n\ NCF	Title	I/O Status Monitor (No Name)
Function	Displays the I/O status and error codes for each axis.				

Display and Operation Details



No.	Item	Setting/ display	Description
1	Axis	Setting	Sets the axis number. (Setting range: 1 to 16)
2	I/O Status	Displays the I/O status. The display will be lit yellow for any signals that are ON. The order of the status is the same as that for 2.8.6 I/O Status.	
3	Error code	Display	Displays any error codes that have been generated.

Remarks

- * There are two different version of this SMART Active Part depending on the following area alStorage directorys.

 One for operating input memory area in CIO Area and one for operating input memory area in DM Area

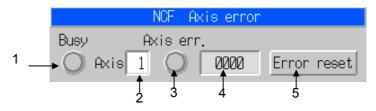
 When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics**, **Data/Time**, and **Address Index** for the \$SW. This SMART Active Part cannot be used on pop-up screens.
- * Do not use this SMART Active Part on the initial screen.
- * Use system version 5 or higher.
- * When reusing SMART Active Parts, be sure to set the unit number.
- Number of frames: 1
- * Data is saved in the following areas:

Operating output memory area in CIO Area and Operating input memory area in CIO Area: OutCIO_InCIO Operating output memory area in CIO Area and Operating input memory area in DM Area: OutCIO_InDM Operating output memory area in DM Area and Operating input memory area in CIO Area: OutDM_InCIO Operating output memory area in DM Area and Operating input memory area in DM Area: OutDM_InDM

1.2.8 Axis Error

Unit type	CJ1W-NCF71	Storage directory	SmartActiveParts_E\ Motion\ NCF	Title	Axis Error	
Function	Displays and resets axis errors.					

Display and Operation Details



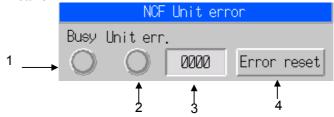
No.	Item	Setting/ display	Description
1	Busy	Display	Lights yellow when processing is being performed for the axis.
2	Axis	Setting	Sets the axis number. (Setting range: 1 to 16)
3	Axis error	Display	Lights yellow when an axis error has occurred.
4	Error code	Display	Displays any error codes that have been generated.
5	Error reset	Setting	Resets the axis error.

- * There are four different version of this SMART Active Part depending on the following area alStorage directorys. Operating output memory area in CIO Area and Operating input memory area in CIO Area Operating output memory area in CIO Area and Operating input memory area in DM Area Operating output memory area in DM Area and Operating input memory area in CIO Area Operating output memory area in DM Area and Operating input memory area in DM Area
- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics**, **Data/Time**, and **Address Index** for the \$SW. This SMART Active Part cannot be used on pop-up screens.
- * Do not use this SMART Active Part on the initial screen.
- * Use system version 5 or higher.
- * When reusing SMART Active Parts, be sure to set the unit number.
- Number of frames: 1
- * Data is saved in the following areas:
 Operating output memory area in CIO Area and Operating input memory area in CIO Area: OutCIO_InCIO
 Operating output memory area in CIO Area and Operating input memory area in DM Area: OutCIO_InDM
 Operating output memory area in DM Area and Operating input memory area in CIO Area: OutDM_InCIO
 Operating output memory area in DM Area and Operating input memory area in DM Area: OutDM_InDM

1.2.9 Unit Error

Unit type	CJ1W-NCF71	Storage directory	SmartActiveParts_E\Motio n\ NCF	Title	Unit Error
Function	Displays and resets Unit errors.				

Display and Operation Details



No.	Item	Setting/ display	Description
1	Busy	Display	Lights yellow during Unit processing.
2	Unit error	Display Lights yellow when a Unit error has occurred.	
3	Error code	Display	Displays any Unit error codes that have been generated.
4	Error reset	Setting	Resets the Unit error.

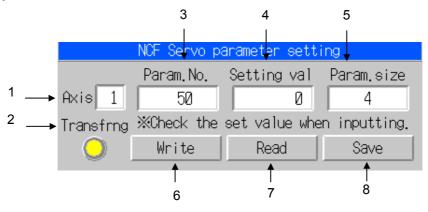
Remarks

- * When reusing SMART Active Parts, be sure to set the unit number.
- * Data is saved in the following areas:

Operating output memory area in CIO Area and Operating input memory area in CIO Area: OutCIO_InCIO Operating output memory area in CIO Area and Operating input memory area in DM Area: OutCIO_InDM Operating output memory area in DM Area and Operating input memory area in CIO Area: OutDM_InCIO Operating output memory area in DM Area and Operating input memory area in DM Area: OutDM_InDMM

1.2.10 Servo Parameter Setting

Unit type	CJ1W-NCF71	Storage directory	SmartActiveParts_E\Moti on\ NCF	Title	Servo Parameter Setting		
Function		Sets and displays servo parameters.					
Dienlay and	Display and Operation Details						



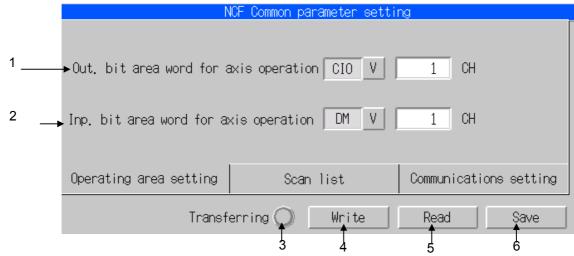
No.	Item	Setting/ display	Description		
1 Axis Setting 2 Transferring Display 3 Parameter No. Setting		Setting	Sets the axis number. (Setting range: 1 to 16)		
		Display	Lights yellow when servo parameters are being transferred.		
		Setting	Sets the parameter number.		
4	Setting value	Setting/ display	Specify the data to write to the servo drive.		
5	5 Parameter size Setting		Sets the parameter size. Set the size as a hexadecimal value. Be sure to set the correct size.		
6			Writes the setting to control memory in the servo drive.		
		Setting	Reads the servo parameter.		
		Setting	Saves the servo parameter to nonvolatile memory in the servo drive.		

- There are four different version of this SMART Active Part depending on the following area alStorage directorys. Operating output memory area in CIO Area and Operating input memory area in CIO Area

 - Operating output memory area in CIO Area and Operating input memory area in DM Area
 - Operating output memory area in DM Area and Operating input memory area in CIO Area
 - Operating output memory area in DM Area and Operating input memory area in DM Area
- When using this SMART Active Part, be sure to select Setting System Settings in the menu bar, press the System Memory List Button on the Initial Tab Page, and select Basics, Data/Time, and Address Index for the \$SW. This SMART Active Part cannot be used on pop-up screens.
- Do not use this SMART Active Part on the initial screen.
- Use system version 5 or higher.
- When reusing SMART Active Parts, be sure to set the unit number.
- Number of frames: 1
- Data is saved in the following areas:
 - Operating output memory area in CIO Area and Operating input memory area in CIO Area: OutCIO InCIO Operating output memory area in CIO Area and Operating input memory area in DM Area: OutCIO InDM Operating output memory area in DM Area and Operating input memory area in CIO Area: OutDM InCIO Operating output memory area in DM Area and Operating input memory area in DM Area: OutDM InDM

1.2.11 Area Setting

1.2.11 Area Setting						
Unit type	CJ1W-NCF71	Storage directory	SmartActiveParts_E\ Motion\ NCF	Title	Area Setting (Common Parameter Setting)	
Function	Sets and displays the operating output and input areas.					
Display and Operation Details						
	NCF Common parameter setting					



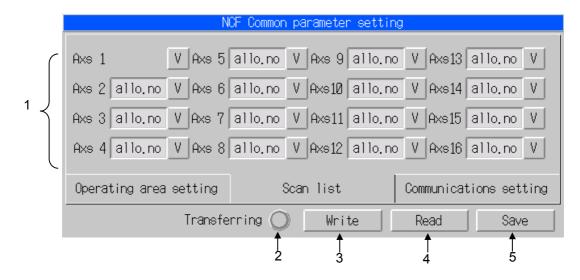
No.	Item	Setting/ display	Description
1	Output bit area word for axis operation	Setting	Sets the operating output area. The settings are as follows: Area: CIO or DM addresses: 0 to 9200
2	Input bit area word for axis operation	Setting	Sets the operating input area. The settings are as follows: Area: CIO or DM addresses: 0 to 9200
3	Transferring	Display	Lights yellow when data is being transferred.
4	Write	Setting	Writes data from the CPU Unit to the Position Control Unit.
5	Read	Setting	Writes data from the Position Control Unit to the CPU Unit.
6	Save	Setting	Saves the contents of internal memory in the Position Control Unit to built-in flash memory.

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB. This SMART Active Part cannot be used on pop-up screens.
- * Do not use this SMART Active Part on the initial screen.
- * Use system version 5 or higher.
- * When reusing SMART Active Parts, be sure to set the unit number.
- * Number of frames: 1 frame (total for operating area settings, scan list, and communications settings)
- * Data is saved in the following areas:
 - Operating output memory area in CIO Area and Operating input memory area in CIO Area: OutCIO_InCIO Operating output memory area in CIO Area and Operating input memory area in DM Area: OutCIO_InDM Operating output memory area in DM Area and Operating input memory area in CIO Area: OutDM_InCIO Operating output memory area in DM Area and Operating input memory area in DM Area: OutDM_InDM

1.2.12 Scan List (Common Parameter Setting)

Unit type	CJ1W-NCF71	Storage directory	SmartActiveParts_E\ Motion\ NCF	Title	Scan List (Common Parameter Setting)		
Function	Sets and displays	Sets and displays the scan list for the MECHATROLINK devices connected to the Unit.					

Display and Operation Details



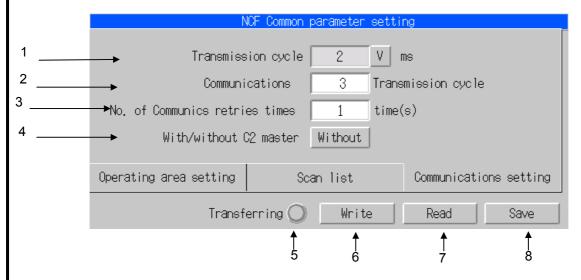
No.	Item	Setting/ display	Description		
1	Scan List	Setting	Switches the alStorage directorys for MECHATROLINK devices connected to the Unit between servo alStorage directorys and no alStorage directorys.		
2	Transferring	Display	Lights yellow when data is being transferred.		
3	Write	Setting	Writes data from the CPU Unit to the Position Control Unit.		
4	Read	Setting	Writes data from the Position Control Unit to the CPU Unit.		
5	Save	Setting	Saves the contents of internal memory in the Position Control Unit to built-in flash memory.		

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB. This SMART Active Part cannot be used on pop-up screens.
- * Do not use this SMART Active Part on the initial screen.
- * Use system version 5 or higher.
- * When reusing SMART Active Parts, be sure to set the unit number.
- Number of frames: 1 frame (total for operating area settings, scan list, and communications settings)
- * Data is saved in the following areas:
 - Operating output memory area in CIO Area and Operating input memory area in CIO Area: OutCIO_InCIO Operating output memory area in CIO Area and Operating input memory area in DM Area: OutCIO_InDM Operating output memory area in DM Area and Operating input memory area in CIO Area: OutDM_InCIO Operating output memory area in DM Area and Operating input memory area in DM Area: OutDM_InDM

1.2.13 Communications Setting (Common Parameter Setting)

Unit type	CJ1W-NCF71	Storage directory	SmartActiveParts_E\ Motion\ NCF	Title	Communications Setting (Common Parameter Setting)
Function	Sets and displays the transmission cycle, communications cycle, number of communications retries, and C2 master setting.				

Display and Operation Details



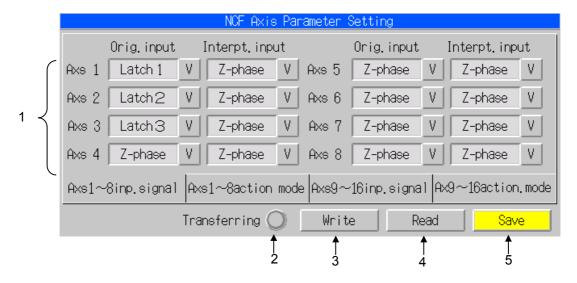
No.	Item	Setting/ display	Description
1	Transmission cycle	Setting	Specifies the cycle for data transfers in MECHATROLINK communications. The settings are as follows: 1, 2, 3, 4, 5, 6, 7, 9, 0.25, or 0.5 ms
2	Communications cycle	Setting	Sets the data update cycle between the Unit and MECHATROLINK devices. (Setting range: 0 to 32 ms)
3	No. of communications retries	Setting	Sets the maximum number of stations for which to retry communications when transferring data between the Unit and MECHATROLINK devices. (Setting range: 0 to 7)
4	With/without C2 master	Setting	Switches between using a communications master and not using a communications master connected for MECHATROLINK system support.
5	Transferring	Display	Lights yellow when data is being transferred.
6	Write	Setting	Writes data from the CPU Unit to the Position Control Unit.
7	Read	Setting	Writes data from the Position Control Unit to the CPU Unit.
8	Save	Setting	Saves the contents of internal memory in the Position Control Unit to built-in flash memory.

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB. This SMART Active Part cannot be used on pop-up screens.
- * Do not use this SMART Active Part on the initial screen.
- * Use system version 5 or higher.
- * When reusing SMART Active Parts, be sure to set the unit number.
- * Number of frames: 1 frame (total for operating area settings, scan list, and communications settings)
- * Data is saved in the following areas:
 - Operating output memory area in CIO Area and Operating input memory area in CIO Area: OutCIO_InCIO Operating output memory area in CIO Area and Operating input memory area in DM Area: OutCIO_InDM Operating output memory area in DM Area and Operating input memory area in CIO Area: OutDM_InCIO Operating output memory area in DM Area and Operating input memory area in DM Area: OutDM_InDM

1.2.14 Input Signal Setting (Axis Parameter Setting)

Unit type	CJ1W-NCF71	Storage directory	SmartActiveParts_E\ Motion\ NCF	Title	Input Signal Setting (Axis Parameter Setting)
Function	Sets and displays the input signals for each axis.				

Display and Operation Details



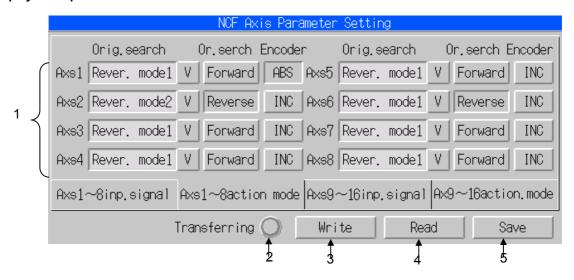
No.	Item	Setting/ display	Description
Origin input		Setting	Specifies the origin input signal to used in origin searches. The settings are as follows: Phase Z, latch 1, latch 2, latch 3
'	Interrupt input	Setting	Specifies the interrupt input signal to used for interrupt feeding. The settings are as follows: Phase Z, latch 1, latch 2, latch 3
2	Transferring	Display	Lights yellow when data is being transferred.
3	Write	Setting	Writes data from the CPU Unit to the Position Control Unit.
4	Read	Setting	Writes data from the Position Control Unit to the CPU Unit.
5	Save	Setting	Saves the contents of internal memory in the Position Control Unit to built-in flash memory.

- * When using this SMART Active Part, be sure to select Setting System Settings in the menu bar, press the System Memory List Button on the Initial Tab Page, and select Basics for the \$SB. This SMART Active Part cannot be used on pop-up screens.
- * Do not use this SMART Active Part on the initial screen.
- * Use system version 5 or higher.
- * When reusing SMART Active Parts, be sure to set the unit number.
- * Number of frames: 1 frame (total for input signals and operation mode)
- * Data is saved in the following areas:
 - Operating output memory area in CIO Area and Operating input memory area in CIO Area: OutCIO_InCIO Operating output memory area in CIO Area and Operating input memory area in DM Area: OutCIO_InDM Operating output memory area in DM Area and Operating input memory area in CIO Area: OutDM_InCIO Operating output memory area in DM Area and Operating input memory area in DM Area: OutDM_InDM

1.2.15 Operating Mode Setting (Axis Parameter Setting)

ľ			Storage	SmartActiveParts E\	<u> </u>	Operating Mode Setting (Axis Parameter
L	Unit type	CJ1W-NCF71	directory	Motion\ NCF	Title	Setting)
	Function	Sets and displays the operating mode for each axis.				

Display and Operation Details



No.	Item	Setting/ display	Description		
	Origin search operation	Setting	Specifies the operation pattern to use in origin searches. The settings are as follows: Reversal mode 1, Reversal mode 2, Single-direction mode		
1	Search direction	Setting	Specifies the origin search direction. The settings are as follows: Forward or reverse		
	Encoder	Setting	Switches the servomotor encoder type between an incremental encoder (INC) and an absolute encoder (ABS).		
2	Transferring	Display	Lights yellow when data is being transferred.		
3	Write	Setting	Writes data from the CPU Unit to the Position Control Unit.		
4	Read	Setting	Writes data from the Position Control Unit to the CPU Unit.		
5	Save	Setting	Saves the contents of internal memory in the Position Control Unit to built-in flash memory.		

Remarks

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB. This SMART Active Part cannot be used on pop-up screens.
- * Do not use this SMART Active Part on the initial screen.
- * Use system version 5 or higher.
- * When reusing SMART Active Parts, be sure to set the unit number.
- * Number of frames: 1 frame (total for input signals and operation mode)
- * Data is saved in the following areas:

Operating output memory area in CIO Area and Operating input memory area in CIO Area: OutCIO_InCIO Operating output memory area in CIO Area and Operating input memory area in DM Area: OutCIO_InDM Operating output memory area in DM Area and Operating input memory area in CIO Area: OutDM_InCIO Operating output memory area in DM Area and Operating input memory area in DM Area: OutDM_InDM

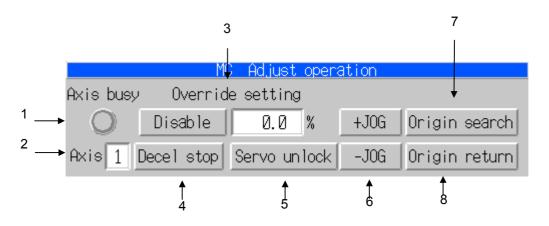
Motion Control

1.3 Standard Motion Control Units

1.3.1 Adjust operation

Unit type	CS1W-MC221 CS1W-MC421	Storage directory	SmartActiveParts_E\Moti on\MC	Title	Adjust Operation	
Function	Performs jogging, origin searches, and origin returns.					

Display and Operation Details



No.	Item	Setting/ display	Description
1	Axis busy	Display	Lights yellow when processing is being performed for the axis.
2	Axis	Setting	Sets the axis number. The setting ranges are as follows: MC221: 1 to 2 MC421: 1 to 4 Note: Axis 1: Axis X, Axis 2: Axis Y, Axis 3: Axis Z, Axis 4: Axis U
3	Override setting	Setting	Sets an override value and enables and disables the override. (Setting range: 0.0 to 199.9)
4	Deceleration stop	Setting	When pressed, lights yellow and decelerates the motor to a stop. Jogging, origin searches, and origin returns cannot be performed during a deceleration stop.
5	Servo Lock	Setting	Switches between servo lock and servo unlock status.
6	JOG operation	Setting	When held down, operates the motor in the specified direction. When released, stops motor operation.
7	Origin search	Setting	When pressed, starts an origin search operation.
8	Origin return	Setting	When pressed, starts an origin return operation.

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** and **Data/Time** for the \$SB. This SMART Active Part cannot be used on pop-up screens.
- * Do not use this SMART Active Part on the initial screen.
- * Use system version 5 or higher.
- * There are two versions of this SMART Active Part, one for the MC221 and one for the MC421.
- * When reusing SMART Active Parts, be sure to set the unit number.
- Number of frames: 1

1.3.2 Program Operation

11012 1 10	gram Operati	011						
Unit type	CS1W-MC221 CS1W-MC421	Storage directory	SmartActiveParts_I tion\ MC	Title	Program	Operation		
Function	Executes memor	(program) operation.						
Display an	d Operation Deta	ils						
,	D 0 1	3	7 MC Program C	8 perat	ion	9	10	
1 2	Busy Overrid Disable Task Manual Decel sto		Running Program No.		read Sino	y block 0 Pause ↑	N Prog.start Block stop	

No.	Item	Setting/ display	Description
1	Busy	Display	Lights yellow during task processing.
2	Task	Setting	Sets the task number. The setting ranges are as follows: MC221: 1 to 2 MC421: 1 to 4 Note: Axis 1: Axis X, Axis 2: Axis Y, Axis 3: Axis Z, Axis 4: Axis U
3	Override setting	Setting	Sets an override value for the axes used in the task and enables and disables the override. (Setting range: 0.0% to 199.9%)
4	Deceleration stop	Setting	When pressed in manual mode, lights yellow and decelerates the motor to a stop. This button is not displayed in automatic mode.
5	Automatic/Manu al	Setting	Switches between automatic and manual modes. Lights yellow in automatic mode. The Unit must be in automatic mode for a program to be started.
6	Servo Lock	Setting	Switches the axes used by the task between servo lock and servo unlock status.
7	Program No.	Setting	Sets the program number to execute in automatic mode. (Setting range: 0 to 999)
8	Program No. read	Setting	Sets the program number to execute.
9	Single block ON	Setting	Switches to single block mode. (Single block mode executes one block of the program each time <i>Program Start</i> is turned ON and OFF.
10	Program start	Setting	Executes the program.
11	Running program No.	Display	Displays the number of the program being executed.
12	Block No.	Display	Displays the number of the block being executed.
13	Pause	Setting	Pauses execution of the program.
14	Block stop	Setting	Cancels execution of the program.
Dame	a wile o		

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** and **Data/Time** for the \$SB. This SMART Active Part cannot be used on pop-up screens.
- * Do not use this SMART Active Part on the initial screen.
- * Use system version 5 or higher.
- * There are two versions of this SMART Active Part, one for the MC221 and one for the MC421.
- * When reusing SMART Active Parts, be sure to set the unit number.
- * Number of frames: 1

1.3.3 Setting

Unit type	CS1W-MC221 CS1W-MC421	Storage directory	SmartActiveParts_E\Mot ion\MC	Title	Setting
Function	Sets the forced origin and the absolute origin.				

Display and Operation Details



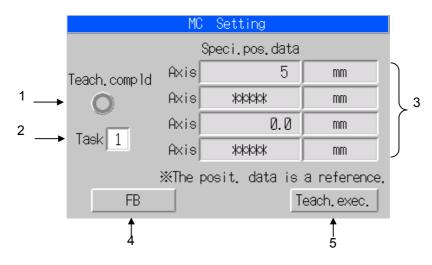
No.	Item	Setting/ display	Description
1	Axis busy	Display	Lights yellow when processing is being performed for the axis.
2	Axis	Setting	Sets the axis number. The setting ranges are as follows: MC221: 1 to 2 MC421: 1 to 4 Note: Axis 1: Axis X, Axis 2: Axis Y, Axis 3: Axis Z, Axis 4: Axis U
3	Forced origin	Setting	Sets the position where the motor is stopped as the origin (i.e., as a position of 0).
4	ABS Forced origin	Setting	Records the position where the motor is stopped in the Motion Control Unit as the absolute origin. (For Absolute Encoder only)
5	Present position	Display	Displays the present position.

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** and **Data/Time** for the \$SB. This SMART Active Part cannot be used on pop-up screens.
- * When using this SMART Active Part, be sure to select **Setting Unit/Scale Setting** in the menu bar and set the scale for number 1000 to 0.0001.
- * Do not use this SMART Active Part on the initial screen.
- * Use system version 5 or higher.
- * There are two versions of this SMART Active Part, one for the MC221 and one for the MC421.
- * When reusing SMART Active Parts, be sure to set the unit number.
- Number of frames: 2

1.3.4 Teaching

Unit type	CS1W-MC221 CS1W-MC421	Storage directory	SmartActiveParts_E\Moti on\MC	Title	Teaching
Function	Executes teaching.				

Display and Operation Details



No.	Item	Setting/ display	Description
1	Teaching completed	Display	Displays the status of teaching. Lit green: Normal end Lit yellow: Teaching address error Lit red: Teaching error
2	Task	Setting	Sets the task number. The setting ranges are as follows: MC221: 1 to 2 MC421: 1 to 4 Note: Axis 1: Axis X, Axis 2: Axis Y, Axis 3: Axis Z, Axis 4: Axis U
3	Specified position data	Display	Sets the position data for axes used by the task. Unused axes are displayed as *****. Note: Only two axes are displayed for the MC221. (There are no axes 3 and 4.)
4	FB	Setting	Sets the teaching type. The button lights yellow when the present position feedback value is set. The button will be gray when the target position is set.
5	Teaching execution	Setting	Executes teaching.

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** and **Data/Time** for the \$SB. This SMART Active Part cannot be used on pop-up screens.
- * When using this SMART Active Part, be sure to select **Setting Unit/Scale Setting** in the menu bar and set the scale for number 1000 to 0.0001.
- * Do not use this SMART Active Part on the initial screen.
- * Use system version 5 or higher.
- * There are two versions of this SMART Active Part, one for the MC221 and one for the MC421.
- * When reusing SMART Active Parts, be sure to set the unit number.
- * Number of frames: 1 frame for the MC221 and 1 frame for the MC421

1.3.5 Present Value Monitoring

Unit type CS1W-MC221 CS1W-MC421 Storage directory SmartActiveParts_E\Moti on\MC Title Present Value Monitor Function Displays the present value of the specified monitor item.							
Function Displays the present value of the specified monitor item.	Unit type			_	Title	Present Value Monitor	
	Function	Displays the present value of the specified monitor item.					

Display and Operation Details



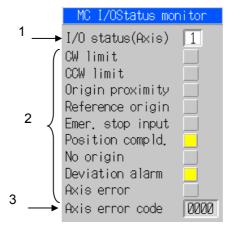
No.	Item	Setting/ display	Description		
1	Axis	Setting	Sets the axis number. The setting ranges are as follows: MC221: 1 to 2 MC421: 1 to 4 Note: Axis 1: Axis X, Axis 2: Axis Y, Axis 3: Axis Z, Axis 4: Axis U		
2	Monitor type	Setting	Sets the type of present value to monitor. The settings are as follows: Present position in workpiece coordinate system, present position in reference coordinate system, present position in reference coordinate system in pulses, position error, workpiece origin shift value, number of multi-turns		
3	Present value	Present value Display Displays the present value of the specified monitor item.			
4	Unit	Display	Displays the unit.		

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** and **Data/Time** for the \$SB. This SMART Active Part cannot be used on pop-up screens.
- * When using this SMART Active Part, be sure to select **Setting Unit/Scale Setting** in the menu bar and set the scale for number 1000 to 0.0001.
- * Do not use this SMART Active Part on the initial screen.
- * Use system version 5 or higher.
- * There are two versions of this SMART Active Part, one for the MC221 and one for the MC421.
- * When reusing SMART Active Parts, be sure to set the unit number.
- * Number of frames: 2

1.3.6 I/O Status Monitoring

Unit type	CS1W-MC221 CS1W-MC421	Storage directory	SmartActiveParts_E\Motio n\MC	Title	I/O Status Monitor
Function	Displays the I/O status and error codes for each axis.				

Display and Operation Details



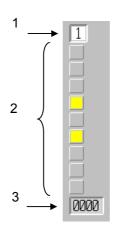
No.	Item	Setting/ display	Description
1	Axis	Setting	Sets the axis number. The setting ranges are as follows: MC221: 1 to 2 MC421: 1 to 4 Note: Axis 1: Axis X, Axis 2: Axis Y, Axis 3: Axis Z, Axis 4: Axis U
2	I/O status	Display	Displays the I/O status. The display will be lit yellow for any status signals that are ON.
3	Error code	Display	Displays any error codes that have been generated.

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** and **Data/Time** for the \$SB. This SMART Active Part cannot be used on pop-up screens.
- * Do not use this SMART Active Part on the initial screen.
- * Use system version 5 or higher.
- * There are two versions of this SMART Active Part, one for the MC221 and one for the MC421.
- * When reusing SMART Active Parts, be sure to set the unit number.
- * Number of frames: 1

1.3.7 I/O Status Monitoring (No name)

Unit type	CS1W-MC221 CS1W-MC421	Storage directory	SmartActiveParts_E\Motio n\MC	Title	I/O Status Monitor (No Name)
Function	Displays the I/O status and error codes for each axis.				

Display and Operation Details



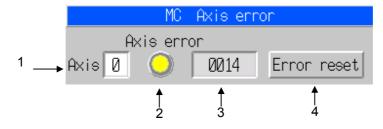
No.	Item	Setting/ display	Description
1	Axis	Setting	Sets the axis number. The setting ranges are as follows: MC221: 1 to 2 MC421: 1 to 4 Note: Axis 1: Axis X, Axis 2: Axis Y, Axis 3: Axis Z, Axis 4: Axis U
2	I/O status	Displays the I/O status. The display will be lit yellow for any signals that are ON. The order of the status is the same as that for 2.9.6 I/O Status.	
3	Error code	Display	Displays any error codes that have been generated.

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** and **Data/Time** for the \$SB. This SMART Active Part cannot be used on pop-up screens.
- * Do not use this SMART Active Part on the initial screen.
- * Use system version 5 or higher.
- * There are two versions of this SMART Active Part, one for the MC221 and one for the MC421.
- * When reusing SMART Active Parts, be sure to set the unit number.
- Number of frames: 1

1.3.8 Axis Error

Unit type	CS1W-MC221 CS1W-MC421	Storage directory	SmartActiveParts_E\Moti on\MC	Title	Axis Error	
Function	Displays and resets axis errors.					

Display and Operation Details



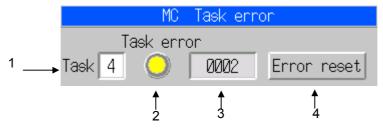
No.	Item	Setting/ display	Description
1	Axis	Setting	Sets the axis number. The setting ranges are as follows: MC221: 1 to 2 MC421: 1 to 4 Note: Axis 1: Axis X, Axis 2: Axis Y, Axis 3: Axis Z, Axis 4: Axis U
2	Axis error	Display	Lights yellow when an axis error has occurred.
3	3 Error code Display		Displays any error codes that have been generated.
4	4 Error reset		Resets the error. Note: When an error is reset, task errors and Unit errors are also reset.

- When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** and **Data/Time** for the \$SB. This SMART Active Part cannot be used on pop-up screens.
- * Do not use this SMART Active Part on the initial screen.
- * There are two versions of this SMART Active Part, one for the MC221 and one for the MC421.
- When reusing SMART Active Parts, be sure to set the unit number.

1.3.9 Task Error

Unit type	CS1W-MC221 CS1W-MC421	Storage directory	SmartActiveParts_E\Moti on\MC	Title	Task Error	
Function	Displays and resets task errors.					

Display and Operation Details



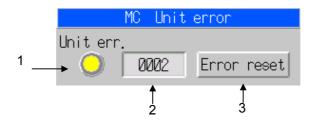
No.	Item	Setting / display	Description		
1	1 Task Setting		Sets the task number. The setting ranges are as follows: 1 Task Setting MC221: 1 to 2 MC421: 1 to 4 Note: Axis 1: Axis X, Axis 2: Axis Y, Axis 3: Axis Z, Axis 4: Axis U		
2 Task error		Display	Lights yellow when a task error has occurred.		
3	Error code	Display	Displays any task error codes that have been generated.		
4	Error reset Setting		Resets the error. Note: When an error is reset, axis errors and Unit errors are also reset.		

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** and **Data/Time** for the \$SB. This SMART Active Part cannot be used on pop-up screens.
- * Do not use this SMART Active Part on the initial screen.
- * There are two versions of this SMART Active Part, one for the MC221 and one for the MC421.
- When reusing SMART Active Parts, be sure to set the unit number.

1.3.10 Unit Error

Unit type	CS1W-MC221 CS1W-MC421	Storage directory	SmartActiveParts_E\Moti on\MC	Titl e	Unit Error	
Function	Displays and resets Unit errors.					

Display and Operation Details



No.	Item	Setting / display	Description
1	Unit error	Display	Lights yellow when a Unit error has occurred.
2	Error code	Display	Displays any Unit error codes that have been generated.
3	Error reset	Setting	Resets the error. Note: When an error is reset, axis errors and task errors are also reset.

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Data/Time** for the \$SB.
- * There are two versions of this SMART Active Part, one for the MC221 and one for the MC421.
- * When reusing SMART Active Parts, be sure to set the unit number.

1.4 MECHATROLINK-compatible Motion Control Units

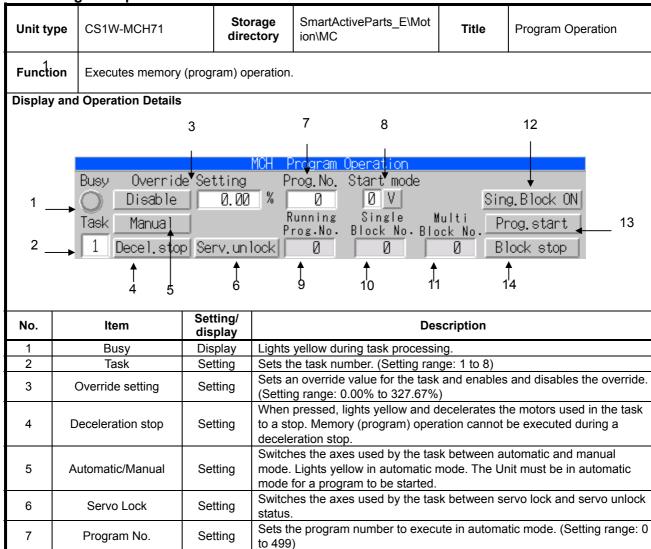
		ust Operat	•	ible Motion oc	7111101	711103				
Unit t	ype	CS1W-MCH	71 Storage directory	SmartActiveParts_on\MCH	Title	Adjust Operation				
Func	tion	Performs jogging, stepping, origin searches, and origin returns.								
Displ	Display and Operation Details									
	3 7									
				1	_		1			
				↓ MCH Adjust	<u>Operat</u>	ion				
		Axis busy	y Overni	de Setting						
1		0	Disable	0.00 %	+J00	à ∫Orio	g, rearch	+STEP		
2	→	Axis 1	Decel.stop	Servo unlock	-J00	à Orio	g. return	-STEP		
			† 4	↑ 5	† 6		† 8	9		
			Setting							

No.	Item	Setting / display	Description
1	Axis busy	Display	Lights yellow when processing is being performed for the axis.
2	Axis	Setting	Sets the axis number. (Setting range: 1 to 32)
3	Override setting	Setting	Sets an override value and enables and disables the override. (Setting range: 0.00 to 327.67)
4	Deceleration stop	Setting	When pressed, lights yellow and decelerates the motor to a stop. Jogging, stepping, origin searches, and origin returns cannot be performed during a deceleration stop.
5	Servo Lock	Setting	Switches between servo lock and servo unlock status.
6	JOG operation	Setting	When held down, operates the motor in the specified direction. When released, stops motor operation.
7	Origin rearch	Setting	When pressed, starts an origin search operation.
8	Origin return	Setting	When pressed, starts an origin return operation.
9	STEP operation	Setting	When pressed, starts a step operation.

Remarks

- * There are four different version of this SMART Active Part depending on the following user-set area alStorage directorys.
 - User-set memory area in CIO area and user-set data area in DM Area
 - User-set memory area in CIO area and user-set data area in EM0 Area
 - User-set memory area in Work area and user-set data area in DM Area
 - User-set memory area in Work area and user-set data area in EM0 Area
- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics**, **Data/Time**, and **Address Index for the \$SW**. This SMART Active Part cannot be used on pop-up screens.
- * Do not use this SMART Active Part on the initial screen.
- * Use system version 5 or higher.
- * When reusing SMART Active Parts, be sure to set the unit number.
- * Number of frames: 1
- * Data is saved in the following areas:

1.4.2 Program Operation



14 Remarks

8

9

10

11

12

13

* There are two different version of this SMART Active Part, one for a CIO Area user-set memory area and one for a Work Area user-set memory area.

Executes the program.

Execute from next block

executed.

executed.

Specifies the program start position. The settings are as follows:

Execute from beginning of program, Execute from current block,

Displays the block number of the single block execution command being

Displays the block number of the multi-block execution command being

Switches to single block mode. (Single block mode executes one block of

the program each time Program Start is turned ON and OFF.)

Stops program execution at the end of the current block.

Displays the number of the program being executed.

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics**, **Data/Time**, and **Address Index** for the \$SW. This SMART Active Part cannot be used on pop-up screens.
- * Do not use this SMART Active Part on the initial screen.
- * Use system version 5 or higher.
- * When reusing SMART Active Parts, be sure to set the unit number.

Setting

Display

Display

Display

Setting

Setting

Setting

- * Number of frames:
- * Data is saved in the following areas:

Start mode

Running program

No.

Single block No.

Multi block No.

Single block ON

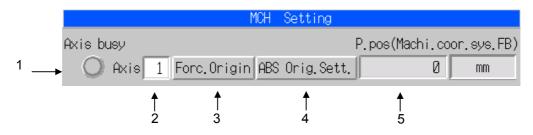
Program start

Block stop

1.4.3 Setting

Unit type	CS1W-MCH71	Storage directory	SmartActiveParts_E\Moti on\MCH	Title	Setting	
Function	Sets the forced origin and the absolute origin.					

Display and Operation Details



No.	Item	Setting/ display	Description
1	Axis busy	Display	Lights yellow when processing is being performed for the axis.
2	Axis	Setting	Sets the axis number. (Setting range: 1 to 32)
3	Forced Origin	Setting	Sets the position where the motor is stopped as the origin (i.e., as a position of 0).
4	ABS Origin Setting	Setting	Records the position where the motor is stopped in the Motion Control Unit as the absolute origin. (For Absolute Encoder only)
5	Present Position	Display	Displays the present position.

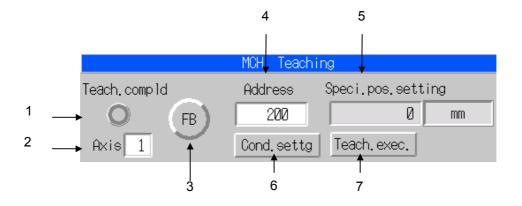
Remarks

- * There are two different version of this SMART Active Part, one for a CIO Area user-set memory area and one for a Work Area user-set memory area.
- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics**, **Data/Time**, and **Address Index** for the \$SW. This SMART Active Part cannot be used on pop-up screens.
- * When using this SMART Active Part, be sure to select **Setting Unit/Scale Setting** in the menu bar and set the scale for number 1000 to 0.0001.
- * Do not use this SMART Active Part on the initial screen.
- * Use system version 5 or higher.
- * When reusing SMART Active Parts, be sure to set the unit number.
- * Number of frames: 2
- * Data is saved in the following areas:

1.4.4 Teaching

Unit type	CS1W-MCH71	Storage directory	SmartActiveParts_E\Moti on\MCH	Title	Teaching
Function	Executes teaching.				

Display and Operation Details



No.	Item	Setting/ display	Description
1	Teaching completed	Display	Displays the status of teaching. Lit green: Teaching completed Lit yellow: Setting conditions completed Lit red: Warning
2	Axis	Setting	Sets the axis number. (Setting range: 1 to 32)
3	FB	Setting	Sets the teaching type. The button lights yellow when the present position feedback value is set. The button will be gray when the target position is set.
4	Address	Setting	Sets the teaching address.
5	Specified position data	Display	Displays the specified position data.
6	Condition setting	Setting	Sets the teaching axis and reads the teaching axis address.
7	Teaching execution	Setting	Executes teaching.

Remarks

- * There are four different version of this SMART Active Part depending on the following user-set area alStorage directorys.
 - User-set memory area in CIO area and user-set data area in DM Area
 - User-set memory area in CIO area and user-set data area in EM0 Area
 - User-set memory area in Work area and user-set data area in DM Area
 - User-set memory area in Work area and user-set data area in EM0 Area
- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics**, **Data/Time**, and **Address Index** for the \$SW. This SMART Active Part cannot be used on pop-up screens.
- * When using this SMART Active Part, be sure to select **Setting Unit/Scale Setting** in the menu bar and set the scale for number 1000 to 0.0001.
- * Do not use this SMART Active Part on the initial screen.
- * Use system version 5 or higher.
- * When reusing SMART Active Parts, be sure to set the unit number.
- * Number of frames: 2
- * Data is saved in the following areas:

1.4.5 l	1.4.5 Present Value Monitoring							
Unit ty	rpe CS1W-MCH71		rage ctory	SmartActiveParts_E\Mot ion\MCH	Title	Present Value Monitor		
Functi	on Displays the prese	Displays the present value of the specified monitor item.						
Display	and Operation Details							
1 _	1 Axis 1 Pre.pos(current coord.FB) V mm 2 3 4							
No.	ltem	Setting/ display		Des	cription			
1	Axis	Setting	Sets th	ne axis number. (Setting ran	ge: 1 to 32)			
2	Monitor type	Setting	Sets the type of present value to monitor. The settings are as follows: Present coordinate system FB present position, Present coordinate system command present position, Machine coordinate system FB present position, Machine coordinate system command present position, counter latch position, FB speed, Command speed, Position error, Torque command value, Workpiece origin shift value, Origin margin, Number of multi-turns (absolute), Initial increment (absolute), Unit cycle, or Communications cycle					
3	Present value	Display		ys the present value of the s	pecified mon	itor item.		
4	Unit	Display	Displa	ys the unit.				

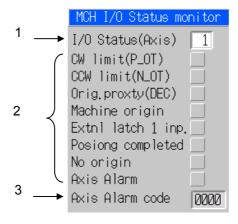
Remarks

- When using this SMART Active Part, be sure to select Setting System Settings in the menu bar, press the System Memory List Button on the Initial Tab Page, and select Basics and Data/Time for the \$SB. This SMART Active Part cannot be used on pop-up screens.
- When using this SMART Active Part, be sure to select Setting Unit/Scale Setting in the menu bar and set the scale for number 1000 to 0.0001.
- Do not use this SMART Active Part on the initial screen.
- Use system version 5 or higher.
- When reusing SMART Active Parts, be sure to set the unit number.
- Number of frames: 2
- Data is saved in the following areas:

1.4.6 I/O Status Monitoring

Unit type	CS1W-MCH71	Storage directory	SmartActiveParts_E\Motio n\MCH	Title	I/O Status Monitor		
Function	Displays the I/O status and error codes for each axis.						

Display and Operation Details



No.	Item	Setting/ display	Description		
1	Axis	Setting	Sets the axis number. (Setting range: 1 to 32)		
2	2 I/O Status Display		Displays the I/O status. The display will be lit yellow for any status signals that are ON.		
3	Error code	Display	Displays any error codes that have been generated.		

Remarks

* There are four different version of this SMART Active Part depending on the following user-set area alStorage directorys.

User-set memory area in CIO area and user-set data area in DM Area

User-set memory area in CIO area and user-set data area in EM0 Area

User-set memory area in Work area and user-set data area in DM Area

User-set memory area in Work area and user-set data area in EM0 Area

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics**, **Data/Time**, and **Address Index** for the \$SW. This SMART Active Part cannot be used on pop-up screens.
- * Do not use this SMART Active Part on the initial screen.
- * Use system version 5 or higher.
- * When reusing SMART Active Parts, be sure to set the unit number.
- * Number of frames: 1
- * Data is saved in the following areas:

User-set memory area in CIO Area and User-set data area in DM Area: MemoryCIO DataDM

User-set memory area in CIO Area and User-set data area in EM0 Area: MemoryCIO DataEM0

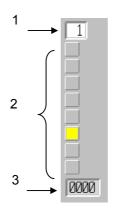
User-set memory area in Work Area and User-set data area in DM Area: MemoryWR_DataDM

User-set memory area in Work Area and User-set data area in EM0 Area: MemoryWR_DataEM0

1.4.7 I/O Status Monitoring (No name)

Unit type	CS1W-MCH71	Storage directory	SmartActiveParts_E\Motio n\MCH	Title	I/O Status Monitor (No Name)
Function	Displays the I/O status ar				

Display and Operation Details



No.	Item	Setting/ display	Description
1	Axis	Setting	Sets the axis number. (Setting range: 1 to 32)
2	I/O Status	Display	Displays the I/O status. The display will be lit yellow for any status signals that are ON. The order of the status is the same as that for 2.10.6 I/O Status.
3	Error code	Display	Displays any error codes that have been generated.

Remarks

- When using this SMART Active Part, be sure to select Setting System Settings in the menu bar, press the System Memory List Button on the Initial Tab Page, and select Basics, Data/Time, and Address Index for the \$SW. This SMART Active Part cannot be used on pop-up screens.
- Do not use this SMART Active Part on the initial screen.
- Use system version 5 or higher.
- There are four different version of this SMART Active Part depending on the following user-set area alStorage directorys.

User-set memory area in CIO area and user-set data area in DM Area User-set memory area in CIO area and user-set data area in EM0 Area

User-set memory area in Work area and user-set data area in DM Area

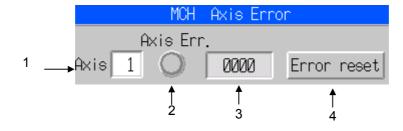
User-set memory area in Work area and user-set data area in EMO Area

- When reusing SMART Active Parts, be sure to set the unit number.
- Number of frames: 1
- Data is saved in the following areas:

1.4.8 Axis Error

Unit type	CS1W-MCH71	Storage directory	SmartActiveParts_E\Motio n\MCH	Title	Axis Error	
Function	Displays and resets axis errors.					

Display and Operation Details



No.	Item	Setting/ display	Description
1	Axis	Setting	Sets the axis number. (Setting range: 1 to 32)
2	Axis error	Display	Lights yellow when an axis error has occurred.
3	Error code	Display	Displays any error codes that have been generated.
4	Error reset	Setting	Resets the axis error.

Remarks

- * When using this SMART Active Part, be sure to select Setting System Settings in the menu bar, press the System Memory List Button on the Initial Tab Page, and select Basics, Data/Time, and Address Index for the \$SW. This SMART Active Part cannot be used on pop-up screens.
- * Do not use this SMART Active Part on the initial screen.
- * There are four different version of this SMART Active Part depending on the following user-set area alStorage directorys.

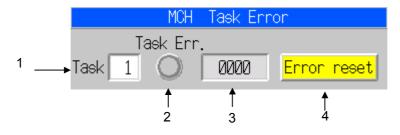
User-set memory area in CIO area and user-set data area in DM Area User-set memory area in CIO area and user-set data area in EM0 Area User-set memory area in Work area and user-set data area in DM Area User-set memory area in Work area and user-set data area in EM0 Area

- * When reusing SMART Active Parts, be sure to set the unit number.
- * Data is saved in the following areas:

1.4.9 Task Error

Unit type	CS1W-MCH71	Storage directory	SmartActiveParts_E\Motio n\MCH	Title	Task Error	
Function	Displays and resets task errors.					

Display and Operation Details



No.	Item	Setting/ display	Description
1	Task	Setting	Sets the task number. (Setting range: 1 to 8)
2	Task error	Display	Lights yellow when a task error has occurred.
3	Error code	Display	Displays any task error codes that have been generated.
4	Error rset	Setting	Resets the error.

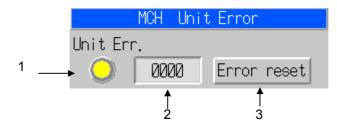
Remarks

- * When using this SMART Active Part, be sure to select Setting System Settings in the menu bar, press the System Memory List Button on the Initial Tab Page, and select Basics for the \$SB. This SMART Active Part cannot be used on pop-up screens.
- * Do not use this SMART Active Part on the initial screen.
- * Use system version 5 or higher.
- * When reusing SMART Active Parts, be sure to set the unit number.
- Number of frames: 1
- * Data is saved in the following areas:

1.4.10 Unit Error

Unit type	CS1W-MCH71	Storage directory	SmartActiveParts_E\Motio n\MCH	Title	Unit Error	
Function	Displays and resets Unit errors.					

Display and Operation Details



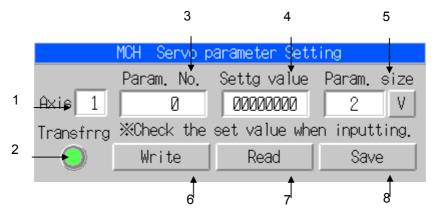
No.	Item	Setting/ display	Description
1	Unit error	Display	Lights yellow when a Unit error has occurred.
2	Error code	Display	Displays any Unit error codes that have been generated.
3	Error reset	Setting	Resets the error.

- * When reusing SMART Active Parts, be sure to set the unit number.
- * Data is saved in the following areas:
 User-set memory area in CIO Area and User-set data area in DM Area: MemoryCIO_DataDM
 User-set memory area in CIO Area and User-set data area in EM0 Area: MemoryCIO_DataEM0
 User-set memory area in Work Area and User-set data area in DM Area: MemoryWR_DataDM
 User-set memory area in Work Area and User-set data area in EM0 Area: MemoryWR_DataEM0

1.4.11 Servo Parameter Setting

Unit type	CS1W-MCH71	Storage directory	SmartActiveParts_E\Moti on\MCH	Title	Servo Parameter Setting	
Function	Sets and displays servo parameters.					

Display and Operation Details



No.	Item	Setting/ display	Description
1	Axis	Setting	Sets the axis number. The setting ranges are as follows: (Setting range: 1 to 32)
2	Transferring	Display	Lights yellow when servo parameters are being transferred.
3	Parameter No.	Setting	Sets the parameter number.
4	Setting value	Setting/ display	Specify the data to write to the servo drive.
5	Parameter size	Setting	Sets the parameter size. 2 or 4
6	Write	Setting	Writes the setting to control memory in the servo drive.
7	Read	Setting	Reads the servo parameter.
8	Save	Setting	Saves the servo parameter to nonvolatile memory in the servo drive.

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** and **Data/Time** for the \$SB. This SMART Active Part cannot be used on pop-up screens.
- * Do not use this SMART Active Part on the initial screen.
- * Use system version 5 or higher.
- * When reusing SMART Active Parts, be sure to set the unit number.
- * Data is saved in the following areas:
 User-set memory area in CIO Area and User-set data area in DM Area: MemoryCIO_DataDM
 User-set memory area in CIO Area and User-set data area in EM0 Area: MemoryCIO_DataEM0
 User-set memory area in Work Area and User-set data area in DM Area: MemoryWR_DataDM
 User-set memory area in Work Area and User-set data area in EM0 Area: MemoryWR_DataEM0

1.4.12 Program Operation Status

Unit type	CS1W-MCH71	Storage directory	SmartActiveParts_E\Motio n\MCH	Title	Program Operation Status		
Function	Displays motion task status during operation.						

Display and Operation Details



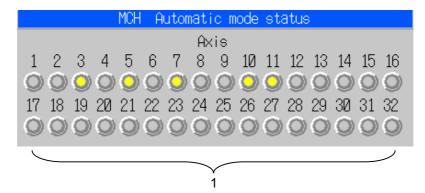
No.	Item	Setting/ display	Description
1	Motion task	Display	Lights yellow during motion task operation.

- * When reusing SMART Active Parts, be sure to set the unit number.
- * Data is saved in the following areas:
 User-set memory area in CIO Area and User-set data area in DM Area: MemoryCIO_DataDM
 User-set memory area in CIO Area and User-set data area in EM0 Area: MemoryCIO_DataEM0
 User-set memory area in Work Area and User-set data area in DM Area: MemoryWR_DataDM
 User-set memory area in Work Area and User-set data area in EM0 Area: MemoryWR_DataEM0

1.4.13 Automatic Mode Status

Unit type	CS1W-MCH71	Storage directory	SmartActiveParts_E\Moti on\MCH	Title	Automatic Mode Status		
Function	Displays the operating m	Displays the operating mode for each axis, automatic or manual.					

Display and Operation Details



No.	Item	Setting/ display	Description
1	Axis	Display	Lights yellow if the axis is in automatic mode.

Remarks

- * When using this SMART Active Part, be sure to select Setting System Settings in the menu bar, press the System Memory List Button on the Initial Tab Page, and select Basics, Data/Time, and Address Index for the \$SW. This SMART Active Part cannot be used on pop-up screens.
- * Do not use this SMART Active Part on the initial screen.
- * There are two different version of this SMART Active Part, one for a CIO Area user-set memory area and one for a Work Area user-set memory area.
- * When reusing SMART Active Parts, be sure to set the unit number.
- * Data is saved in the following areas:

1.5 CS1W/CJ1W-NC413/433/213/233 (from Ver5 or Earlier)

Smart Active Parts described in this section

Mart Active Parts described in this section can be used only when beginning word of the operating data area destination is determined (fixed) by the unit number.

E.g. Case that the unit number is two. The operating data area is fixed from m + 116 to m + 187. Set 0000 for operating data area (m) to fix the beginning word. m=D2000+100xunit number

Motion Control

1.5.1 NC4[]3 (Smart Active Parts Ver 5 or Earlier)

Model	CS1W- NC413/433 CJ1W- NC413/433	Storage directory	SmartActivePa otion\Ver5orEa _1\NC413,433	arlier\NC	Title	JOG Opera	tion (4)		
Function	Displays I/O status, p CCW and sets overrid	resent position	on, error code fo ontrol flag (Enal	or each ax ble button)	kis. Also s is ON	witches betw	een RUN an	nd STOP, CW	and
[Image]									
	JOG Operati	on	NC Unit	Operatio	on				
	Position		Err	ErCode	г I/0) Х	Y Z U		
1 _	5632102	2 pls 9T	OP O	0	Sequer	nce <u>0</u>		<u>4</u>	
2 -	V 600000	7 - 1 - OT	10D	E0.40	CW Lir				
3 -	Y 60000	Tbia 21	OP /	5040	CCW L Origin				
	Z 35000	pls ST	OP OP	0	0. Inpo	ut 🔣 🛛			
	U 95000	pls ST	OP OP	0	Emer.S	Stop 🔳 🛭	##		
5 _	Enable Enable				Err. R				
6 -	X Axis Busy	CCW 0	verride	Z Axis Busy I		CCW	Override		
7 –	RUN	CW F	500 %		STOP	CW	D 80	[%	
8 -	Y Axis Busy	CCW 0	verride	∐ Axis Busy	OTOD	CCW	Override		
	STOP	CW	250 %		STOP	CW	D 800	[%	
9 –									

No.	Item	Setting/ Display	Details	
1	Present Position (Position)	Display	Displays present position for each axis to be controlled by NC unit. (-2,147,483,647 to 2,147,483,647)	
2	STOP	Setting	Stops axis in a set time.	
3	Error (Err)	Display	Lights lamps when an error has been occurred and displays error codes.	
4	I/O Status (I/O)	Display	Displays I/O status.	
5	Enable	Setting	Controls inputs, such as operation, read, override, and position numbers.	
6	RUN/STOP	Setting	Switches between RUN and STOP (0: STOP, 1: RUN).	
7	Busy	Display	Display whether NC unit processes operations or not. Also lights lamp for X axis when initializing unit.	
8	CW/CCW	Setting	Specifies rotative direction (0: CW, 1: CCW).	
9	Override	Setting	Sets values for override and switches between enable and disable.	

[Note]
Those parts can be used for 4 axes unit only. They cannot be used for 1 axis or 2 axes.

1.5.2 Teaching

N	lodel	CS1W-NC413/433 CJ1W-NC413/433	Storage directory	SmartActiveParts_E\M otion\Ver5orEarlier\NC _1\NC413,433	Title	Teach (4)		
Fu	nction	Displays I/O status, present position, error code for each axis. Also sets sequence No. and performs teaching when the control flag(Enable button) is ON						
ſlm	agel							

NC Unit Operation TEACH Err ErCode 1/0 8520 pls **≱TOP** 5040 1 Seguence CW Limit 2 53612 pls CCW Limit Ø 3 OriginProx 86523 pls STOP Ζ 0 0. Input I. Input 691570 pls STOP 0 EmerStop PCompleted Err.Reset 5 Enable 6 Z Axis Axis Position Numbers Seque. Position Seque. Busy Busy Numbers 5 5600 TEACH 46 25700 TEACH Position Numbers 8 Position Numbers Seque. pls Seque. pls Busy 50 53612 TEACH 8 964130 TEACH

No.	Item	Setting/ Display	Details
1	Present Position (Position)	Display	Displays present position for each axis to be controlled by NC unit. (-2,147,483,647 to 2,147,483,647)
2	STOP	Setting	Stops axis in a set time.
3	Error (Err)	Display	Lights lamps when an error has been occurred and displays error codes.
4	I/O Status (I/O)	Display	Displays I/O status.
5	Enable	Setting	Controls inputs, such as operation, read, override, and position numbers.
6	Position Numbers	Setting	Sets position numbers and displays position of sequence No.
7	Busy	Display	Display whether NC unit processes operations or not. Also lights lamp for X axis when initializing unit.
8	TEACH	Setting	Sets present position for position numbers.

[Note]

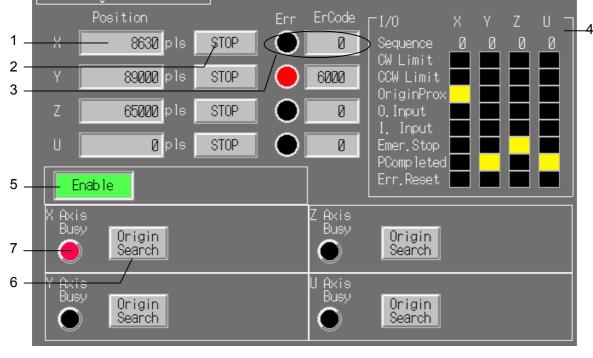
Select **Settings-System Setting-Initial** tab page in the NS-Designer, click System Memory List button, and check the Basics for the \$SB before using this library.

Do NOT use as an initial screen.

Those parts can be used for 4 axes unit only. They cannot be used for 1 axis or 2 axes.

1.5.3 Origin Search

1.5.5	1.5.3 Origin Search						
Mod	el	CS1W-NC413/433 CJ1W-NC413/433	Storage directory	SmartActiveParts_E\M otion\Ver5orEarlier\NC _1\NC413,433	Title	Origin Search	
Funct	Displays I/O status, present position, error code for each axis. Also enables origin search operation when control flag(Enable button) is ON						
[lmage	:]						
		Origin Search		NC Unit Operation			
		Position		Err ErCode 🖂	0	X Y Z U ¬ ,	
1 –	X		STOP	Se	quence Limit		
2 - 3 -	Y	89000 pla	STOP	6000 00	W Limit iginProx		
	Z	65 000 pla	STOP		Input Input		



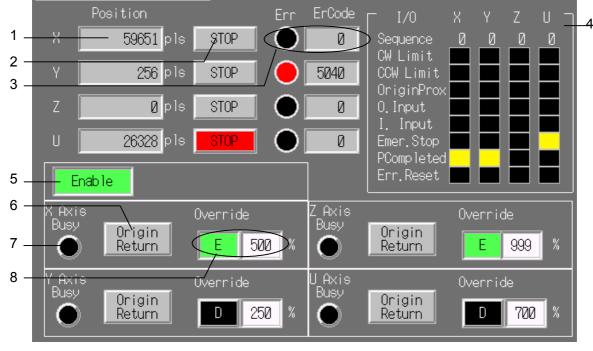
No.	Item	Setting/ Display	Details	
1	Present Position (Position)	Display	Displays present position for each axis to be controlled by NC unit. (-2,147,483,647 to 2,147,483,647)	
2	STOP	Setting	Stops axis in a set time.	
3	Error (Err)	Display	Lights lamps when an error has been occurred and displays error codes.	
4	I/O Status (I/O)	Display	Displays I/O status.	
5	Enable	Setting	Controls inputs, such as operation, read, override, and position numbers.	
6	Origin Search	Setting	Starts origin search operation when it is pressed.	
7	Busy	Display	Display whether NC unit processes operations or not. Also lights lamp for X axis when initializing unit.	

[Note]

Those parts can be used for 4 axes unit only. They cannot be used for 1 axis or 2 axes.

1.5.4 Origin Return

Model	CS1W-NC413/433 CJ1W-NC413/433	Storage directory	SmartActiveParts_E\M otion\Ver5orEarlier\NC _1\NC413,433	Title	Origin Return (4)			
Function	Displays I/O status, present position, error code for each axis. Also enables origin search operation and sets override when the control flag (Enable button) is ON.							
[lmage]								
	Origin Return NC Unit Operation							
	Position		Err ErCode —	I/0	X Y Z U ¬ 4			
1 X	59651 pla	STOP		quence Limit				
2 — Y	256 pla	STOP	5040 cc	W Limit				
Z	Ø pls	STOP		iginProx Input				



No.	Item	Setting/ Display	Details
1	Present Position (Position)	Display	Displays present position for each axis to be controlled by NC unit. (-2,147,483,647 to 2,147,483,647)
2	STOP	Setting	Stops axis in a set time.
3	Error (Err)	Display	Lights lamps when an error has been occurred and displays error codes.
4	I/O Status (I/O)	Display	Displays I/O status.
5	Enable	Setting	Controls inputs, such as operation, read, override, and position numbers.
6	Origin Return	Setting	Axis returns from any position to the origin.
7	Busy	Display	Display whether NC unit processes operations or not. Also lights lamp for X axis when initializing unit.
8	Override	Setting	Sets values for override and switches between enable and disable.

[Note]
Those parts can be used for 4 axes unit only. They cannot be used for 1 axis or 2 axes.

Motion Control

1.5.5 Changing Preset Value

Mode	CS1W-NC413/433 CJ1W-NC413/433	Storage directory		Title	Changing Present Value (4)			
Function	Displays I/O status (Enable button) is 0		tion, error code for each ax	is. Also pres	sets position numbers when the control fla			
[Image]								
	Changing Presen	t Value	NC Unit Operati	ion				
	Positio	 n	Err ErCode	г I/0	X Y Z U ¬ ,			
				a '''	 4			
	n J	860 pls	9TOP 5040	Sequen CW Lim				
	2 V 560	180 pls :	STOP Ø] CCW Li				
	3	100 210		Origin				
	Z 869	920 pls 📑	STOP 0	0. Inpu				
				I. Inp				
	U 90	650 pls :	STOP 0	Emer.S	Stop 🔳 🔳 📗			
				" PCompl				
	5 Enable			Err.Re	set 🔛 🔛 🔛 📗			
	LIN LIVIS	osition √umbers	pls Z Axis Busy		sition mbers pls			
	7 — 🕒	5860	Preset	200	MMMMM Preset			
	8 Y Axis P	osition	Dls U Axis	Pos	sition plo			
		Numbers	pls UHXIS		mbers pls			
		563320	Preset		9650 Preset			
		000025						
No.	Item	Setting/ Display		D	etails			
1	Present Position (Position)		Displays present position for each axis to be controlled by NC unit. (-2,147,483,647 to 2,147,483,647)					
2	STOP	Setting	Stops axis in a set time.					
3	Error (Err)		Lights lamps when an error has been occurred and displays error codes.					
4	I/O Status (I/O)		Displays I/O status.					
5	Enable	-	•		d, override, and position numbers.			
		1 0 110 1	Sets position numbers to preset.					
6	Position Numbers		Display whether NC unit processes operations or not. Also lights lamp for X axis					
	Position Numbers Busy	Display I	Display whether NC unit prowhen initializing unit.	ocesses ope	erations or not. Also lights lamp for X axis			

[Note]
Those parts can be used for 4 axes unit only. They cannot be used for 1 axis or 2 axes.

1.5.6 Direct Operation

data when the							
data when the							
1							
Direct Operation NC Unit Operation Position Err ErCode - 1/0 x y z 11 - 1							
Position							
- 1 1							
10							
9							
8							
-							
- 7 1 3							
(R).							
Display whether NC unit processes operations or not. Also lights lamp for X axis							
mp for X axi							
amp for X axi							

Sets acceleration time for each axis.

Sets deceleration time for each axis.

11 [Note]

10

Acceleration Time (A. Time)

Deceleration Time

(D.Time)

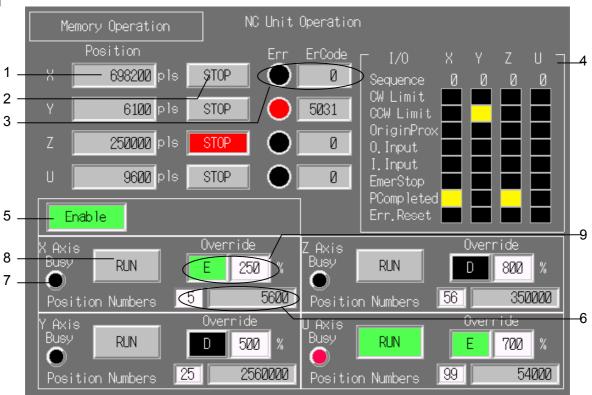
[Note]
Those parts can be used for 4 axes unit only. They cannot be used for 1 axis or 2 axes.

Setting

Setting

1.5.7 Memory Operation(4)

Model	CS1W-NC413/433 CJ1W-NC413/433	Storage directory	DV\NC_V1\ NC413,433	Title	Memory Operation (4)	
Function	Displays I/O status, present position, error code for each axis. Also sets override and sequence No. and starts operation with the set conditions by pressing RUN button when the control flag (Enable button) is ON.					
[Image]	Memory Opera	tion	NC Unit Operatio	'n		



No.	Item	Setting/ Display	Details	
1	Present Position (Position)	Display	Displays present position for each axis to be controlled by NC unit. (-2,147,483,647 to 2,147,483,647)	
2	STOP	Setting	Stops axis in a set time.	
3	Error (Err)	Display	Lights lamps when an error has been occurred and displays error codes.	
4	I/O Status (I/O)	Display	Displays I/O status.	
5	Enable	Setting	Controls inputs, such as operation, read, override, and position numbers.	
6	Position Numbers	Setting		
7	Busy	Display	Display whether NC unit processes operations or not. Also lights lamp for X axis when initializing unit.	
8	RUN	Setting	Starts memory operation when it is pressed.	
9	Override	Setting	Sets values for override and switches between enable and disable.	

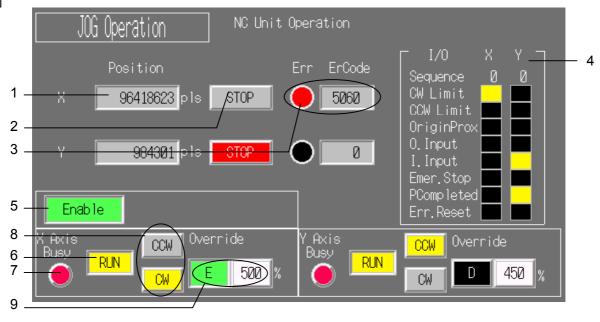
[Note]

- 1. Select **Settings-System Setting-Initial** tab page in the NS-Designer, click **System Memory List** button, and check the **Basics** for the \$SB before using this library.
- 2. Do NOT use as an initial screen.
- 3. Those parts can be used for 4 axes unit only. They cannot be used for 1 axis or 2 axes.

1.5.8 JOG Operation(2)

Model	CS1W-NC213/233 CJ1W-NC213/233	Storage directory	DV\NC_V1\ NC213,233	Title	JOG Operation (2)	
Function	Displays I/O status, present position, error code for each axis. Also switches between RUN and STOP, CW and CCW and sets override when the control flag(Enable button) is ON					

[Image]



No.	Item	Setting/ Display	Details
1	Present Position (Position)	Display	Displays present position for each axis to be controlled by NC unit. (-2,147,483,647 to 2,147,483,647)
2	STOP	Setting	Stops axis in a set time.
3	Error (Err)	Display	Lights lamps when an error has been occurred and displays error codes.
4	I/O Status (I/O)	Display	Displays I/O status.
5	Enable	Setting	Controls inputs, such as operation, read, override, and position numbers.
6	RUN/STOP	Setting	Switches between RUN and STOP (0: STOP, 1: RUN).
7	Busy	Display	Display whether NC unit processes operations or not. Also lights lamp for X axis when initializing unit.
8	CW/CCW	Setting	Specifies rotative direction (0: CW, 1: CCW).

[Note]

Those parts can be used for 2 axes unit only. They cannot be used for 1 axis or 4 axes.

Motion Control

1.5.9 Teach

Model	CS1W-NC213/233 CJ1W-NC213/233	Storage directory	DV\NC_V1\ NC213,233	Title	Teach (2)	
Function	Displays I/O status, present position, error code for each axis. Also sets sequence No. and performs teaching when the control flag(Enable button) is ON					
[Image]						

NC Unit Operation **TEACH** 1/0 - 4 ErCode CW Limit 1 863000 pls STOP CCW Limit 2 0. Input 3 6000 I. Input EmerStop PCompleted 5 Enable Err.Reset 6 Position Numbers /Axis Busy Position Numbers Seque. pls 236200 TĘACH 99 2369500 TEACH 7 8

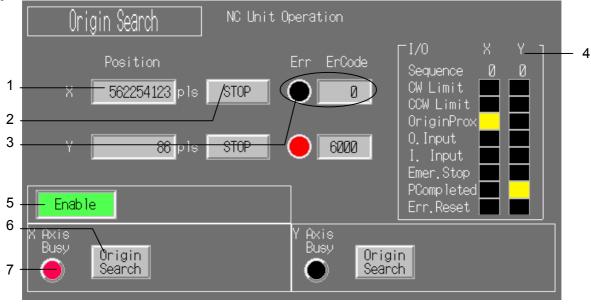
No.	Item	Setting/ Display	Details
1	Present Position (Position)	Display	Displays present position for each axis to be controlled by NC unit. (-2,147,483,647 to 2,147,483,647)
2	STOP	Setting	Stops axis in a set time.
3	Error (Err)	Display	Lights lamps when an error has been occurred and displays error codes.
4	I/O Status (I/O)	Display	Displays I/O status.
5	Enable	Setting	Controls inputs, such as operation, read, override, and position numbers.
6	Position Numbers	Setting	
7	Busy	Display	Display whether NC unit processes operations or not. Also lights lamp for X axis when initializing unit.
8	TEACH	Setting	Sets present position for position numbers.

[Note]

- 1. Select **Settings-System Setting-Initial** tab page in the NS-Designer, click **System Memory List** button, and check the **Basics** for the \$SB before using this library.
- 2. Do NOT use as an initial screen.
- 3. Those parts can be used for 2 axes unit only. They cannot be used for 1 axis or 4 axes.

1.5.10 Origin Search

Model	CS1W-NC213/233 CJ1W-NC213/233	Storage directory	DV\NC_V1\ NC213,233	Title	Origin Search (2)		
Function	Displays I/O status, present position, error code for each axis. Also enables origin search operation when the control flag (Enable button) is ON						
[Image]							



No.	Item	Setting/ Display	Details
1	Present Position (Position)	Display	Displays present position for each axis to be controlled by NC unit. (-2,147,483,647 to 2,147,483,647)
2	STOP	Setting	Stops axis in a set time.
3	Error (Err)	Display	Lights lamps when an error has been occurred and displays error codes.
4	I/O Status (I/O)	Display	Displays I/O status.
5	Enable	Setting	Controls inputs, such as operation, read, override, and position numbers.
6	Origin Search	Setting	Starts origin search operation when it is pressed.
7	Busy	Display	Display whether NC unit processes operations or not. Also lights lamp for X axis when initializing unit.

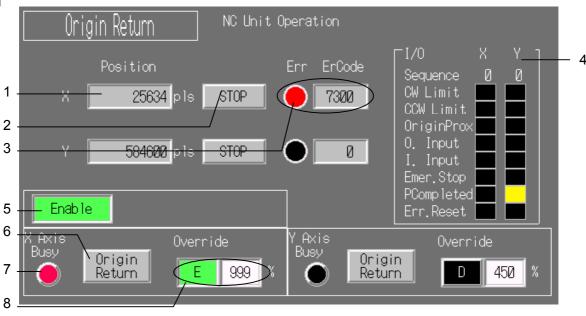
[Note

Those parts can be used for 2 axes unit only. They cannot be used for 1 axis or 4 axes.

1.5.11 Origin Return(2)

Model	CS1W-NC213/233 CJ1W-NC213/233	Storage directory	DV\NC_V1\ NC213,233	Title	Origin Return (2)		
Function	Displays I/O status, present position, error code for each axis. Also enables origin search operation and sets override when the control flag (Enable button) is ON.						

[Image]



No.	ltem	Setting/ Display	Details
1	Present Position (Position)	Display	Displays present position for each axis to be controlled by NC unit. (-2,147,483,647 to 2,147,483,647)
2	STOP	Setting	Stops axis in a set time.
3	Error (Err)	Display	Lights lamps when an error has been occurred and displays error codes.
4	I/O Status (I/O)	Display	Displays I/O status.
5	Enable	Setting	Controls inputs, such as operation, read, override, and position numbers.
6	Origin Return	Setting	Axis returns from any position to the origin.
7	Busy	Display	Display whether NC unit processes operations or not. Also lights lamp for X axis when initializing unit.
8	Override	Setting	Sets values for override and switches between enable and disable.

[Note]

Those parts can be used for 2 axes unit only. They cannot be used for 1 axis or 4 axes.

1.5.12 Changing Present Value

Model	CS1W-NC213/233 CJ1W-NC213/233	Storage directory	DV\NC_V1\ NC213,233	Title	Changing Present Value (2)				
Function		Displays I/O status, present position, error code for each axis. Also presets position numbers when the control flag (Enable button) is ON.							
[Image]	Changing Present Positio		NC Unit Operation Err ErCoo	de [I/O X Y_7 4 Sequence Ø Ø				
1 - 2 - 3 -		251 pls 500 pls	/STOP 0		CW Limit				
5 - 6 -	Enable Enable			E	Completed Err. Reset Est				
7 -	X Hxis Position Busy 256		Pls Y Axis p Busy Yreset (Position 898	Pls 500 Preset				

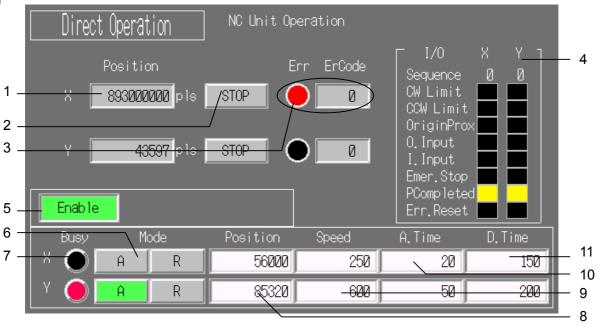
No.	Item	Setting/ Display	Details
1	Present Position (Position)	Display	Displays present position for each axis to be controlled by NC unit. (-2,147,483,647 to 2,147,483,647)
2	STOP	Setting	Stops axis in a set time.
3	Error (Err)	Display	Lights lamps when an error has been occurred and displays error codes.
4	I/O Status (I/O)	Display	Displays I/O status.
5	Enable	Setting	Controls inputs, such as operation, read, override, and position numbers.
6	Position Numbers	Setting	Sets position numbers to preset.
7	Busy	Display	Display whether NC unit processes operations or not. Also lights lamp for X axis when initializing unit.
8	Preset	Setting	Changes position form present position to position numbers forcibly.

[Note]
Those parts can be used for 2 axes unit only. They cannot be used for 1 axis or 4 axes.

Motion Control

1.5.13 Direct Operation

Model	CS1W-NC213/233 CJ1W-NC213/233	Storage directory	DV\NC_V1\ NC213,233	Title	Direct Operation (2)		
Function	Displays I/O status, present position, error code for each axis. Also sets operation mode and other data when the control flag (Enable button) is ON.						
[Image]							
	Nimed Operat	ion	NC Unit Operation				



No.	ltem	Setting/ Display	Details
1	Present Position (Position)	Display	Displays present position for each axis to be controlled by NC unit. (-2,147,483,647 to 2,147,483,647)
2	STOP	Setting	Stops axis in a set time.
3	Error (Err)	Display	Lights lamps when an error has been occurred and displays error codes.
4	I/O Status (I/O)	Display	Displays I/O status.
5	Enable	Setting	Controls inputs, such as operation, read, override, and position numbers.
6	Operation Mode (Mode)	Setting	Switches movement for operation data area between Absolute (A) and Relative (R).
7	Busy	Display	Display whether NC unit processes operations or not. Also lights lamp for X axis when initializing unit.
8	Position	Setting	Sets target position for each axis.
9	Speed	Setting	Sets target speed for each axis.
10	Acceleration Time (A. Time)	Setting	Sets acceleration time for each axis.
11	Deceleration Time (D.Time)	Setting	Sets deceleration time for each axis.

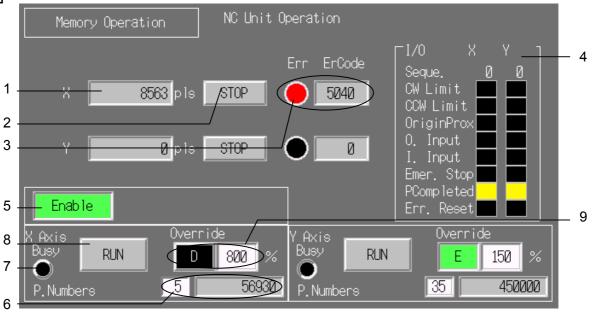
[Note]

- 1. Select **Settings-System Setting-Initial** tab page in the NS-Designer, click **System Memory List** button, and check the **Basics** for the \$SB before using this library.
- 2. Do NOT use as an initial screen.
- 3. Those parts can be used for 2 axes unit only. They cannot be used for 1 axis or 4 axes.

1.5.14 Memory Operation(2)

Ī	Model	CS1W-NC213/233 CJ1W-NC213/233	Storage directory	DV\NC_V1\ NC213,233	Title	Memory Operation (2)
	Function	Displays I/O status, present position, error code for each axis. Also sets override and sequence No. and state operation with the set conditions by pressing RUN button when the control flag (Enable button) is ON.				

[Image]



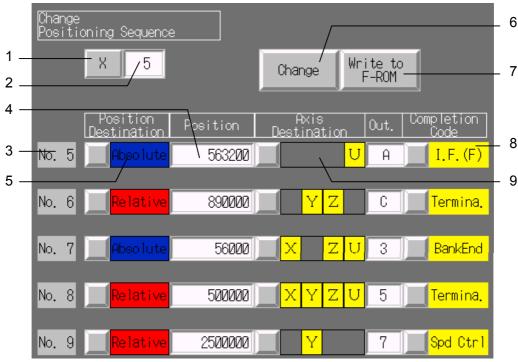
No.	Item	Setting/ Display	Details
1	Present Position (Position)	Display	Displays present position for each axis to be controlled by NC unit. (-2,147,483,647 to 2,147,483,647)
2	STOP	Setting	Stops axis in a set time.
3	Error (Err)	Display	Lights lamps when an error has been occurred and displays error codes.
4	I/O Status (I/O)	Display	Displays I/O status.
5	Enable	Setting	Controls inputs, such as operation, read, override, and position numbers.
6	Position Numbers	Setting	Sets position numbers and displays position of sequence No.
7	Busy	Display	Display whether NC unit processes operations or not. Also lights lamp for X axis when initializing unit.
8	RUN	Setting	Starts memory operation when it is pressed.
9	Override	Setting	Sets values for override and switches between enable and disable.

[Note

- 1. Select **Settings-System Setting-Initial** tab page in the NS-Designer, click **System Memory List** button, and check the **Basics** for the \$SB before using this library.
- 2. Do NOT use as an initial screen.
- 3. Those parts can be used for 2 axes unit only. They cannot be used for 1 axis or 4 axes.

1.5.15 Change Positioning Sequence(4)

Model	CS1W-NC413/433 CJ1W-NC413/433	Storage directory	DV\NC_V1\ NC413,433	Title	Change Positioning Sequence (4)	
Function	Sets sequence data, such as position destination, axis destination, output (Out.), and completion code, and position.					
[Image] Change Positioning Sequence 6						



No.	ltem	Setting/ Display	Details		
1	Axis	Display	Displays axis which settings should be made.		
2	Sequence No.	Setting	Input the desired sequence No.		
3	Sequence No.	Display	Displays sequence No. to be set.		
4	Position	Setting	Sets the position for the selected axis.		
5	Position Destination	Setting	Sets whether the position is absolute or relative.		
6	Change	Setting	Writes the displayed data to parameter area in the NC Unit.		
7	Write to F-ROM	Display	Saves data written to the parameter area to F-ROM. Make sure to perform this before turning OFF the power.		
8	Completion Code	Setting	Sets completion codes.		
9	Axis Destination	Setting	Specifies axis to be started up.		

[Note]

- 1. Select **Settings-System Setting-Initial** tab page in the NS-Designer, click **System Memory List** button, and check the **Basics** for the \$SB before using this library.
- 2. When changing sequence No., press **Change** button and write it to parameter area. Unless the sequence No. is written to the parameter area, data will NOT be saved.
- 3. Unless F-ROM button is pressed, data will be deleted before turning OFF the power. Data to be saved in the NC Unit by pressing the Write to F-ROM button is data saved in the parameter area of PLC, NOT displaying on the screen.
- 4. Do NOT use as an initial screen.
- 5. Those parts can be used for 4 axes unit only. They cannot be used for 1 axis or 2 axes.

1.5.16 Change Positioning Sequence(2)

Model	CS1W-NC213/233 CJ1W-NC213/233	Storage directory	DV\NC_V1\ NC213,233	Title	Change Position	ning Sequence (2)
Function	Sets sequence data, s	Sets sequence data, such as position destination, axis destination, output, and completion code, and position.				
[Image]						
	Change Positioni	ing Sequenc	e			6
	1	X 89	Change	Write F-R	to 0 M	7
	4 —	Position estination	Position Axis Desti.	Out.	Completion Code	

	Positi	oning Sequence	<u>:</u>				<u></u> б
1 _		- X 89		Change	Write		_
2 _				oriange	F-f	ROM	7
4 —		Position	<u> </u>	Axis	la .	Completion	
		Destination	Position	Desti.	Out.	Code	
3 —	No. 89	Ab/so lute	\ 58 0 00	∐ <mark>X</mark> \	Ĥ	Continu.	8
5 —							_ 9
	No. 90	Relative	10000000	X.	Y E	Auto.	
	No. 91	Relative	250000		Y 4	I.F. (R)	
	No. 92	Abso lute	6800000	X.	<mark>Y</mark> 9	Continu.	
	No. 93	Relative	1500000	X	1	Spd Ctrl	
							I

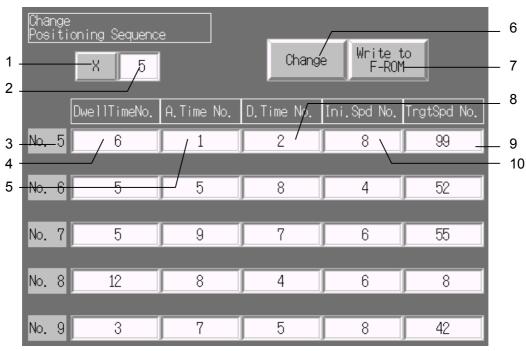
No.	Item	Setting/ Display	Details
1	Axis	Display	Displays axis which settings should be made.
2	Sequence No.	Setting	Input the desired sequence No.
3	Sequence No.	Display	Displays sequence No. to be set.
4	Position	Setting	Sets the position for the selected axis.
5	Position Destination	Setting	Sets whether the position is absolute or relative.
6	Change	Setting	Writes the displayed data to parameter area in the PLC.
7	Write to F-ROM	Display	Saves data written to the parameter area to F-ROM in the NC Unit. (Make sure to perform this before turning OFF the power.)
8	Completion Code	Setting	Sets completion codes.
9	Axis Destination	Setting	Specifies axis to be started up.

[Note]

- 1. Select **Settings-System Setting-Initial** tab page in the NS-Designer, click **System Memory List** button, and check the **Basics** for the \$SB before using this library.
- 2. When changing sequence No., press **Change** button and write it to parameter area. Unless the sequence No. is written to the parameter area, data will NOT be saved.
- 3. Unless F-ROM button is pressed, data will be deleted before turning OFF the power. Data to be saved in the NC Unit by pressing the Write to F-ROM button is data saved in the parameter area of PLC NOT displaying on the screen.
- 4. Do NOT use as an initial screen.
- 5. Those parts can be used for 2 axes unit only. They cannot be used for 1 axis or 4 axes.

1.5.17 Change Positioning Sequence(2axes,4axes)

Model	CS1W- NC413/433/213/233 CJ1W- NC413/433/213/233	Storage directory	DV\NC_V1\ NC413,433/NC213,233	Title	Change Positioning Sequence (2axes, 4axes)	
Function	Sets sequence data, such as dwell time number, acceleration time number, deceleration time number, initial speed number, and target speed number.					
[lmage]						



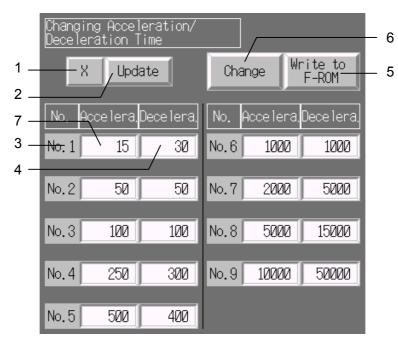
No.	Item	Setting/ Display	Details
1	Axis	Display	Displays axis which settings should be made.
2	Sequence Number	Setting	Input the desired sequence No.
3	Sequence Number	Display	Displays sequence No. to be set.
4	Dwell Time Number (Dwell Time No.	Setting	Sets dwell time number to be selected.
5	Acceleration Time Number (A.Time No.)	Setting	Sets acceleration time number to be selected.
6	Change	Setting	Writes the displayed data to parameter area in the PLC.
7	Write to F-ROM	Setting	Saves data written to the parameter area to F-ROM in the NC Unit. (Make sure to perform this before turning OFF the power.)
8	Deceleration Time Number (D.Time No.)	Setting	Sets deceleration time number to be selected.
9	Target Speed Number (Trgt Spd No.)	Setting	Sets target speed number to be selected.
10	Initial Speed Number (Ini.Spd No.)	Setting	Sets initial speed number to be selected.

- 1. Select Settings-System Setting-Initial tab page in the NS-Designer, click System Memory List button, and check the Basics for the \$SB before using this library.
- 2. When changing sequence No., press Change button and write it to parameter area. Unless the sequence No. is written to the parameter area, data will NOT be saved.
- 3. Unless F-ROM button is pressed, data will be deleted before turning OFF the power. Data to be saved in the NC Unit by pressing the Write to F-ROM button is data saved in the parameter area of PLC NOT displaying on the screen.
- 4. Do NOT use as an initial screen.

1.5.18 Changing Acceleration

Model	CS1W- NC413/433/213/233 CJ1W- NC413/433/213/233	Storage directory	DV\NC_V1\ NC413,433/NC213,233	Title	Changing Acceleration / Deceleration Time
Function	Sets acceleration time and deceleration time for x, Y, Z, and U axis.				

[Image]



No.	Item	Setting/ Display	Details
1	Axis	Display	Displays axis which settings should be made.
2	Sequence Number	Setting	Input the desired sequence No.
3	Sequence Number	Display	Displays sequence No. to be set.
4	Deceleration Time (Decelera.)	Setting	Sets deceleration time.
5	Change	Setting	Writes the displayed data to parameter area in the PLC.
6	Write to F-ROM	Setting	Saves data written to the parameter area to F-ROM in the NC Unit. (Make sure to perform this before turning OFF the power.)
7	Acceleration Time (Accelera.)	Setting	Sets acceleration time.

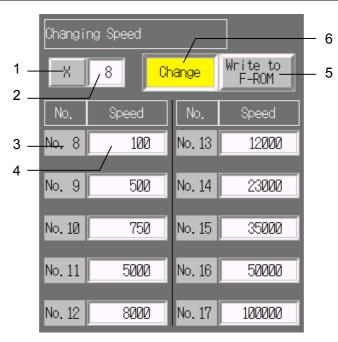
[Note]

- 1. Select **Settings-System Setting-Initial** tab page in the NS-Designer, click **System Memory List** button, and check the **Basics** for the \$SB before using this library.
- 2. When changing sequence No., press **Change** button and write it to parameter area. Unless the sequence No. is written to the parameter area, data will NOT be saved.
- 3. Unless F-ROM button is pressed, data will be deleted before turning OFF the power. Data to be saved in the NC Unit by pressing the Write to F-ROM button is data saved in the parameter area of PLC NOT displaying on the screen.
- 4. Do NOT use as an initial screen.

1.5.19 Changing Speed

Model	CS1W- NC413/433/213/233 CJ1W- NC413/433/213/233	Storage directory	DV\NC_V1\ NC413,433/NC213,233	Title	Changing Speed (2 axes, 4axes)
Function	Sets speed for each axis(X, Y, Z, and U).				

[Image]



No.	Item	Setting/ Display	Details
1	Axis	Display	Displays axis which settings should be made.
2	Sequence Number	Setting	Input the desired sequence No.
3	Sequence Number	Display	Displays sequence No. to be set.
4	Speed	Setting	Sets the desired speed.
5	Write to F-ROM	Setting	Saves data written to the parameter area to F-ROM in the NC Unit. (Make sure to perform this before turning OFF the power.)
6	Change	Setting	Writes the displayed data to parameter area in the PLC.

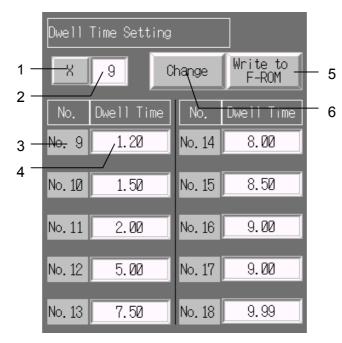
[Note]

- 1. Select **Settings-System Setting-Initial** tab page in the NS-Designer, click **System Memory List** button, and check the **Basics** for the \$SB before using this library.
- 2. When changing sequence No., press **Change** button and write it to parameter area. Unless the sequence No. is written to the parameter area, data will NOT be saved.
- 3. Unless F-ROM button is pressed, data will be deleted before turning OFF the power. Data to be saved in the NC Unit by pressing the Write to F-ROM button is data saved in the parameter area of PLC NOT displaying on the screen.
- 4. Do NOT use as an initial screen.

1.5.20 Dwell Time Setting

Model	CS1W- NC413/433/213/233 CJ1W- NC413/433/213/233	Storage directory	DV\NC_V1\ NC413,433/NC213,233	Title	Dwell Time Setting (2axes, 4axes)
Function	Sets well time for each axis(X, Y, Z, and U).				

[Image]



No.	Item	Setting/ Display	Details
1	Axis	Display	Displays axis which settings should be made.
2	Sequence Number	Setting	Input the desired sequence No.
3	Sequence Number	Display	Displays sequence No. to be set.
4	Dwell Time	Setting	Sets the desired dwell time.
5	Write to F-ROM	Setting	Saves data written to the parameter area to F-ROM in the NC Unit. (Make sure to perform this before turning OFF the power.)
6	Change	Setting	Writes the displayed data to parameter area in the PLC.

[Note]

- 1. Select **Settings-System Setting-Initial** tab page in the NS-Designer, click **System Memory List** button, and check the **Basics** for the \$SB before using this library.
- 2. When changing sequence No., press **Change** button and write it to parameter area. Unless the sequence No. is written to the parameter area, data will NOT be saved.
- 3. Unless F-ROM button is pressed, data will be deleted before turning OFF the power. Data to be saved in the NC Unit by pressing the Write to F-ROM button is data saved in the parameter area of PLC NOT displaying on the screen.
- 4. Do NOT use as an initial screen.

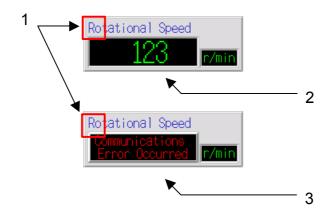


1.1 3G3MV

1.1.1 Speed Monitor

Monitors the speed of the SYSDRIVE 3G3MV-series Multi-function Compact Inverter in serial connection or connected through the 3G3MV-PDRT2 DeviceNet Communications Unit. The monitoring cycle is adjustable in combination with the PLC program.	Unit type	3G3MV(-PDRT2)	Storage directory	SmartActiveParts_E\Invertor\3G3MV\DeviceNet\Monitor	Title	Speed monitor	
- r - 3 -	Function						

Display and Operation Details



No.	Item	Setting/ display	Description
1	Hidden indicator for trigger use	Display	A trigger indicator used to read the speed from the 3G3MV. This indicator is not displayed on the screen. The value can be read on a regular basis by turning ON and OFF the allocated address from the program in the PLC. The monitor cycle is determined by the program in the PLC. Adjust the cycle according to the communications load.
2	Rotational Speed	Display	Displays the speed read from the 3G3MV.
3	Communications error display	Setting/ display	Displays the status of an error if a communications error occurs between the Unit and the 3G3MV. Reading is not performed while this item is displayed. If the recovery of communications is expected, press the displayed part so that reading will be restarted.

Remarks

When using this Smart Active Part, select the r/min unit with *Parameter n035 (Frequency Reference Settings/Reference Unit Selection)* on the 3G3MV. Specifically, set n035 to 2 through 39 (number of motor poles).

The following diagram shows a programming example on the PLC to monitor the value on a regular basis. The 0.1-second clock pulse is allocated to the specified address (Serial A: WR00511.15).



- * The actual monitor refreshing cycle varies with the number of Smart Active Parts monitored on the screen and the operating conditions of other Smart Active Parts. The refreshing cycle will be increased if the number of Smart Active Parts increases.
- * If the other Smart Active Parts on the screen are in operation, refreshing the monitor will stop. When the operation of the Smart Active Parts stops, refreshing the monitor will restart.
- * Open the property sheet of this Smart Active Parts in the NS-Designer to set the Communication Setting.

1.1.2 Output Frequency Monitor

Unit type	3G3MV(-PDRT2)	Storage directory	SmartActiveParts_E\Inver tor\3G3MV\Serial(Device Net)\Monitor	Title	Output frequency monitor
Function Monitors the output frequency of the SYSDRIVE 3G3MV-series Multi-function Compact Inverter in serial connection or connected through the 3G3MV-PDRT2 DeviceNet Communications Unit. The monitoring cycle is adjustable in combination with the PLC program.					
Display and Operation Details					



No.	Item	Setting/	Description
	1.0	display	2000 Page
1	Hidden indicator for trigger use	Display	A trigger indicator used to read the output frequency from the 3G3MV. This indicator is not displayed on the screen. The value can be read on a regular basis by turning ON and OFF the allocated address from the program in the PLC. The monitor cycle is determined by the program in the PLC. Adjust the cycle according to the communications load.
2	Output Frequency	Display	Displays the output frequency read from the 3G3MV.
3	Communications error display	Setting/ display	Displays the status of an error if a communications error occurs in the 3G3MV. Reading is not performed while this item is displayed. If the recovery of communications is expected, press the displayed part so that reading will be restarted.

Remarks

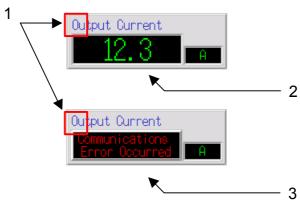
- When using this Smart Active Part, be sure to select Setting Unit/Scale Setting in the menu bar and set the scale for number 999
- When using this Smart Active Part, select the 0.01 Hz unit (default) with Parameter n035 (Frequency Reference Settings/Reference Unit Selection) on the 3G3MV. Specifically, set n035 to 0.
- The following diagram shows a programming example on the PLC to monitor the value on a regular basis. The 0.1-second clock pulse is allocated to the specified address (Serial A: WR00511.15).



- The actual monitor refreshing cycle varies with the number of Smart Active Parts monitored on the screen and the operating conditions of other Smart Active Parts. The refreshing cycle will increase if the number of Smart Active Parts increases.
- If the other Smart Active Parts on the screen are in operation, refreshing the monitor will stop. When the operation of the Smart Active Parts stops, refreshing the monitor will restart.
- * Open the property sheet of this Smart Active Parts in the NS-Designer to set the Communication Setting.

1.1.3 Output Current Monitor

Unit type	3G3MV(-PDRT2)	Storage directory	SmartActiveParts_E\Invertor\3G3MV\Serial(Device Net)\Monitor	Title	Output current monitor						
Function	Monitors the output current of the SYSDRIVE 3G3MV-series Multi-function Compact Inverter in serial connection or connected through the 3G3MV-PDRT2 DeviceNet Communications Unit. The monitoring cycle is adjustable in combination with the PLC program.										
Display and Operation Details											



No.	Item	Setting/ display	Description
1	Hidden indicator for trigger use	Display	A trigger indicator used to read the output current from the 3G3MV. This indicator is not displayed on the screen. The value can be read on a regular basis by turning ON and OFF the allocated address from the program in the PLC. The monitor cycle is determined by the program in the PLC. Adjust the cycle according to the communications load.
2	Output Current	Display	Displays the output current read from the 3G3MV.
3	Communications error display	Setting/ display	Displays the status of an error if a communications error occurs between the Unit and the 3G3MV. Reading is not performed while this item is displayed. If the recovery of communications is expected, press the displayed part so that reading will be restarted.

Remarks

- * When using this Smart Active Part, be sure to select **Setting Unit/Scale Setting** in the menu bar and set the scale for number 1000 to 0.1
- * The following diagram shows a programming example on the PLC to monitor the value on a regular basis. The 0.1-second clock pulse is allocated to the specified address (Serial A: WR00511.15).

1 CF100 W511.15 2 0.1秒クロックハルス

- * The actual monitor refreshing cycle varies with the number of Smart Active Parts monitored on the screen and the operating conditions of other Smart Active Parts. The refreshing cycle will increase if the number of Smart Active Parts increases.
- * If the other Smart Active Parts on the screen are in operation, refreshing the monitor will stop. When the operation of the Smart Active Parts stops, refreshing the monitor will restart.
- * Open the property sheet of this Smart Active Parts in the NS-Designer to set the Communication Setting.

1.1.4 Parameter No. 1 to 12 (Unit: r/min)

Unit ty	pe 3G3MV(-PDRT2)	Storaç		SmartActiveParts_E tor\3G3MV\Serial(De Net)\Parameters		Title	Pá	arameter	No. 1 to	o 12 (un	it: r/min)	
Functi	on through paramet	the 3G3MV ers.	'-PDRT2 De		VE 3G3MV-series Mu Communications Uni								
Display	y and Operati	on Details											
		1	2 		3 	4 ↓	•	5 ↓					
		No.1 to N	lo.12		. (cannot t	oe set du	ring c	peration)				
		No.	Constant		Name	Defau			Unit				
		No.1	n003 F	Run Cor	mmand Selection	0	2	2	-				
		No.2	n004 f	Freq.Re	ference Selection	0	2	2	-				
		No.3	n019 /	Acceler	ation Time 1	10.0	3 0	1.2	s				
		No.4	n020 [Deceler:	ation Time 1	10.0	3 6	1.2	s				
		No.5	n024 F	Rotation	nal Speed 1	0		1	r/min				
		No.6	n025 F	Rotation	nal Speed 2	0		1	r/min				
		No.7	n026	Rotation	nal Speed 3	0		1	r/min				
		No.8	n034 l	_ower F	req. Reference Limit	0		2	%				
		No.9	n017	Min.Out	put Freq.Valtage			1.2	V				
		No.10	n095 f	requen	cy Detection Level	0.00] 0	.02	Hz				
		No.11	n103	Forque (Compensation Gain	1.0	0.	2					
		No.12	n111	Slip Cor	mpensation Gain	0.0	0.	2	-				
					Read	l Valu	e [Wn	ite	•	7		
						^				•			
						6							
						•							
No.	Item		Setting/ display		cription								
1	No.		Display		ays the item numbers								
2	Constant	stant Display Displays the constant numbers where the parameters are saved in the 3G3MV.											

No.	Item	display	Description
1	No.	Display	Displays the item numbers from the parameter table.
2	Constant	Display	Displays the constant numbers where the parameters are saved in the 3G3MV.
3	Name	Display	Displays descriptions of parameters.
4	Default	Display	Displays the default value of each parameter (i.e., the default in the 3G3MV).
5	Set Val.	Setting/ display	Displays the set value of each parameter. By pressing the setting, the set value can be overwritten. Each set item will be saved when the data is written.
6	Read Value	Setting	Reads the present value set for each parameter.
7	Write	Setting	Writes the settings to the EEPROM in the Unit.

- * When using this Smart Active Part, be sure to select **Setting Unit/Scale Setting** in the menu bar and set the scale for number 1000 to 0.1 and the scale for number 999 to 0.01.
- * When using this Smart Active Part, select the r/min unit with *Parameter n035 (Frequency Reference Settings/Reference Unit Selection)* on the 3G3MV. Specifically, set n035 to 2 through 39 (number of motor poles). If a unit other than r/min is selected, values for parameters n024 to n026 will not be displayed normally.
- * Execute EEPROM Write to save the settings so that they will be stored after the Unit is turned OFF. The settings will be lost if the 3G3MV is turned OFF without writing the settings to EEPROM. EEPROM can be written up to 100,000 times.
- * For details on the parameters, refer to the 3G3MV Operation Manual.
- * Open the property sheet of this Smart Active Parts in the NS-Designer to set the Communication Setting.

1.1.5 Parameter No.13 to 24

No.20

No.21

No.22

No.23

No.24

n163

n129

n139

n140

PID Output Gain

E. S. Coefficient

F.b. Value Adjustment Gain

E. S. Control Selection

Unit type	3G3MV(-PD		Storage directory SmartActiveParts_E\tor\3G3MV\Serial(Dev			Title	Pa	Parameter No.13 to 24					
Function		3G3MV-P			VE 3G3MV-series Mul Communications Unit								ed
Display an	Display and Operation Details												
		1	2		3		4		5				
		j			Ĭ		ĺ		Ĭ				
		*	▼	•	▼		▼	1	7				
	N	lo.13 to No	.24		(cannot b							
		No. Co	nstant		Name	Defau	lt Set	t ∀al.	Unit				
	1	No.13	n128	PID Cor	ntrol Selection	0		2	-				
	1	No.14	n130	Propotio	onal Gain	1.0		0.2	-				
	1	No.15	n131	Integral	Time	1.0		0.2	s				
	1	No.16	n132	Derivativ	ve Time	0.00	0.	.02	s				
	No.17 n13			PID Offset Adjustment		0		2	%				
	No.18 n			Integral	100		2	%					
	1	n135	PID Prir	mary Delay Time	0.0		0.2	s					

0.2

0.02

0.2

0

Write

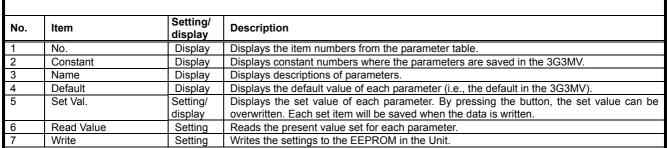
1.0

1.00

Ø

Read Value

6



- When using this Smart Active Part, be sure to select **Setting Unit/Scale Setting** in the menu bar and set the scale for number 1000 to 0.1 and the scale for 999 to 0.01
- * Execute EEPROM Write to save the settings so that they will be stored after the Unit is turned OFF. The settings will be lost if the 3G3MV is turned OFF without writing the settings to EEPROM. EEPROM can be written up to 100,000 times.
- * For details on the parameters, refer to the 3G3MV Operation Manual.
- * Open the property sheet of this Smart Active Parts in the NS-Designer to set the Communication Setting.

1.1.6 Conveyer Basic Adjustment (Unit: r/min)

Unit type	3G3MV(-PDRT2)	Stora			itle	Conveyer basic adjustment (unit: r/m						
Function			SYSDRIVE 3G3MV-series Mu eviceNet Communications Uni									
Display an	d Operation Details	3										
	1	2 ↓	3 ↓	4 ↓	5 ↓							
	Parameters for Controling Conveyer (cannot be set during operation)											
	No.	Constant	Name	Default	Set Va	I. Unit						
	No.1	n003	Run Command Selection	0	2	-						
	No.2	n004	Freq.Reference Selection	0	2	-						
	No.3	n019	Acceleration Time 1	10.0	0.2	2 s						
	No.4	n020	Deceleration Time 1	10.0	0.2	<u>2</u> s						
	No.5	n024	Rotational Speed 1	0	1	r/min						
	No.6	n025	Rotational Speed 2	0	1	r/min						
	No.7	n026	Rotational Speed 3	0	1	r/min						
	No.8	n103	Torque Compensation Gain	1.0	0.2	-						
	No.9	n111	Slip Compensation Gain	0.0	0.2	_						
			Rea	d Value	Į.	/rite	←	7				
			,	↑			I	•				
				6								

No.	Item	Setting/ display	Description
1	No.	Display	Displays the item numbers from the parameter table.
2	Constant	Display	Displays constant numbers where the parameters are saved in the 3G3MV.
3	Name	Display	Displays descriptions of parameters.
4	Default	Display	Displays the default value of each parameter (i.e., the default in the 3G3MV).
5	Set Val.	Setting/ display	Displays the set value of each parameter. By pressing the button, the set value can be overwritten. Each set item will be saved when the data is written.
6	Read Value	Setting	Reads the present value set for each parameter.
7	Write	Setting	Writes the settings to the EEPROM in the Unit.

- * When using this Smart Active Part, be sure to select **Setting Unit/Scale Setting** in the menu bar and set the scale for number 1000 to 0.1.
- * When using this SmartActive Part, select the r/min unit with *Parameter n035 (Frequency Reference Settings/Reference Unit Selection)* on the 3G3MV. Specifically, set n035 to 2 through 39 (number of motor poles). If a unit other than r/min is selected, values for parameters n024 to n026 will not be displayed normally.
- * Execute EEPROM Write to save the settings so that they will be stored after the Unit is turned OFF. The settings will be lost if the 3G3MV is turned OFF without writing the settings to EEPROM. EEPROM can be written up to 100,000 times.
- * For details on the parameters, refer to the 3G3MV Operation Manual.
- * Open the property sheet of this Smart Active Parts in the NS-Designer to set the Communication Setting.

1.1.7 Fan/Pump Basic Adjustment (Unit: r/min unit)

Unit type	3G3MV(-PD	ORT2)	Stora	•	SmartActiveParts_E tor\3G3MV\Serial(De Net)\Parameters		Title	Fa	n/Pump	basic	adjusti	ment (l	Jnit: r/m	in)
Function					VE 3G3MV-series Mul Communications Unit									
Display an	d Operation	Details	1											
	_	1	2 		3 ↓ ▼	4 ↓	•	5 						
	Parameters for Controlling Fan/Pump (cannot be set during operation)													
		Constant		Name	Defaul	t ∫Set \	/al.	Unit						
		n003	Run Cor	mmand Selection	0	3		-						
		No.2	n004	Freq.Reference Selection		0	2		-					
		No.3	n019	Accelera	10.0	1	.2	s						
		No.4	n020	Deceler	ation Time 1	10.0	1	.2	s					
		No.5	n024	Rotation	nal Speed 1	0		_	r/min					
		No.6	n025	Rotation	nal Speed 2	0		12	r/min					
		No.7	n026	Rotation	nal Speed 3	0	1	12	r/min					
		No.8	n034	Lower F	req. Reference Limit	0	1	2	%					
					Read	l Value	e [Wri	te	←	- 7			
	6													

No.	Item	Setting/ display	Description
1	No.	Display	Displays the item numbers from the parameter table.
2	Constant	Display	Displays constant numbers where the parameters are saved in the 3G3MV.
3	Name	Display	Displays descriptions of parameters.
4	Default	Display	Displays the default value of each parameter (i.e., the default in the 3G3MV).
5	Set Val.	Setting/	Displays the set value of each parameter. By pressing the button, the set value can be
		display	overwritten. Each set item will be saved when the data is written.
6	Read Value	Setting	Reads the present value set for each parameter.
7	Write	Setting	Writes the settings to the EEPROM in the Unit.

- When using this Smart Active Part, be sure to select **Setting Unit/Scale Setting** in the menu bar and set the scale for number 1000 to 0.1.
- * When using this Smart Active Part, select the r/min unit with *Parameter n035 (Frequency Reference Settings/Reference Unit Selection)* on the 3G3MV. Specifically, set n035 to 2 through 39 (number of motor poles). If a unit other than r/min is selected, values for parameters n024 to n026 will not be displayed normally.
- * Execute EEPROM Write to save the settings so that they will be stored after the Unit is turned OFF. The settings will be lost if the 3G3MV is turned OFF without writing the settings to EEPROM. EEPROM can be written up to 100,000 times.
- * For details on the parameters, refer to the 3G3MV Operation Manual.
- * Open the property sheet of this Smart Active Parts in the NS-Designer to set the Communication Setting.

1.1.8 Fan/Pump Basic + Energy-saving Adjustment (Unit: r/min unit)

Unit type	3G3MV(-	-PDRT2)	Stora direc		SmartActiveParts_E tor\3G3MV\Serial(De Net)\Parameters		Title		an/Pump Init: r/min		inergy-sa	ving adjustm
Function	through t	he 3G3M\ aving con	V-PDRT2 De trol are extra	eviceNet	VE 3G3MV-series Mu Communications Uni							
Display a	and Operation	on Details	3									
		1	2 ↓		3 ↓	4 ↓		5 ↓				
		Controllin	ng and Ener	gy-Savin	g Fan/Pump (cannot b	e set dur	ing o	peration)			
		No.	Constant		Name	Defaul	lt Set \	Val.	Unit			
		No.1	n003	Run Cor	mmand Selection	0	3	}	-			
		No.2	n004	Freq.Re	ference Selection	0	2		-			
		No.3	n019	Acceler	ation Time 1	10.0	1	.2	s			
		No.4	n020	Deceler	ation Time 1	10.0	1	.2	s			
		No.5	n024	Rotation	nal Speed 1	0		12	r/min			
		No.6	n025	Rotation	nal Speed 2	0		12	r/min			
		No.7	n026	Rotation	nal Speed 3	0		12	r/min			
		No.8	n034	Lower F	req. Reference Limit	0	1	2	%			
		No.9	n139	E. S. C	ontrol Selection	0	1		-			
		No.10	n140	E. S. C	oefficient		1	2	-			
					Read	d Value	e [Wr	ite [←	7	
						1						
						6						
No.	tem	Setting/ display										
	No.		Display		lays the item numbers						- 20214	
	Constant Name		Display Display		Displays constant numbers where the parameters are saved in the 3G3MV. Displays descriptions of parameters.							
	Name Defects		Display		plays descriptions of parameters.							

No.	Item	Setting/ display	Description
1	No.	Display	Displays the item numbers from the parameter table.
2	Constant	Display	Displays constant numbers where the parameters are saved in the 3G3MV.
3	Name	Display	Displays descriptions of parameters.
4	Default	Display	Displays the default value of each parameter (i.e., the default in the 3G3MV).
5	Set Val.	Setting/	Displays the set value of each parameter. By pressing the button, the set value can be
		display	overwritten. Each set item will be saved when the data is written.
6	Read Value	Setting	Reads the present value set for each parameter.
7	Write	Setting	Writes the settings to the EEPROM in the Unit.

- * When using this Smart Active Part, be sure to select **Setting Unit/Scale Setting** in the menu bar and set the scale for number 1000 to 0.1.
- * When using this Smart Active Part, select the r/min unit with *Parameter n035 (Frequency Reference Settings/Reference Unit Selection)* on the 3G3MV. Specifically, set n035 to 2 through 39 (number of motor poles). If a unit other than r/min is selected, values for parameters n024 to n026 will not be displayed normally.
- * Execute EEPROM Write to save the settings so that they will be stored after the Unit is turned OFF. The settings will be lost if the 3G3MV is turned OFF without writing the settings to EEPROM. EEPROM can be written up to 100,000 times.
- * For details on the parameters, refer to the 3G3MV Operation Manual.
- * Open the property sheet of this Smart Active Parts in the NS-Designer to set the Communication Setting.

1.1.9 PID Control Adjustment

1.1.9	PID COIL	roi Aajus	unent												
Unit ty	pe 3G3M	V(-PDRT2)	Stora direct	ge	SmartActivePa tor\3G3MV\Se Net)\Paramete	rial(De		Title	P	ID contro	ol adjust	ment			
Functi	on Adjust	ts the parame	eters of the S V-PDRT2 De	SYSDRIV viceNet (E 3G3MV-serion	es Mul ns Unit	ti-function Only p	on Co param	mpact eters u	Inverter sed for F	in serial PID cont	conne rol are	ction or extracte	connec d.	ted
Display	y and Oper	ation Details	5												
		1	2 ↓		3 ↓		4 ↓		5 ↓						
		PID Cont	trol Selection			(annot b	e set o	during o	peration)					
		No.	Constant		Name		Defaul	t S	et Val.	Unit					
		No.1	n128	PID Conti	rol Selection		0		8	_					
		No.2	n130	Proprtion	al Gain		1.0		1.2	-					
		No.3	n131	Integral Time			1.0		1.2	S					
		No.4	n132	Derivative Time			0.00		7. 12	S					
		No.5	n133	PID Offset Adjustment			0		12	%					
		No.6	n134	Integral (I) Upper Limit		100		12	%					
		No.7	n135	PID Prima	ary Delay Time		0.0		1.2	S					
		No.8	n163	PID Outp	ut Gain		1.0		1.2	-					
		No.9	n129	F.b. Valu	e Adjustment (Gain	1.00		0. 12	-					
						Read	l Value	e [Wr	ite	—	7			
						,					-				
							6								
No.	Item		Setting/ display												
1	No.		Display	Displa	ys the item nu	mbers	from th	e para	ameter	table.					

No.	Item	Setting/ display	Description
1	No.	Display	Displays the item numbers from the parameter table.
2	Constant	Display	Displays constant numbers where the parameters are saved in the 3G3MV.
3	Name	Display	Displays descriptions of parameters.
4	Default	Display	Displays the default value of each parameter (i.e., the default in the 3G3MV).
5	Set Val.	Setting/ display	Displays the set value of each parameter. By pressing the button, the set value can be overwritten. Each set item will be saved when the data is written.
6	Read Value	Setting	Reads the present value set for each parameter.
7	Write	Setting	Writes the settings to the EEPROM in the Unit.

- * When using this Smart Active Part, be sure to select **Setting Unit/Scale Setting** in the menu bar and set the scale for number 1000 to 0.1 and the scale for 999 to 0.01
- * Execute EEPROM Write to save the settings so that they will be stored after the Unit is turned OFF. The settings will be lost if the 3G3MV is turned OFF without writing the settings to EEPROM. EEPROM can be written up to 100,000 times.
- * For details on the parameters, refer to the 3G3MV Operation Manual.
- * Open the property sheet of this Smart Active Parts in the NS-Designer to set the Communication Setting.

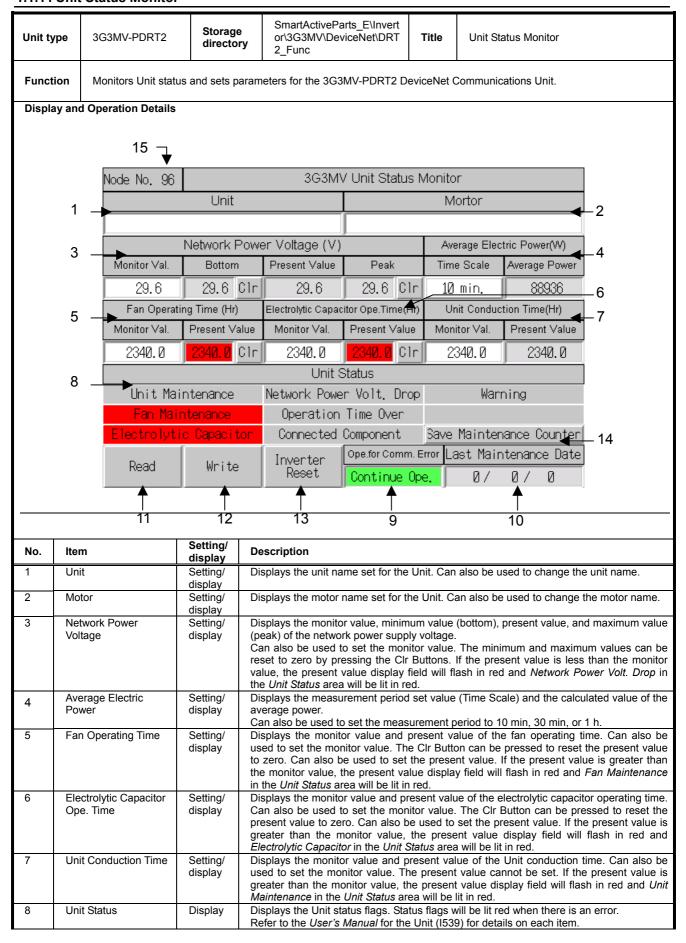
1.1.10 Elevator Basic Adjustment (Unit: r/min unit)

			SmartActiveParts_E	Inver							
Unit type	3G3MV(-PDRT2)	Stora	age tor/3G3M/ASorial/Do	tor\3G3MV\Serial(Device			Elevator basic adjustment (Unit: r/min unit)				
Function			SYSDRIVE 3G3MV-series Mul eviceNet Communications Unit								
Display and Operation Details											
	1	2	3	4	ţ	5					
	\downarrow	\downarrow	\downarrow	\downarrow		7					
	Parame	eters for Con	trolling Elevator (cannot b	e set duri	ng op	eration)				
	No.	Constant	Name	Defau	lt Set \	√al.	Unit				
No.1 n			Run Command Selection	0	3		-				
	No.2 no		Freq.Reference Selection	0	2		-				
	No.3 nO		Acceleration Time 1	10.0	1	.2	S				
	No.4	n020	Deceleration Time 1	10.0	1	.2	s				
	No.5	n024	Rotational Speed 1	0		12	r/min				
	No.6	n025	Rotational Speed 2	0		12	r/min				
	No.7	n026	Rotational Speed 3	0		12	r/min				
	No.8	n017	Min.Output Freq.Valtage		1	.2	V				
	No.9	n095	Frequency Detection Level	0.00	0.	. 12	Hz				
	No.10	n103	Torque Compensation Gain	1.0	1.	2	-				
	No.11	n111	Slip Compensation Gain	0.0	1.	2	-				
			Read	d Valu	e [Wri	te	←	- 7		
							`	ı	,		
				6							
				J							

No.	Item	Setting/ display	Description
1	No.	Display	Displays the item numbers from the parameter table.
2	Constant	Display	Displays constant numbers where the parameters are saved in the 3G3MV.
3	Name	Display	Displays descriptions of parameters.
4	Default	Display	Displays the default value of each parameter (i.e., the default in the 3G3MV).
5	Set Val.	Setting/ display	Displays the set value of each parameter. By pressing the button, the set value can be overwritten. Each set item will be saved when the data is written.
6	Read Value	Setting	Reads the present value set for each parameter.
7	Write	Setting	Writes the settings to the EEPROM in the Unit.

- * When using this Smart Active Part, be sure to select **Setting Unit/Scale Setting** in the menu bar and set the scale for number 1000 to 0.1 and the scale for 999 to 0.01.
- * When using this Smart Active Part, select the r/min unit with *Parameter n035 (Frequency Reference Settings/Reference Unit Selection)* on the 3G3MV. Specifically, set n035 to 2 through 39 (number of motor poles). If a unit other than r/min is selected, values for parameters n024 to n026 will not be displayed normally.
- * Execute EEPROM Write to save the settings so that they will be stored after the Unit is turned OFF. The settings will be lost if the 3G3MV is turned OFF without writing the settings to EEPROM. EEPROM can be written up to 100,000 times.
- * For details on the parameters, refer to the 3G3MV Operation Manual.
- * Open the property sheet of this Smart Active Parts in the NS-Designer to set the Communication Setting.

1.1.11 Unit Status Monitor



9	Ope. for Comm. Error	Setting/ display	Displays whether motor operation is continued or stopped when a DeviceNet communications error occurs. If the button is pressed, stopping or continuing operation can be selected.					
10	Last Maintenance Date	Display	Displays the last maintenance date registered in the Unit. The value cannot be changed.					
11	Read	Setting	Pressed to read all of the Unit status from 1 through 10.					
12	Write	Setting	Writes the Unit name, motor name, network power voltage monitor value, average electric power measurement period, Unit conduction time monitor value, fan operating time monitor value/present value, electrolytic capacitor operating time monitor value/present value, and operation for communications error setting.					
13	Inverter Reset	Setting	Always press this button after changing the measurement period for the average electric power. Pressing this button is not necessary after changing other settings. (Executes a software reset for the Inverter.)					
14	Save Maintenance Counter	Setting	Writes the maintenance counter information (i.e., the Unit conduction time, fan operating time, electrolytic capacitor operating time, and I/O terminal maintenance counter values) to EEPROM in the DeviceNet Communications Unit.					
15	Node No.	Display	Displays the node number set for the Unit.					

- * When using this Smart Active Part, be sure to select **Setting Unit/Scale Setting** in the menu bar and set the scale for number 1000 to 0.1.
- * Always press the Read Button to read the current settings from the Unit before changing the Unit name, motor name, network power voltage monitor value, average electric power measurement period, Unit conduction time monitor value, fan operating time monitor value/present value, electrolytic capacitor operating time monitor value/present value, and operation for communications error setting. For example, if there is a Configurator on the DeviceNet communications network and settings are changed from the Configurator, the settings displayed at the PT may not agree with those stored in the Unit. This may result in incorrect settings being written from the PT.
- * Maintenance counter information is written to EEPROM in the DeviceNet Communications Unit approximately every 6 minutes.

 Depending on the timing of when the power supply is turned OFF, up to 6 minutes worth of data may be lost. For more accurate management, press the Save Maintenance Counter Button just before turning OFF the power supply.
- * Open the property sheet of this Smart Active Parts in the NS-Designer to set the Communication Setting.

1.1.12 Input Status Monitor: 00 to 03

Unit ty	/pe 3G3MV-PDRT2	Storage directory	SmartActiveParts_E or\3G3MV\DeviceN 2_Func		Title	Input Status	Monitor: 00 to 03			
Funct	ion Displays and se	ts the status of i	put terminals 00 to 03 (te	rminals \$	S1 to S4).					
Displa	Display and Operation Details									
	9	→								
	Node No	. 96	3G3MV Input Stat	us Moni	tor (T/	F)				
	No.	I/0 Cd	mments Mo	ode 1	1. V.	P.V.	.6			
	0			F 26	8435752	268435752	R			
	1			T 26	8435752	268435752	Clr ₇			
	2			T 26	8435752	268435752	W			
	3			26	8435752	268435752				
	1				1	†	- 8			
	1		2	3	4	5				
		Setting/	.							
No.	Item	display	Description							
1	No.	Setting/ display	functions as a status ind	icator). an indic sent vali	ator to dis ue to zero.	play the input to	out terminal (i.e., bottom have erminals for which to reset the s.			
2	I/O Comments	Setting/ display	Displays the I/O commer	nts set fo	r the input	terminal. Settir	ng is also possible.			
3	Mode	Setting/ display	Displays the maintenance Can also be used to set			ency) set for th	e input terminal.			
4	M.V.	Setting/ display	Displays the maintenance			etting is also po	essible.			
5	P.V.	Setting/ display	Displays the present valual If the present value is lar	ger than	the monitor	or value, the dis	splay field will be lit red.			
6	R	Setting		tus, I/O	comments	, maintenance	mode, maintenance counte			
7	Clr	Setting					s for which the top half of the			
8	W	Setting				de, maintenand	ce counter monitor value, ar			
9 Remar	Node No.	Display	Displays the node number	er set for	the Unit.					

- Always press the Read Button to read the current settings from the Unit before changing the I/O comments, maintenance mode, maintenance counter monitor value, and present value. For example, if there is a Configurator on the DeviceNet communications network and settings are changed from the Configurator, the settings displayed at the PT may not agree with those stored in the Unit. This may result in incorrect settings being written from the PT.
- * Maintenance counter values (number of contact operations and total ON time) are written to EEPROM in the DeviceNet Communications Unit approximately every 6 minutes. Depending on the timing of when the power supply is turned OFF, up to 6 minutes worth of data may be lost. For more accurate management, press the Save Maintenance Counter Button in the Unit Status Monitor Smart Active Part just before turning OFF the power supply.
- * Open the property sheet of this Smart Active Parts in the NS-Designer to set the Communication Setting.

1.1.13 put Status Monitor: 04 to 06

			Cmart Astivo Darta Ellavort							
Unit ty	pe 3G3MV-PDRT2	Storage directory	SmartActiveParts_E\Invert or\3G3MV\DeviceNet\DRT 2_Func	Title	Input Status M	Ionitor: 04 to 06				
Function Displays and sets the status of input terminals 04 to 06 (terminals S5 to S7).										
Displa	Display and Operation Details									
	9 –	₹								
	Node No.	96	3G3MV Input Status Mon	itor (T/	F)					
	No.	I/O Comm	ments Mode	M. V.	P. V.	.6				
	4		F 2	68435752	268435752	R				
	5		T 2	8435752	268435752	Clr				
	6			68435752		₩ 7				
	^	↑	↑	lack	†					
	1	2	3	4	5	8				
No.	Item	Setting/ display	escription							
1	No.		isplays the number and the (DN/OFF st	atus of the input	t terminal (i.e., bottom half				
			inctions as a status indicator). he top half functions as an indic	ator to dis	play the input terr	minals for which to reset the				
		m	aintenance counter present val	ue to zero.						
2	I/O Comments	Setting/ Di	ress the number of an input to displays the I/O comments set for	change the	selection status.	ia alaa naasibla				
2	I/O Comments	display	isplays the 1/O confinents set it	ii iiie iiiput	terriiriai. Settirig	is also possible.				
3	Mode	Setting/ D	Displays the maintenance mode		uency) set for the	input terminal.				
4	M.V.		an also be used to set the mod isplays the maintenance monitor		etting is also noss	sihle				
7	IVI. V.	display	isplays the maintenance monito	n value. O	otting is also poss	noic.				
5	P.V.		isplays the present value of the							
6	R	display If Setting Re	the present value is larger than eads the ON/OFF status, I/O	comments	or value, the displ maintenance in	ay field will be lit red.				
Ŭ		m	onitor value, and present value	for all of th	ne input terminals	i.				
7	Clr		esets the maintenance counte o. display is lit.	r present v	alues for items for	or which the top half of the				
8	W	Setting W	rites the I/O comments, mainteresent value for all of the input t		de, maintenance	counter monitor value, and				
	Node No.		isplays the node number set for							

- Always press the Read Button to read the current settings from the Unit before changing the I/O comments, maintenance mode, maintenance counter monitor value, and present value. For example, if there is a Configurator on the DeviceNet communications network and settings are changed from the Configurator, the settings displayed at the PT may not agree with those stored in the Unit. This may result in incorrect settings being written from the PT.
- * Maintenance counter values (number of contact operations and total ON time) are written to EEPROM in the DeviceNet Communications Unit approximately every 6 minutes. Depending on the timing of when the power supply is turned OFF, up to 6 minutes worth of data may be lost. For more accurate management, press the Save Maintenance Counter Button in the Unit Status Monitor Smart Active Part just before turning OFF the power supply.
- * Open the property sheet of this Smart Active Parts in the NS-Designer to set the Communication Setting.

1.1.14 Output Status Monitor

Unit ty	ype 30	33MV-PDRT2	Storage directory	0r/3C3M/\/D	Parts_E\Invert eviceNet\DRT	Title	Output Status Monitor		
Funct	tion Di	splays and sets	the status of o	utput terminals 00	to 02 (terminals	MA, MB, F	P1, and P2).		
Display and Operation Details									
		10					_		
			lack	2	3	4	5		
		Node N	o. 96	3G3MV = Our	tput Sta <mark>t</mark> us	Monitor	(T/F)		
	1	I → No. T	1/0	Comments	Mode	M. V.	P.▼V.		
		<u> </u>	-, -	0011111011100	F	2684357			
		1			F				
		<u> </u>				2684357			
		2			F	2684357	52 268435752		
		Read	d Write	_ Fault	Hold Cle		ld Clear		
		near	- milo	Action	No. 00 No.	01 No.	02 P.V.		
							↑		
				l					
		7	8	6			9		
		,	U	O			9		
No.	Item		Setting/ display	Description					
1	No.		Setting/	Displays the num	ber and the Of	V/OFF sta	tus of the output terminal (i.e., b	ottom half	
'			display	functions as a stat	tus indicator).		, , ,		
				The top half functi maintenance cour			play the input terminals for which to	o reset the	
				Press the number			selection status.		
2	I/O Com	nments	Setting/	Displays the I/O c	omments set for	the outpu	t terminal. Setting is also possible.		
3	Mode		display Setting/	Displays the main	tenance mode (time/freque	ency) set for the output terminal.		
			display	Can also be used	to set the mode	٠.			
4	M.V.		Setting/	Displays the main	tenance monitor	r value. Se	tting is also possible.		
5	P.V.		display Setting/	Displays the prese	ent value of the	maintenan	ce counter. Setting is also possible	2 .	
			display	If the present valu	e is larger than	the monito	r value, the display field will be lit r	red.	
6	Fault Ac	ction	Setting/				tus is held or cleared when a		
			display	be selected.	error occurs. If the	ie button i	s pressed, holding or clearing ope	ration can	
7	Read		Setting	Reads all of the da					
8	Write		Setting				node, maintenance counter mon	itor value,	
9	Clear P.	V.	Setting	present value, and Resets the mainte			alues for items for which the top	half of the	
			_	No. display is lit.		•			
10	Node N	0.	Display	Displays the node	number set for	the Unit.			
Remar	KS								

- * When using this Smart Active Part, set the connection path for the Slave's remote I/O function to control I/O remote I/O. If any other setting is used for the remote I/O function, output status cannot be set or monitored.
- * Always press the Read Button to read the current settings from the Unit before changing the I/O comments, maintenance mode, maintenance counter monitor value, present value, and fault action. For example, if there is a Configurator on the DeviceNet communications network and settings are changed from the Configurator, the settings displayed at the PT may not agree with those stored in the Unit. This may result in incorrect settings being written from the PT.
- * Maintenance counter values (number of contact operations and total ON time) are written to EEPROM in the DeviceNet Communications Unit approximately every 6 minutes. Depending on the timing of when the power supply is turned OFF, up to 6 minutes worth of data may be lost. For more accurate management, press the Save Maintenance Counter Button in the Unit Status Monitor Smart Active Part just before turning OFF the power supply.
- * Open the property sheet of this Smart Active Parts in the NS-Designer to set the Communication Setting.

1.1.15 Operation Time Monitor

Unit ty	rpe 3G3M	/IV-PDRT2	Storage directory	SmartActivePart or\3G3MV\Devic 2_Func	s_E\Invert :eNet\DRT	Title	Opera	tion Time Monit	or
Funct	ion Displa	ays and sets t	ne operating tim	e for motors or perip	heral device	es connect	ed to the	e 3G3MV.	
Displa	y and Opera	tion Details			_			_	
		11 🗀	2		3	4	i	5	
			<u> </u>						
		Node No. 9	6	3G3MV Operat	ting Time	Monitor	(ms)		
	1 →	No. Equ	ipment Name	(Patterns)	Mon. Val	. Ope.	Time	Peak	
	-	0	(Ter.MA->Ter.S5)	296		296	296	
		1	(Ter.P1->Ter.S6)	296		296	296	
		2	(Ter. S3->Ter. S4)	296		296	296	
		3	(Ter. S5->Ter. S6)	296		296	296	
		4	((Ope.ON->Ter.S5)	296		296	296	
		5	((Ope.ON->Ter.S6)			296	296	
		Read		Write Stat	us Hold	Cle Er	ear ror	Clear Peak	
		<u></u>		<u></u>		1		+	
		7		8	6	ç	9	10	
		,			-				
No.	Item		Setting/ display	escription					
1	No.		display p	isplays the number eak value are to be or ress the number of a	cleared.				ne monitor error and
2	Equipment	Name		isplays the commen					ng is also possible.
3	Mon.Val.			isplays the operating	g time monito	or value. S	Setting is	also possible.	
4	Ope. Time		Display D	isplays the operatin	g time. If the	e operatin	g time i	is larger than the	e monitor value, the

Remarks

5

6

7

8

9

10

11

Peak

Read

Write

Status Hold

Clear Error

Clear Peak

Node No.

Always press the Read Button to read the current settings from the Unit before changing the equipment name, operating time monitor value, and status hold setting for No. 00 to 05. For example, if there is a Configurator on the DeviceNet communications network and settings are changed from the Configurator, the settings displayed at the PT may not agree with those stored in the Unit. This may result in incorrect settings being written from the PT.

display field will be lit red.

status can be selected.

No. 00 to 05.

Displays the peak value of the operating time.

Resets to zero the items for which the No. display is lit.

and status hold setting for No. 00 to 05.

Displays the node number set for the Unit.

Displays whether the status is to be held or cleared (updated) each time when an

operating time monitoring error is detected. If the button is pressed, holding or clearing

Reads the equipment name, operating time monitor value, operating time, peak value,

Writes the equipment name, operating time monitor value, and status hold setting for

Clears operating time monitoring errors for items for which the No. display is lit.

* The setting range for the monitor values is 0 to 65,535 (ms).

Display

Setting/ display

Setting

Setting

Setting

Setting

Display

- * Operating time monitoring for No. 00 (terminal MA to terminal S5) and No. 11 (terminal P1 to terminal S6) is valid only if the Slave's remote I/O function is set to control I/O remote I/O. If any other setting is used for the remote I/O function, monitoring will not be possible.
- * Open the property sheet of this Smart Active Parts in the NS-Designer to set the Communication Setting.

1.1.16 Warning Torque Monitor

Unit type	3G3	MV-PDRT2	Storage directory	SmartActivePart or\3G3MV\Device 2_Func		Title	Warning Torque Monitor		itor	
Function	Sets (torq		alue and displa	ys the peak current f	or monitoring	g error sta	tus of the lo	ad using the	Inverter's current	
Display a	Display and Operation Details									
		11	2		3	4	,	9		
	Node No. I	Node No. 9	6	3G3MV Warning	rning Torque Detection (A)					
		No.	Equipmen	t Name	Mon. Val	. Pe	eak C1	earError		
		Ø Accel/	Decel Torqu	e Current	2.96		2.96 C1	ear Peak	← 10	
		1 Torque	Current du	ring Frequency	2.96		2.96 01	ear Peak		
		Read	Write	status <mark>Ho</mark>	ld Detec	ction S er L	ensitivit evel 5 (H	y Highest)		
						1				
		7	8		5	6	6			
						·	-			
No. It	em		Setting/	Description						

No.	Item	Setting/ display	Description
1	No.	Display	Displays the number of the value to be monitored.
2	Equipment Name	Display	Displays the name of the value to be monitored.
3	Mon.Val.	Setting/ display	Displays the output current monitor value for the output current during acceleration/deceleration and output current monitor value for frequency agreements (constant-speed operation). Setting is also possible.
4	Peak	Display	Displays the peak current during acceleration/deceleration and peak current during frequency agreement. If the current is larger than the monitor value, a warning torque monitoring error will be detected and the display field will be lit red.
5	Status Hold	Setting/ display	Displays whether the status is to be held or cleared (updated) each time when a warning torque monitoring error is detected. If the button is pressed, holding or clearing status can be selected.
6	Detection Filter	Setting/ display	Displays the setting of the detection sensitivity used to prevent detection when the monitor value is exceeded only temporarily. Press the button to select the detection sensitivity from level 1 (lowest sensitivity) to level 5 (highest sensitivity).
7	Read	Setting	Reads the warning torque current monitor value, peak value, status hold setting, and detection filter setting for No. 00 to 01.
8	Write	Setting	Writes the warning torque current monitor value, status hold setting, and detection filter setting for No. 00 to 01.
9	Clear Error	Setting	Clears warning torque monitoring errors for items for which the peak display field is lit red. (The red displays will go out when the errors are cleared.)
10	Clear Peak	Setting	Resets the peak values to zero.
11	Node No.	Display	Displays the node number set for the Unit.

- When using this Smart Active Part, be sure to select Setting Unit/Scale Setting in the menu bar and set the scale for number 999 to 0.01.
- * Always press the Read Button to read the current settings from the Unit before changing the warning torque current monitor value, status hold setting, and detection filter setting for No. 00 to 01. For example, if there is a Configurator on the DeviceNet communications network and settings are changed from the Configurator, the settings displayed at the PT may not agree with those stored in the Unit. This may result in incorrect settings being written from the PT.
- * The setting range for the monitor values is 0.00 to 655.35 (A).
- * Warning torques will not be detected if the monitor value is set to 0.00 (A).
- * A detection sensitivity level of 5 (highest sensitivity) does not use a filter. A detection sensitivity level of 1 (lowest sensitivity) detects errors using a moving average of five current value samples.
- * Open the property sheet of this Smart Active Parts in the NS-Designer to set the Communication Setting.

1.2 3G3RV

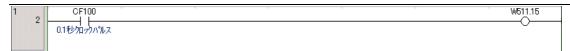
1.2.1 Speed Monitoring

Unit type	3G3RV	Storage directory	SmartActiveParts_E\Invertor\3G3RV\Serial(Device Net)\Monitor	Title	Speed Monitoring				
Function	Monitors the speed of the SYSDRIVE 3G3RV-series High-function Compact Inverter in serial connection or connected through the 3G3RV-PDRT2 DeviceNet Communications Unit. The monitoring cycle is adjustable in combination with a PLC program.								
Display an	d Operation Details								
		1	Rotational Speed 123 r/m Rotational Speed Communications Error Occurred		2				

No.	Item	Setting/ display	Description
1	Hidden indicator for trigger use	Display	A trigger indicator used to read the output current from the 3G3RV. This indicator is not displayed on the screen. The value can be read on a regular basis by turning ON and OFF the allocated address from the program in the PLC. The monitor cycle is determined by the program in the PLC. Adjust the cycle according to the communications load. The default address is (Serial A: WR00511.15). Change the address if required.
2	Rotational Speed	Display	Displays the speed read from the 3G3RV.
3	Communications error display	Setting/ display	Displays the status of an error if a communications error occurs between the Unit and the 3G3RV. Reading is not performed while this item is displayed. If the recovery of communications is expected, press the displayed part so that reading will be restarted.

Remarks

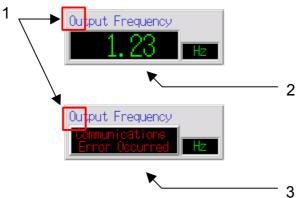
- * When using this Smart Active Part, select the r/min unit with *Parameter o1-03(Frequency Reference Settings/Reference Unit Selection)* on the 3G3RV. Specifically, set o1-03 to 2 through 39 (number of motor poles).
- * The following diagram shows a programming example on the PLC to monitor the value on a regular basis. The 0.1-second clock pulse is allocated to the specified address (Serial A: WR00511.15).



- * The actual monitor refreshing cycle varies with the number of Smart Active Parts monitored on the screen and the operating conditions of other Smart Active Parts. The refreshing cycle will increase if the number of Smart Active Parts increases.
- * If the other Smart Active Parts on the screen are in operation, refreshing the monitor will stop. When the operation of the Smart Active Parts stops, refreshing the monitor will restart.
- * Open the property sheet of this Smart Active Parts in the NS-Designer to set the Communication Setting.

1.2.2 Output Frequency Monitor

Unit type	3G3RV	Storage directory	SmartActiveParts_E\Invertor\3G3RV\Serial(Device Net)\Monitor	Title	Output frequency monitor				
Function					Compact Inverter in serial connection or monitoring cycle is adjustable in combination				
Display and Operation Details									



No.	Item	Setting/ display	Description
1	Hidden indicator for trigger use	Display	A trigger indicator used to read the output frequency from the 3G3RV. This indicator is not displayed on the screen. The value can be read on a regular basis by turning ON and OFF the allocated address from the program in the PLC. The monitor cycle is determined by the program in the PLC. Adjust the cycle according to the communications load. The default address is (Serial A: WR00511.15). Change the address if required.
2	Output Frequency	Display	Displays the output frequency read from the 3G3RV.
3	Communications error display	Setting/ display	Displays the status of an error if a communications error occurs on the 3G3RV. Reading is not performed while this item is displayed. If the recovery of communications is expected, press the displayed part so that reading will be restarted.

Remarks

- * When using this Smart Active Part, be sure to select **Setting Unit/Scale Setting** in the menu bar and set the scale for number 999 to 0.1.
- * When using this Smart Active Part, select the 0.01 Hz unit (default) with *Parameter n035 (Frequency Reference Settings/Reference Unit Selection)* on the 3G3RV. Specifically, set o1-03 to 0.
- * The following diagram shows a programming example on the PLC to monitor the value on a regular basis. The 0.1-second clock pulse is allocated to the specified address (Serial A: WR00511.15).

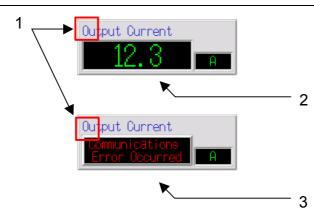


- * The actual monitor refreshing cycle varies with the number of Smart Active Parts monitored on the screen and the operating conditions of other Smart Active Parts. The refreshing cycle will increase if the number of Smart Active Parts increases.
- * If the other Smart Active Parts on the screen are in operation, refreshing the monitor will stop. When the operation of the Smart Active Parts stops, refreshing the monitor will restart.
- * Open the property sheet of this Smart Active Parts in the NS-Designer to set the Communication Setting.

1.2.3 Output Current Monitor

Unit type	3G3RV	Storage directory	SmartActiveParts_E\Invertor\3G3RV\Serial(Device Net)\Monitor	Title	Output current monitor
Function					empact Inverter in serial connection or monitoring cycle is adjustable in combination

Display and Operation Details



No.	Item	Setting/ display	Description
1	Hidden indicator for trigger use	Display	A trigger indicator used to read the output current from the 3G3RV. This indicator is not displayed on the screen. The value can be read on a regular basis by turning the program in the PLC ON and OFF. The monitor cycle is determined by the program in the PLC. Adjust the cycle according to the communications load. The default address is (Serial A: WR00511.15). Change the address if required.
2	Output Current	Display	Displays the output current read from the 3G3RV.
3	Communications error display	Setting/ display	Displays the status of an error if a communications error occurs between the Unit and the 3G3RV. Reading is not performed while this item is displayed. If the recovery of communications is expected, press the displayed part so that reading will be restarted.

Remarks

- * When using this Smart Active Part, be sure to select **Setting Unit/Scale Setting** in the menu bar and set the scale for number 1000 to 0.1.
- * The following diagram shows a programming example on the PLC to monitor the value on a regular basis. The 0.1-second clock pulse is allocated to the specified address (Serial A: WR00511.15).



- * The actual monitor refreshing cycle varies with the number of Smart Active Parts monitored on the screen and the operating conditions of other Smart Active Parts. The refreshing cycle will increase if the number of Smart Active Parts increases.
- * If the other Smart Active Parts on the screen are in operation, refreshing the monitor will stop. When the operation of the Smart Active Parts stops, refreshing the monitor will restart.
- * Open the property sheet of this Smart Active Parts in the NS-Designer to set the Communication Setting.

1.2.4 Parameter No. 1 to 12 (Unit: Hz)

.2.4 Pai		<u> </u>	•	•					
Unit type	3G3RV		Storage director		Title	Paramet	er No. 1 t	o 12 (unit:	Hz)
Function				SDRIVE 3G3RV-series High-func eNet Communications Unit. Only					
Display a	nd Operation Det	tails							
		1	2 	3	4	5 ↓			
		No.1 to No.	No.12 Constan	t Name	Default	et during op Set Val.	Deration) Unit		
		No.1	b1-02	Run Command Selection	0	2	-		
		No.2	b1-01	Freq.Reference Selection	0	2	-		
		No.3	C1-01	Acceleration Time 1	10.0	0.2	s		
		No.4	C1-02	Deceleration Time 1	10.0	0.2	S		
		No.5	d1-01	Frequency Reference 1	0.00	0.02	Hz		
		No.6	d1-02	Frequency Reference 2	0.00	0.02	Hz		
		No.7	d1-03	Frequency Reference 3	0.00	0.02	Hz		
		No.8	d2-02	Lower Freq. Reference Limit	0.0	0.2	%		
		No.9	E1-10	Min. Output Freq. Valtage		0.2	V		
		No.10	L4-01	Frequency Detection Level	0.0	0.2	Hz		
		No.11	C4-01	Torque Compensation Gain	1.00	0.02	_		
		No.12	C3-01	Slip Compensation Gain	0.0	0.2	_		
				Read Value Enab	le Val.	<u> W</u> ri	te		
				†	\uparrow	1	\		
				6	7	3	3		
No.	em		Setting/ display	Description					
1 N	lo.	Display Displays the item numbers from the parameter tab							\ /

No.	Item	Setting/ display	Description
1	No.	Display	Displays the item numbers from the parameter table.
2	Constant	Display	Displays constant numbers where the parameters are saved in the 3G3RV.
3	Name	Display	Displays descriptions of parameters.
4	Default	Display	Displays the default value of each parameter (i.e., the default in the 3G3RV).
5	Set Val.	Setting/ display	Displays the set value of each parameter. By pressing the button, the set value can be overwritten.
6	Read Value	Setting	Reads the present value set for each parameter.
7	Enable Val.	Setting	Reflects set descriptions in the operation of the Unit without writing them to the EEPROM.
8	Write	Setting	Writes set descriptions to the EEPROM and reflects them in the operation of the Unit.

- * When using this Smart Active Part, be sure to select **Setting Unit/Scale Setting** in the menu bar and set the scale for number 1000 to 0.1 and the scale for number 999 to 0.01.
- * When using this Smart Active Part, select the 0.01-Hz unit with *Parameter o1-03(Frequency Reference Settings/Reference Unit Selection)* on the 3G3RV. Specifically, set o1-03 to 0. If a unit other than 0.01 Hz is selected, values for parameters d1-01 to d1-03 will not be displayed normally.
- * After writing the settings, press the Enable Val. button and reflect the setting in the operation of the Unit.
- * Execute EEPROM Write to save the settings so that they will be stored after the Unit is turned OFF. The settings will be lost if the 3G3RV is turned OFF without writing the settings to EEPROM. EEPROM can be written up to 100,000 times.
- * For details on the parameters, refer to the 3G3RV Operation Manual.
- * Open the property sheet of this Smart Active Parts in the NS-Designer to set the Communication Setting.

1.2.5 Parameter No.13 to 24

1.2.5 Pai	ameter No.1	3 tO 24	•									
Unit type	3G3RV		Storage directory	SmartActiveParts_E\Inver tor\3G3RV\Serial(Device Net)\Pameters	Title	Paramet	er No.13	3 to 24				
Adjusts the parameters of the SYSDRIVE 3G3RV-series High-function Compact Inverter in serial connection or connected through the 3G3RV-PDRT2 DeviceNet Communications Unit. Only the main parameters are extracted from all the parameters.												
Display an	d Operation De	tails										
		1	2	3	4	5						
		\downarrow	\downarrow	↓	\downarrow	\downarrow						
		No.13 t	o No.24	(annot be s	et during op	eration)					
		No.	Constant	Name	Default	Set Val.	Unit					
		No.13	b5-01	PID Control Selection	0	2	-					
		No.14	b5-02	Propotional Gain	1.00	0.02	-					
		No.15	b5-03	Integral Time	1.0	0.2	s					
		No.16	b5-05	Derivative Time	0.00	0.02	s					
		No.17	b5-07	PID Offset Adjustment	0.0	0.2	%					
		No.18	b5-04	Integral (I) Upper Limit	100.0	0.2	%					
		No.19	b5-08	PID Primary Delay Time	0.00	0.02	s					
		No.20	b5-10	PID Output Gain	1.0	0.2	-					
		No.21	b8-01	E. S. Control Selection	0	1	-					
		No.22	b8-04	E. S. Coefficient		0.02	-					
		No.23				0	-					
		No.24				0	-					
				Read Value Enab	le Val.	Wri	te					
				A			\					
1				6	7	8	3					

No.	Item	Setting/ display	Description
1	No.	Display	Displays the item numbers from the parameter table.
2	Constant	Display	Displays constant numbers where the parameters are saved in the 3G3RV.
3	Name	Display	Displays descriptions of parameters.
4	Default	Display	Displays the default value of each parameter (i.e., the default in the 3G3RV).
5	Set Val.	Setting/ display	Displays the set value of each parameter. By pressing the button, the set value can be overwritten.
6	Read Value	Setting	Reads the present value set for each parameter.
7	Enable Val.	Setting	Reflects set descriptions in the operation of the Unit without writing them to the EEPROM.
8	Write	Setting	Writes set descriptions to the EEPROM and reflects them in the operation of the Unit.

- * When using this Smart Active Part, be sure to select **Setting Unit/Scale Setting** in the menu bar and set the scale for number 1000 to 0.1 and the scale for 999 to 0.01.
- * After writing the settings, press the Enable Val. button and reflect the setting in the operation of the Unit.
- * Execute EEPROM Write to save the settings so that they will be stored after the Unit is turned OFF. The settings will be lost if the 3G3RV is turned OFF without writing the settings to EEPROM. EEPROM can be written up to 100,000 times.
- * For details on the parameters, refer to the 3G3RV Operation Manual.
- * Open the property sheet of this Smart Active Parts in the NS-Designer to set the Communication Setting.

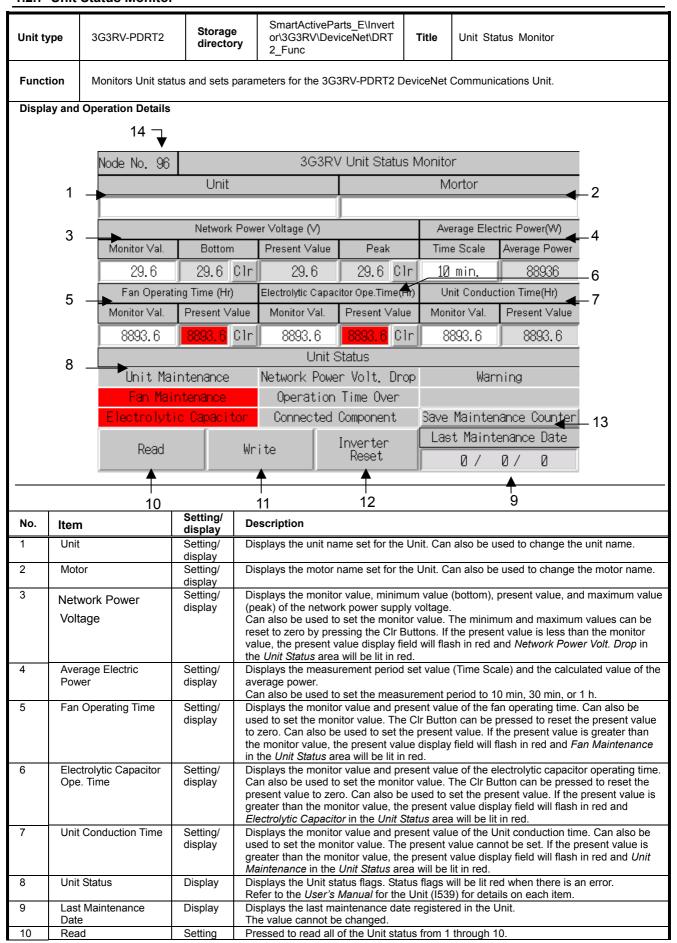
1.2.6 Fan/Pump Basic Adjustment (Unit: Hz)

Unit type	3G3RV		Storage directory	SmartActiveParts_E\Inver tor\3G3RV\Serial(Device Net)\Pameters	Title	Fan/Pum	np Basic	Adjustment (Unit: Hz)					
Function	Adjusts the parameters of the SYSDRIVE 3G3RV-series High-function Compact Inverter in serial connection or connected through the 3G3RV-PDRT2 DeviceNet Communications Unit. Only basic parameters used for fan and pump control are extracted.												
Display an	isplay and Operation Details												
		1	2	3	4	5							
		\downarrow	\downarrow	↓	\downarrow	\downarrow		_					
		Parame	ters for Cont	rolling Fan/Pump ((annot be s								
		No.	Constant	Name	Default	Set Val.	Unit						
		No.1	b1-02	Run Command Selection	0	2	-						
		No.2	b1-01	Freq.Reference Selection	0	2	-						
		No.3	C1-01	Acceleration Time 1	10.0	0.2	s						
		No.4	C1-02	Deceleration Time 1	10.0	0.2	s						
		No.5	d1-01	Frequency Reference 1	0.00	0.02	Hz						
		No.6	d1-02	Frequency Reference 2	0.00	0.02	Hz						
		No.7	d1-03	Frequency Reference 3	0.00	0.02	Hz						
		No.8	d2-02	Lower Freq. Reference Limit	0.0	0.2	%						
				Read Value Enab	le Val.	Wri	te						
	·			1	^			•					
				6	7	3	3						

No.	Item	Setting/ display	Description				
1	No.	Display	Displays the item numbers from the parameter table.				
2	Constant	Display	Displays constant numbers where the parameters are saved in the 3G3RV.				
3	Name	Display	Displays descriptions of parameters.				
4	Default	Display	Displays the default value of each parameter (i.e., the default in the 3G3RV).				
5	Set Val.	Setting/	Displays the set value of each parameter. By pressing the button, the set value can be				
		display	overwritten.				
6	Read value	Setting	Reads the present value set for each parameter.				
7	Enable Val.	Setting	Reflects set descriptions in the operation of the Unit without writing them to the EEPROM.				
8	Write	Setting	Writes set descriptions to the EEPROM and reflects them in the operation of the Unit.				

- * When using this Smart Active Part, be sure to select **Setting Unit/Scale Setting** in the menu bar and set the scale for number 1000 to 0.1 and the scale for 999 to 0.01.
- * When using this Smart Active Part, select the 0.01-Hz unit with *Parameter o1-03(Frequency Reference Settings/Reference Unit Selection)* on the 3G3RV. Specifically, set o1-03 to 0. If a unit other than 0.01 Hz is selected, values for parameters d1-01 to d1-03 will not be displayed normally.
- * After writing the settings, press the Enable Val. button and reflect the setting in the operation of the Unit.
- * Execute EEPROM Write to save the settings so that they will be stored after the Unit is turned OFF. The settings will be lost if the 3G3RV is turned OFF without writing the settings to EEPROM. EEPROM can be written up to 100,000 times.
- * For details on the parameters, refer to the 3G3RV Operation Manual.
- Open the property sheet of this Smart Active Parts in the NS-Designer to set the Communication Setting.

1.2.7 Unit Status Monitor



11	Write	Setting	Writes the Unit name, motor name, network power voltage monitor value, average electric power measurement period, Unit conduction time monitor value, fan operating time monitor value/present value, electrolytic capacitor operating time monitor value/present value, and operation for communications error setting.
12	Inverter Reset	Setting	Always press this button after changing the measurement period for the average electric power. Pressing this button is not necessary after changing other settings. (Executes a software reset for the Inverter.)
13	Save Maintenance Counter	Setting	Writes the maintenance counter information (i.e., the Unit conduction time, fan operating time, electrolytic capacitor operating time, and I/O terminal maintenance counter values) to EEPROM in the DeviceNet Communications Unit.
14	Node No.	Display	Displays the node number set for the Unit.

- * When using this Smart Active Part, be sure to select **Setting Unit/Scale Setting** in the menu bar and set the scale for number 1000 to 0.1
- * Always press the Read Button to read the current settings from the Unit before changing the Unit name, motor name, network power voltage monitor value, average electric power measurement period, Unit conduction time monitor value, fan operating time monitor value/present value, electrolytic capacitor operating time monitor value/present value, and operation for communications error setting. For example, if there is a Configurator on the DeviceNet communications network and settings are changed from the Configurator, the settings displayed at the PT may not agree with those stored in the Unit. This may result in incorrect settings being written from the PT.
- * Maintenance counter information is written to EEPROM in the DeviceNet Communications Unit approximately every 6 minutes.

 Depending on the timing of when the power supply is turned OFF, up to 6 minutes worth of data may be lost. For more accurate management, press the Save Maintenance Counter Button just before turning OFF the power supply.
- * Open the property sheet of this Smart Active Parts in the NS-Designer to set the Communication Setting.

1.2.8 Input Status Monitor: 00 to 03

Unit ty	pe 3G3RV-PDRT2	Storage directory	SmartActiveParts_E or\3G3RV\DeviceNe 2_Func		Title	Input Status	Monitor: 00 to 03						
Functi	Function Displays and sets the status of input terminals 00 to 03 (terminals S1 to S4).												
Displa	Display and Operation Details												
	O - Nodo No	00	OCODY Input Ctate	o Mon:	+on /T/	Γ\							
	9 Node No		3G3RV Input Statu										
	No.	I/O Com	ments Mo	de N	1. V.	P. V.	6						
	<u>0</u>		F	26	8435752	268435752	R						
	1			26	8435752	268435752	Clr						
	2		F	='-	8435752	268435752	₩ 7						
							YY						
	4			26	8435752	268435752							
							` 8						
	1	2	3		4	5							
No.	Item	Setting/ display	escription										
1	No.		isplays the number and		OFF status	s of the input ter	rminal (i.e., bottom half						
			inctions as a status indic		ator to dier	slav the input te	rminals for which to reset the						
			naintenance counter pres			nay the input ter	illilliais for which to reset the						
		F	ress the number of an in	put to cl	hange the								
2	I/O Comments	Setting/ Display	isplays the I/O comment	s set for	the input	terminal. Setting	g is also possible.						
3	Mode		isplays the maintenance	mode (time/frequ	ency) set for the	e input terminal.						
		display	an also be used to set the	ne mode	١.								
4	M.V.	Setting/ Display	isplays the maintenance	monitor	r value. Se	etting is also pos	ssible.						
5	P.V.		isplays the present value	e of the i	maintenan	ce counter. Set	ting is also possible.						
			the present value is larg										
6	R		leads the ON/OFF status nonitor value, and preser				ode, maintenance counter						
7	Clr						or which the top half of the						

Remarks

Node No.

Always press the Read Button to read the current settings from the Unit before changing the I/O comments, maintenance mode, maintenance counter monitor value, and present value. For example, if there is a Configurator on the DeviceNet communications network and settings are changed from the Configurator, the settings displayed at the PT may not agree with those stored in the Unit. This may result in incorrect settings being written from the PT.

present value for all of the input terminals

Displays the node number set for the Unit.

Writes the I/O comments, maintenance mode, maintenance counter monitor value, and

- * Maintenance counter values (number of contact operations and total ON time) are written to EEPROM in the DeviceNet Communications Unit approximately every 6 minutes. Depending on the timing of when the power supply is turned OFF, up to 6 minutes worth of data may be lost. For more accurate management, press the Save Maintenance Counter Button in the Unit Status Monitor Smart Active Part just before turning OFF the power supply.
- * Open the property sheet of this Smart Active Parts in the NS-Designer to set the Communication Setting.

No. display is lit.

Setting

Display

1.2.9 Input Status Monitor: 04 to 06

Unit ty	/pe	3G3RV-PDRT2	Storage directory				Input Status Monitor: 04 to 06				
Funct	Function Displays and sets the status of input terminals 04 to 06 (terminals S5 to S7).										
Displa	Display and Operation Details										
	9 -	→ Node No. 9	8 I	3G3RV Input Stat	ue Moni	tor (I/	E)				
	9	No.	<u> </u>			1. V.	P. V.				
			1/0 0011	illerits in				6			
		4				8435752	268435752	R			
		5				8435752	268435752	Clr ₹ 7			
		*			♠ <u> </u> 26	8 48 5752	<u> 268495752</u>	₩ .			
					l						
		1	2		3	4	5	8			
No.	Item		Setting/ display	escription							
1	No.			Displays the number and		OFF statu	s of the input terr	minal (i.e., bottom half			
			T	unctions as a status ind The top half functions as	an indica	ator to disp	play the input terr	minals for which to reset the			
				maintenance counter present value to zero. Press the number of an input to change the selection status.							
2	I/O C	Comments		Displays the I/O comme							
			display	· · ·							
3	Mode			Displays the maintenand Can also be used to set			ency) set for the	input terminal.			
4	M.V.		Setting/	Displays the maintenant			etting is also poss	sible.			
5	P.V.		display Setting/	Displays the present val	ue of the	maintenan	ice counter Setti	ng is also nossible			
3	1			f the present value is la							
6	Read	d		Reads the ON/OFF state monitor value, and prese	,	,		de, maintenance counter			
7	Clr		Setting F	Resets the maintenance				which the top half of the			
8 Write Setting			Setting V	No. display is lit. Writes the I/O comments, maintenance mode, maintenance counter monitor value, and present value for all of the input terminals.							
9	Node	e No.	Displan	Displays the node number set for the Unit.							
	<u> </u>		· , L	rispiays the node hul	inei set	וטו נוופ ט	IIIL.				

- * Always press the Read Button to read the current settings from the Unit before changing the I/O comments, maintenance mode, maintenance counter monitor value, and present value. For example, if there is a Configurator on the DeviceNet communications network and settings are changed from the Configurator, the settings displayed at the PT may not agree with those stored in the Unit. This may result in incorrect settings being written from the PT.
- * Maintenance counter values (number of contact operations and total ON time) are written to EEPROM in the DeviceNet Communications Unit approximately every 6 minutes. Depending on the timing of when the power supply is turned OFF, up to 6 minutes worth of data may be lost. For more accurate management, press the Save Maintenance Counter Button in the Unit Status Monitor Smart Active Part just before turning OFF the power supply.
- * Open the property sheet of this Smart Active Parts in the NS-Designer to set the Communication Setting.

1.2.10 Output Status Monitor

Unit ty	ype			ge ory	SmartActiveParts or\3G3RV\Device 2_Func		Title	Output Status M	onitor	
Funct	tion	Displays and set	s the status	of outp	put terminals 00 to 0	02 (terminals	s M1, M2,	P1, and P2).		
Displa	Display and Operation Details									
					2	3	4	5		
		1	0 —		_	,	7	ı		
		Node I	No. 96	,	↓ 3G3RV Outpu	t Sta <mark>t</mark> us	Monitor	(T/F) ↓		
		1 → No. T		70 C	omments	Mode	M. V.	P. V.		
		0				F	2684357		,	
		1				F	2684357			
		2				F	2684357			
		Rea	ad Wr	ite		old Ho .00 No.	ld Cle Ø1 No.	ar Clear 02 P.V.		
		1	· •		A			•		
		I	I					l		
		7	8		6			9		
No.	Item		Setting/							
NO.			display		escription	1.11 - 0.11	OFF 1.1			
1	No.		Setting/ display		spiays the number a nctions as a status i		OFF statu	s of the output term	ninal (i.e., bottom half	
			a.op.a.y	Th	ne top half functions	as an indica			nals for which to reset the	
					aintenance counter ess the number of a					
2	2 I/O Comments Sett				splays the I/O comn				is also possible.	
			display					_		
3	Mode		Setting/		splays the maintena			ency) set for the ou	ıtput terminal.	
4	M.V.		display Setting/	Can also be used to set the mode. Displays the maintenance monitor value. Setting is also possible.						
			display							
5	P.V.		Setting/		splays the present value is					
6	Fault /	Action	display Setting/		splays whether the					
		-	display	со	mmunications error				or clearing operation can	
7	Bood		Cotting	_	e selected.					
7 8	Read Write		Setting Setting		eads all of the data. rites the I/O comme	nts. mainter	nance mod	le, maintenance co	unter monitor value,	
			J		esent value, and fau					
9	Clear	P.V.	Setting	Re	esets the maintena	ance coun	ter presei	nt values for item	s for which the top half	
					the No. display is		-		·	
10	Node	No.	Display	_	splays the node nur		the Unit.			
Remar				•	-					

- * When using this Smart Active Part, set the connection path for the Slave's remote I/O function to control I/O remote I/O. If any other setting is used for the remote I/O function, output status cannot be set or monitored.
- * Always press the Read Button to read the current settings from the Unit before changing the I/O comments, maintenance mode, maintenance counter monitor value, present value, and fault action. For example, if there is a Configurator on the DeviceNet communications network and settings are changed from the Configurator, the settings displayed at the PT may not agree with those stored in the Unit. This may result in incorrect settings being written from the PT.
- * Maintenance counter values (number of contact operations and total ON time) are written to EEPROM in the DeviceNet Communications Unit approximately every 6 minutes. Depending on the timing of when the power supply is turned OFF, up to 6 minutes worth of data may be lost. For more accurate management, press the Save Maintenance Counter Button in the Unit Status Monitor Smart Active Part just before turning OFF the power supply.
- * Open the property sheet of this Smart Active Parts in the NS-Designer to set the Communication Setting.

1.2.11 Operation Time Monitor

Unit ty	/pe 3	G3RV-PDRT2	Storage directo	or/3C3	ctiveParts_E\Inv RV\DeviceNet\DF c		itle Oper	ation Time Moni	tor	
Funct	tion [isplays and sets	the operatin	g time for moto	ors or peripheral o	devices c	connected to	the 3G3RV.		
Displa	Display and Operation Details									
		11		2		3	4	5		
		1		_		•	i	J		
		Node No.	96	3G3RV	[/] Operating T	<u>il</u> me Mor	nito <u>r</u> (ms)			
	1	No. Equ	uipment Na	ame (Patter	ns) Mon.	Val.	Ope. Time	Peak		
		0		(Ter.MA->		296	296	296		
		1		(Ter.P1->		296	200 208	296		
		2		(Ter.S3->		296	200	296		
				• • • • •			296	,		
		3		(Ter. S5->		296	296	296		
		4		(Ope.ON->		296	296	296		
		5		(Ope.ON->	Ter.S6) 2	296	296	296		
		Read	ı [Write	Status H	old	Clear Error	Clear Peak		
		T		T	T		T	T		
		7		8	6		9	10		
No.	Item		Setting/ display	Description	n					
1	No.		Setting/				indicator if th	e operating time ı	monitor error and	
			display	•	are to be cleared. Imber of an input		ge the selecti	on status.		
2	Equipm	ent Name	Setting/ display	Displays the comments set for the equipment being monitored. Setting is also possible						
3	Mon.Va	l.	Setting/ display	Displays the	operating time m	nonitor va	alue. Setting	is also possible.		
4	Ope. Tir	me	Display	Displays the display field		f the ope	erating time is	larger than the n	nonitor value, the	
5	Peak		Display	Displays the peak value of the operating time.						
6	Status F	Hold	Setting/ display		ne monitoring erro			d (updated) each utton is pressed,	time when an holding or clearing	
7	Read		Setting	Reads the e	quipment name,			r value, operating	g time, peak value,	
8	Write		Setting		old setting for No			r value, and statu	us hold setting for	
	VVIILE		Setting	No. 00 to 05	quipilielli liaille, (peraury		value, allu Slatu	is now setting for	
9	Clear E	rror	Setting			ring error	rs for items for	or which the No. d	lisplay is lit.	

Remarks

10

Clear Peak

Node No.

* Always press the Read Button to read the current settings from the Unit before changing the equipment name, operating time monitor value, and status hold setting for No. 00 to 05. For example, if there is a Configurator on the DeviceNet communications network and settings are changed from the Configurator, the settings displayed at the PT may not agree with those stored in the Unit. This may result in incorrect settings being written from the PT.

Resets to zero the items for which the No. display is lit.

Displays the node number set for the Unit.

* The setting range for the monitor values is 0 to 65,535 (ms).

Setting

Display

- * Operating time monitoring for No. 00 (terminal M1 to terminal S5) and No. 11 (terminal P1 to terminal S6) is valid only if the Slave's remote I/O function is set to control I/O remote I/O. If any other setting is used for the remote I/O function, monitoring will not be possible.
- * Open the property sheet of this Smart Active Parts in the NS-Designer to set the Communication Setting.

1.2.12 Warning Torque Monitor

Unit type	3G3RV-PDRT2		Storage directory					Warning Torque Monitor		nitor	
Function	Sets the monitor value (torque).			ue and displays	the peak current f	or monitorin	ig error sta	tus of the	e load u	sing the	e Inverter's current
Display and	l Opera	tion I	Details								
			11 —	2		3	4	1	Ç)	
		Node	e No. 96		3G3MV Warning	Torque [Detectio	n (A)			
		No.		Equipment	Name	Mon. ▼ Va`	1. P	Z ak	Clear	Error	
	1 →	0	Acce1/De	ecel Torque	Current	2.96		2.96	Clear	Peak	← 10
		1	Torque (Ourrent dur	ing Frequency	2.96		2.96	Clear	Peak	
			Read	Write	Status Ho	ld Dete Filt	ction S er L	ensitiv evel 5	/ity (High	est)	
			1	1						•	
			7	8	Ę	5	ė	3			

No.	Item	Setting/ display	Description
1	No.	Display	Displays the number of the value to be monitored.
2	Equipment Name	Display	Displays the name of the value to be monitored.
3	Mon.Val.	Setting/ display	Displays the output current monitor value for the output current during acceleration/deceleration and output current monitor value for frequency agreements (constant-speed operation). Setting is also possible.
4	Peak	Display	Displays the peak current during acceleration/deceleration and peak current during frequency agreement. If the current is larger than the monitor value, a warning torque monitoring error will be detected and the display field will be lit red.
5	Status Hold	Setting/ display	Displays whether the status is to be held or cleared (updated) each time when a warning torque monitoring error is detected. If the button is pressed, holding or clearing status can be selected.
6	Detection Filter	Setting/ display	Displays the setting of the detection sensitivity used to prevent detection when the monitor value is exceeded only temporarily. Press the button to select the detection sensitivity from level 1 (lowest sensitivity) to level 5 (highest sensitivity).
7	Read	Setting	Reads the warning torque current monitor value, peak value, status hold setting, and detection filter setting for No. 00 to 01.
8	Write	Setting	Writes the warning torque current monitor value, status hold setting, and detection filter setting for No. 00 to 01.
9	Clear Error	Setting	Clears warning torque monitoring errors for items for which the peak display field is lit red. (The red displays will go out when the errors are cleared.)
10	Clear Peak	Setting	Resets the peak values to zero.
11	Node No.	Display	Displays the node number set for the Unit.

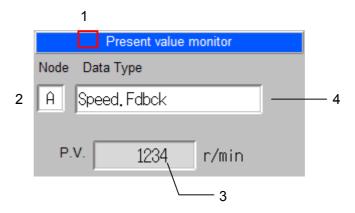
- * When using this Smart Active Part, be sure to select **Setting Unit/Scale Setting** in the menu bar and set the scale for number 999 to 0.01.
- * Always press the Read Button to read the current settings from the Unit before changing the warning torque current monitor value, status hold setting, and detection filter setting for No. 00 to 01. For example, if there is a Configurator on the DeviceNet communications network and settings are changed from the Configurator, the settings displayed at the PT may not agree with those stored in the Unit. This may result in incorrect settings being written from the PT.
- * The setting range for the monitor values is 0.00 to 655.35 (A).
- * Warning torques will not be detected if the monitor value is set to 0.00 (A).
- * A detection sensitivity level of 5 (highest sensitivity) does not use a filter. A detection sensitivity level of 1 (lowest sensitivity) detects errors using a moving average of five current value samples.
- * Open the property sheet of this Smart Active Parts in the NS-Designer to set the Communication Setting.



1.1 R88D-WT/R7D-AP

1.1.1 Present Value Monitor

Unit Type	R88D-WT R7D-AP	Storage directory	SmartActiveParts_E\ServoDriver	Title	Present value monitor		
Function	The present value of up to 16 servo drivers (W series, and Smart step) connected in a serial connection can be read by setting the node no. and selecting the data type. If the servo driver is not connected or has a communication error, the data will not be read or set.						
Display and Operation Details							



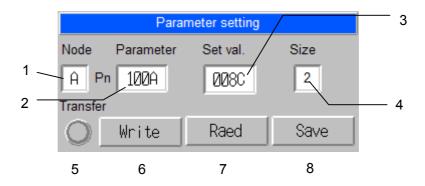
No.	Item	Setting/ display	Description
1	Hidden indicator for trigger use	Display	A trigger indicator used to refresh the present value. The indicator is not displayed on the NS hardware. The data can be periodically refreshed by turning ON and OFF the allocated address from the program in the PLC. The program in the PLC determines the monitor cycle, so please adjust it according to the communications load. The set address is [SerialA:WR00511.15]. Change the address if required. Data refreshment will start only after the unit communicates normally with the set node no. Switching a screen can also refresh the data.
2	Node No.	Setting	Sets the node no. to be displayed.
3	Present value	Display	Sets the present value.
4	Data type	Setting	Selects a data type to display the type and the unit. (The Unit is displayed to the right of the present value.)

^{*} When using this Smart Active Parts, be sure to select **Setting** - **System Setting** in the menu bar, press the **System Memory List** on the Initial Tab Page, and select **Basic Operation** for \$SB. The Smart Active Parts cannot be used on the pop-up screen.

1.1.2 Parameter Setting

Unit type	R88D-WT R7D-AP	Storage directory	SmartActiveParts_E\ServoDriver	Title	Parameter setting
Function	'	•	drivers (W series, and Smart step) cons Servo driver is not connected or has a co		

Display and Operation Details



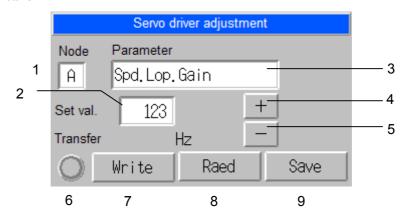
No.	Item	Setting/ display	Description
1	Node No.	Setting	Sets the Node no.
2	Parameter No.	Setting	Set the parameter no.
3	Set value	Setting/ Display	Displays the set value read from the servo driver parameter. The value can be overwritten.
4	Parameter Size	Display	Displays parameter size (fixed to 2).
5	Transferring	Display	It will flash when the communication is in progress.
6	Write	Setting	Writes the settings to the RAM in the servo driver parameter no. Writes the set value in the last three digits of the parameter address.
7	Read	Setting	Reads the details of servo driver parameter number either from RAM or EEPROM and displays to the set value. Parameter No.: 0xxx(when the high order digit is 0) reads from the RAM area. 1xxx(when the high order digit is 1) reads from the EEEPROM
8	Save	Setting	Writes the set value to the EEPROM of servo driver parameter no. Writes the set value in the last three digits of the parameter address.

- * If the gain setting rotary switch on the smart step is not set to 0, a certain parameter cannot be written to EEPROM.
- * Refer to the *Unit Manual* for details on Parameter.

1.1.3 Servo Driver Adjustment

Unit type	R88D-WT R7D-AP	Storage directory	SmartActiveParts_E\ServoDriver	Title	Servo driver adjustment
Function	•	cting the param	, and Smart step) connected in a serial c leter name. If the servo driver is not conf		, ,

Display and Operation Details



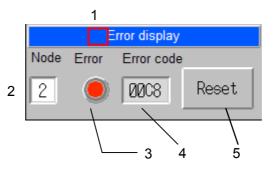
No.	Item	Setting/ display	Description		
1	Node No.	Setting	Sets the node no.		
2	Set value	Setting/ display	Displays the set value read from the servo driver parameter. The value can be overwritten.		
3	Parameter name	Setting	Selects the parameter name to be displayed and the unit. (Unit is displayed outside of the setting value frame.)		
4	+	Setting	Increases the setting value.		
5	-	Setting	Decreases the setting value.		
6	Transferring	Display	It will flash when the communication is in progress.		
7	Write	Setting	Writes the setting value to the RAM of a servo driver parameter name.		
8	Read	Setting	Reads the RAM of a servo driver parameter name and displays it in the setting value		
9	Save	Setting	Writes the setting value to EEPROM of the servo driver name.		

- * If the gain setting rotary switch on the smart step is not 0, a certain parameter cannot be written to EEPROM.
- * Refer to the Unit Manual for details on Parameter.

1.1.4 Error Display

Unit type	R88D-WT R7D-AP	Storage directory	SmartActiveParts_E\ServoDriver	Title	Error display	
Function	By setting the node no, reads error details of the parameter of up to 16 servo drivers (W series, and Smart step) connecte in a serial connection. If the servo driver is not connected or has a communication error, the data will not be read.					

Display and Operation Details



No.	Item	Setting/ display	Description
1	Hidden indicator for trigger use	Display	A trigger indicator used to refresh the error lamp and the error code. The indicator is not displayed on the NS hardware. The value can be periodically refreshed by turning ON and OFF the allocated address from the program in the PLC. The program in the PLC determines the monitor cycle, so please adjust it according to the communications load. The set address is [SerialA:WR00511.15]. Change the address if required. Data refreshment will start only after the unit communicates normally with the set node no. Switching a screen can also refresh the data.
2	Node No.	Setting	Sets the node no. to be displayed.
3	Error	Display	It will flash when an error occurs.
4	Error code	Display	Shows the error code when an error occurs. (0000 is displayed when it operates normally.)
5	Error reset	Setting	Resets the developing error for the servo driver.

^{*} When using this Smart Active Parts, be sure to select **Setting** - **System Setting** in the menu bar, press the **System Memory List** on the Initial Tab Page, and select **Basic Operation** for \$SB. The Smart Active Part cannot be used on the pop-up screen.

1.1.5 I/O Status Monitor 1 (NS Hardware)

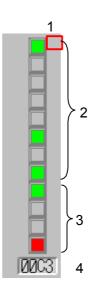
1.1.5	I/O Status Mon	1101 1 (1	10 Hai	uwa	11 <i>6)</i>		,		
Unit type	R88D-WT		orage ectory	SmartactiveParts E/ServoDriver Little					
Function	Monitors the I/O status of up to 16 servo drivers (W series) connected in a serial connection. If the servo driver is not connected or has a communication error, the data will not be monitored.								
Display an	d Operation Details								
RUN Command Gain Reduction POT Signal NOT Signal Alarm Reset Pos. Current. Limit Rev. Current. Limit Sensor ON SEN Speed. Reached Motor. Rev. Detect Servo. Ready Alarm Error code RUN Command Fundament 4 4 4 5 6									
	Ţ			OI (oue .				
No.	Item	Setting/ display				Descript	ion		
1	Hidden indicator for trigger use	Display	A trigger indicator used to refresh the I/O status monitor. The indicator is not displayed on the NS hardware. The value can be periodically refreshed by turning ON and OFF the allocated address from the program in the PLC. The program in the PLC determines the monitor cycle, so please adjust it according to the communications load. The set address [SerialA:WR00511.15]. Change the address if required. Data refreshment will start only after the unit communicates normally with the set node no.						
2	Input signal I/O status name	Display			creen can also ref input signal I/O sta				
3	Output signal I/O status name	Display	Display	s the	output signal I/O s	tatus name.			
4	Input signal I/O lamp	Display	Lamps Please	are al	nen the input signal located in the following to the allocation be Pin for CN CN1-40 CN1-41 CN1-42 CN1-43 CN1-44 CN1-45 CN1-46 CN1-46	owing order. elow. Name display	e e e e	A to Pn50D and	

5	Output signal I/O status lamp	Display			nen the output si located in the fol	<u> </u>	
ļ		'	Please	e refer t	to the allocation l	below.	
		!		No. Pin for CN Name Display			
		!		1 CN1-25 Allocated between Pn50E to Pn510			
		!		2 CN1-27 Same as above		Same as above	
		!		3	CN1-29	Same as above	
		,		4	CN11-31	Fixed to ALARM	
6	Error code	Display	Shows the error code when an error occurs. (0000 is displayed when it operates normally.)				

- * When using this SMART Active Part, be sure to select **Setting System Setting** in the menu bar, press the **System Memory List** on the Initial Tab Page, and select **Basic Operation** for \$SB. The Smart Active Part cannot be used on the pop-up screen.
- * Input output signal I/O status name varies with the servo driver parameter. Please set the parameter to be displayed in advance. However, SEN for the censer on and ALM for the alarm are fixed.
- * Refer to the *Unit Manual* for details on Parameter.
- * When using this device library, be sure to set both the unit no. direction for the communication setting dialog screen and the servo driver node address.

1.1.6 I/O Status 1 (No name)

Unit type	R88D-WT	Storage directory	SmartActiveParts_E\ServoDriver	Title	I/O Status monitor 1 (No name)		
Function		Monitors the I/O status of up to 16 servo drivers (W series) connected in a serial connection. If the servo driver is not connected or has a communication error, the data will not be monitored.					



No.	Item	Setting/ display	Description
1	Hidden indicator for trigger use	Display	A trigger indicator used to refresh the I/O status monitor. The indicator is not displayed on the NS hardware. The value can be periodically refreshed by turning ON and OFF the allocated address from the program in the PLC. The program in the PLC determines the monitor cycle, so please adjust it according to the communications load. The set address is [SerialA:WR00511.15]. Change the address if required. Data refreshment will start only after the unit communicates normally with the set node no. Switching a screen can also refresh the data.
2	Input signal I/O status lamp	Display	It will flash when the input signal is ON.
3	Output signal I/O status lamp	Display	It will flash when the output signal is ON.
4	Error code	Display	Shows the error code when an error occurs. (0000 is displayed when it operates normally.)

- When using this Smart Active Parts, be sure to select Setting System Setting in the menu bar, press the System Memory List
- on the Initial Tab Page, and select *Basic Operation* for \$SB. The Smart Active Parts cannot be used on the pop-up screen. Set the parameter the same as the one for the I/O status monitor 1(NS hardware), even though the name will not be shown on this
- Refer to the *Unit Manual* for details on Parameter.
- When using this device library, be sure to set both the unit no. direction for the communication setting dialog screen and the servo driver node address.

1.1.7 I/O Status Monitor 2 (NS Hardware)

Unit type	R7D-AP	Storage directory	SmartActivePart	s_E\ServoDriver	Title	I/O Status Monitor 2 (NS Hardware)	
Function	unction Monitors the I/O status of up to 16 servo drivers (Smart step) connected in a serial connection. If the servo driver is not connected or has a communication error, the data will not be monitored.						
Display an	d Operation Details						
			1				
		-	70.1/0.01-1				
		Н.	7D I/O Status				
		Run Comma Alarm Reset		}	2		
			mpleted(INP)	i i			
		Brake Interlo	ck(BKIR)	}	3		
		Alarm(ALM)					
		Error code			- 4		

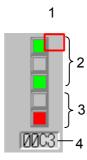
No.	Item	Setting/ display	Description
1	Hidden indicator for trigger use	Display	A trigger indicator used to refresh the I/O status monitor. The indicator is not displayed on the screen. The value can be periodically refreshed by turning ON and OFF the allocated address from the program in the PLC. The program in the PLC determines the monitor cycle, so please adjust it according to the communications load. The set address is [SerialA:WR00511.15]. Change the address if required. Data refreshment will start only after the unit communicates normally with the set node no. Switching a screen can also refresh the data.
2	Input signal I/O status lamp	Display	It will flash when the input signal is ON.
3	Output signal I/O status lamp	Display	It will flash when the output signal is ON.
4	Error code	Display	Shows the error code when an error occurs. (0000 is displayed when it operates normally.)

- * When using this SMART Active Part, be sure to select **Setting System Setting** in the menu bar, press the **System Memory List** on the Initial Tab Page, and select **Basic Operation** for \$SB. The Smart Active Part cannot be used on the pop-up screen.
- * When using this device library, be sure to set both the unit no. direction for the communication setting dialog screen and the servo driver node address.

1.1.8 I/O Status Monitor 2 (No name)

Unit type	R7D-AP	Storage directory	SmartActiveParts_E\ServoDriver	Title	I/OS Status Monitor 2 (No name)
Function	Monitors the I/O status of up to 16 servo drivers (Smart step) connected in a serial connection. If the servo driver is not connected or has a communication error, the data will not be monitored.				

Display and Operation Details



No.	Item	Setting/ display	Description
1	Hidden indicator for trigger use	Display	Triggers to refresh the monitor for I/O status. The value is not displayed on the NS hardware screen. Data can be periodically refreshed by On and OFF of the address allocated to the unit on the PLC. The program in the PLC determines the monitor cycle, so please adjust it according to the communications load. The set address is [SerialA:WR00511.15]. Change the address if required. Data refreshment will start only after the unit communicates normally with the set node no. Switching a screen can also refresh the data.
2	Input signal I/O status lamp	Display	It will flash when the input signal is ON.
3	Output signal I/O status lamp	Display	It will flash when the output signal is ON.
4	Error code	Display	Shows the error code when an error occurs. (0000 is displayed when it operates normally.)

- * When using this SMART Active Part, be sure to select **Setting System Setting** in the menu bar, press the **System Memory List** on the Initial Tab Page, and select **Basic Operation** for \$SB. The Smart Active Part cannot be used on the pop-up screen.
- * Set a parameter the same as the one for the I/O Status monitor 2(NS hardware), even though its name will not be shown on this screen.
- * When using this device library, be sure to set both the unit no. direction for the communication setting dialog screen and the servo driver node address.



The following table lists the Smart Active Parts for the E5ZN Temperature Controller.

	sts the Smart Active Parts for the E5ZN		
Setting level	Temperature Controller type	Channel	Smart Active Part name
Operation level	Temperature Controllers with Thermocouples	CH1	Operation Monitor for Standard Control Operation Monitor for Heating/Cooling
	·		Control
			SP and Alarm Settings
			PV Hold Value
			SP Setting
		CH2	Operation Monitor for Standard Control
			Operation Monitor for Heating/Cooling
			Control
			SP and Alarm Settings
			PV Hold Value
			SP Setting
	Temperature Controllers with	CH1	Operation Monitor for Standard Control
	Platinum-resistance Thermometers		Operation Monitor for Heating/Cooling
			Control
			SP and Alarm Settings
			PV Hold Value
			SP Setting
		CH2	Operation Monitor for Standard Control
			Operation Monitor for Heating/Cooling
			Control
			SP and Alarm Settings
			PV Hold Value
			SP Setting
Adjustment level	Temperature Controllers with Thermocouples	CH1	Manual MV Settings
			Multi-SP Settings
		CH2	Manual MV Settings
			Multi-SP Settings
	Temperature Controllers with	CH1	Manual MV Settings
	Platinum-resistance Thermometers		Multi-SP Settings
		CH2	Manual MV Settings
			Multi-SP Settings
	Temperature Controllers with	CH1	Heater Burnout Detection
	Thermocouples or		PID Settings
	Platinum-resistance Thermometers		Input Shift Values
			Manual Reset Value
			Cooling Coefficient, Dead Band, and Control Period
			Dead Band and Hysteresis
		CH2	Heater Burnout Detection
			PID Settings
			Input Shift Values
			Manual Reset Value
			Cooling Coefficient, Dead Band, and
			Control Period
			Dead Band and Hysteresis
	Temperature Controllers with Analog	CH1	Manual MV Settings
	Outputs and Thermocouple Inputs	CH2	Manual MV Settings
	Temperature Controllers with Analog	CH1	Manual MV Settings
	Outputs and Platinum-resistance Thermometer Inputs	CH2	Manual MV Settings

Setting level	Temperature Controller type	Channel	
Initial setting level	Temperature Controllers with	CH1	Input 1 Type, Temperature Unit, Scaling,
	Thermocouples		and Decimal Point
			SP Limits
		CH2	Input 1 Type, Temperature Unit, Scaling,
			and Decimal Point
			SP Limits
		Common	Transfer Output Upper and Lower Limits
	Temperature Controllers with	CH1	SP Limits
	Platinum-resistance Thermometers	CH2	SP Limits
		Common	Input 1 Type and Temperature Unit
			Transfer Output Upper and Lower Limits
	Temperature Controllers with	CH1	PID or ON/OFF Control
	Thermocouple or Platinum-resistance		Direct/Reverse Operation
	Thermometer Inputs		Alarm 1 Type, Open/Close in Alarm,
			Latch, Hysteresis
			Alarm 2 Type, Open/Close in Alarm, Latch, Hysteresis
			Alarm 3 Type, Open/Close in Alarm, Latch, Hysteresis
		CH2	PID or ON/OFF Control
			Direct/Reverse Operation
			Alarm 1 Type, Open/Close in Alarm,
			Latch, Hysteresis
			Alarm 2 Type, Open/Close in Alarm,
			Latch, Hysteresis
			Alarm 3 Type, Open/Close in Alarm, Latch, Hysteresis
		Common	Control Output 1 and 2 Allocations
			Auxiliary Output 1 and 2 Allocations
			Auxiliary Output 3 and 4 Allocations
			Current/Voltage Output
			Sensor Error Indicator Used and Input
			Error Output
			Operation after Power ON
Advanced function	Temperature Controllers with	CH1	SP Ramp
setting level	Thermocouples	CH2	SP Ramp
octaring lover	Temperature Controllers with	CH1	SP Ramp
	Platinum-resistance Thermometers	CH2	
		CH1	SP Ramp
	Temperature Controllers with Thermocouple or Platinum-resistance	CHI	HBA Used, Latch, Hysteresis
	Thermometer Inputs		MV Upper/Lower Limits and Input Digital Filter
	·		
	Temperature Controllers with		MV Upper/Lower Limits and Input Digital
	Thermocouples or Platinum-resistance Thermometers	CHO	Filter (Models with Analog Outputs)
	i idilitili-resistance memometers	CH2	HBA Used, Latch, Hysteresis
			MV Upper/Lower Limits and Input Digital Filter
			MV Upper/Lower Limits and Input Digital
			Filter (Models with Analog Outputs)
		Common	Input Shift Type
		50/11/10/1	Number of Multi-SP Uses, Event Input
			Allocation, Use Multi-SP
			Standby Sequence Restart
			a
			Cold Junction Componentian Mathed
Communications		Common	Cold Junction Compensation Method
Communications		Common	Communications Settings
setting level			

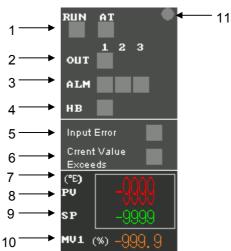
1.1 E5ZN

1.1.1 Operation Level

(1) Operation Monitor for Standard Control

Setting level	Input type	Channel	Part
Operation level	Thermocouple input	CH1	Yes
		CH2	Yes
		All CH	No
	Platinum-resistance thermometer	CH1	Yes
		CH2	Yes
		All CH	No

Unit type	E5ZN	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5ZN\OperationLe vel	Title	Operation Monitor for Standard Control
Function	Continuously monitors operating status on a face plate.				
Display and Operation Details					



No.	Item	Setting/ display	Description	
1	RUN AUTO	Display	Displays the run/stop, auto/manual, and autotuning status.	
·	AT	Biopiay	Diopidyo tho falliotop, addomanda, and addotailing status.	
2	OUT	Display	Displays the output status of control outputs 1 and 2.	
3	ALM	Display	Displays the output status of alarm outputs 1, 2, and 3.	
4	HB	Display	Displays the heater burnout output status.	
5	Input Error	Display	lay Displays the input error status.	
6	Current Value Exceeds	Display	Displays the status of a current value exceeded error.	
7	(°C) / (°F)	Display	Displays the temperature unit.	
8	PV	Display	Displays the process value.	
9	SP	Display	Displays the set point.	
10	MV1	Display	Displays the manipulated variable.	
11	Display Update Indicator	Display	Flashes each time the display is updated.	

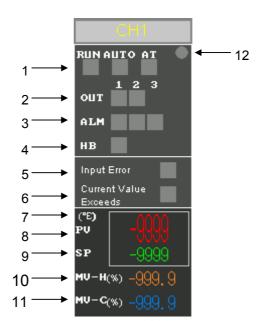
- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- Use System version 5 or higher version.

(2) Operation Monitor for Heating/Cooling Control

Setting level	Input type	Channel	Part
Operation level	Thermocouple input	CH1	Yes
		CH2	Yes
		All CH	No
	Platinum-resistance thermometer	CH1	Yes
		CH2	Yes
		All CH	No

Unit type	E5ZN	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5ZN\OperationLe vel	Title	Operation Monitor for Heating/Cooling Control
Function	Continuously monitors operating status on a face plate.				

Display and Operation Details

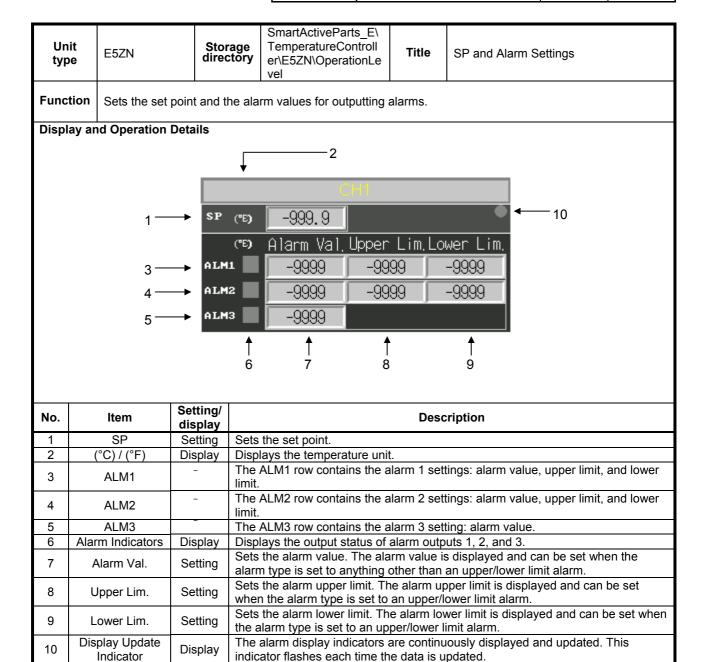


No.	Item	Setting/ display	Description
1	RUN AUTO AT	Display	Displays the run/stop, auto/manual, and autotuning status.
2	OUT	Display	Displays the output status of control outputs 1 and 2.
3	ALM	Display	Displays the output status of alarm outputs 1, 2, and 3.
4	HB	Display	Displays the heater burnout output status.
5	Input Error	Display	Displays the input error status.
6	Current Value Exceeds	Display	Displays the status of a current value exceeded error.
7	(°C) / (°F)	Display	Displays the temperature unit.
8	PV	Display	Displays the process value.
9	SP	Display	Displays the set point.
10	MV-H	Display	Displays the manipulated variable for heating.
11	MV-C	Display	Displays the manipulated variable for cooling.
12	Display Update Indicator	Display	Flashes each time the display is updated.

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- Use System version 5 or higher version.

(3) SP and Alarm Settings

Setting level	Input type	Channel	Part
Operation level	Thermocouple input	CH1	Yes
		CH2	Yes
		All CH	No
	Platinum-resistance thermometer	CH1	Yes
		CH2	Yes
		All CH	No



- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- Use System version 5 or higher version.

(4) PV Hold Value

Setting level	Input type	Channel	Part
Operation level	Thermocouple input	CH1	Yes
		CH2	Yes
		All CH	No
	Platinum-resistance thermometer	CH1	Yes
		CH2	Yes
		All CH	No

Unit type	E5ZN	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5ZN\OperationLe vel	Title	PV Hold Value	
Function	Continuously monitors the PV hold value.					
Display and Operation Details						



No.	Item	Setting/ display	Description
1	PV Hold Value	Display	Displays the PV hold value.
2	°C / °F	Display	Displays the temperature unit.
3	Display Update Indicator	Display	The PV hold value is continuously displayed and updated. This indicator flashes each time the data is updated.

- When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- Do not use this SMART Active Part on the initial screen.
- Use System version 5 or higher version.

(5) SP Setting

Setting level	Input type	Channel	Part
Operation level	Thermocouple input	CH1	Yes
		CH2	Yes
		All CH	No
	Platinum-resistance thermometer	CH1	Yes
		CH2	Yes
		All CH	No

Unit type	E5ZN	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5ZN\OperationLe vel	Title	SP Setting
Function	Sets the set po	int.			
Display a	nd Operation De	tails			
		1	→ SP (°B) -999 ↑ 2	9	
No.		etting/ lisplay		Desc	cription
1	SP S	Setting Sets	the set point.		
2 Pamarka	(°C) / (°F)	Display Disp	lays the temperature unit		

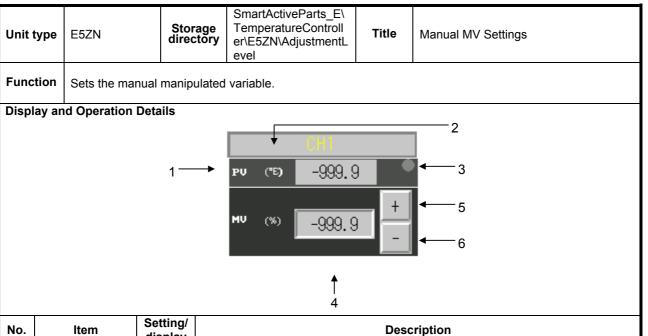
- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

1.1.2 Adjustment Level

(6) Manual MV Settings

There are different the SMART Active Parts for each channel and for Temperature Controllers with Pulse Outputs and Temperature Controllers with Analog Outputs. Be sure to use the correct SMART Active Part.

Setting level	Input type	Channel	Part
Adjustment level	Thermocouple input	CH1	Yes
		CH2	Yes
		All CH	No
	Platinum-resistance thermometer	CH1	Yes
		CH2	Yes
		All CH	No



No.	Item	display	Description
1	PV	Display	Displays the process value. The display is updated continuously.
2	(°C) / (°F)	Display	Displays the temperature unit.
3	Display Update Indicator	Display	Flashes each time the PV display is updated.
4	MV	Setting	Sets the manual manipulated variable.
5	A	Setting	Increments the manual manipulated variable by one engineering unit.
6	▼	Setting	Decrements the manual manipulated variable by one engineering unit.

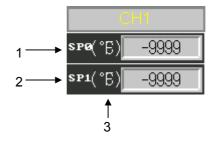
- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

(7) Multi-SP Settings

Setting level	Input type	Channel	Part
Adjustment level	Thermocouple input	CH1	Yes
		CH2	Yes
		All CH	No
	Platinum-resistance thermometer	CH1	Yes
		CH2	Yes
		All CH	No

Unit type	E5ZN	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5ZN\AdjustmentL evel	Title	Multi-SP Settings
Function	Sets set points 0	and 1.			

Display and Operation Details



No.	Item	Setting/ display	Description
1	SP0	Setting	Sets set point 0.
2	SP1	Setting	Sets set point 1.
3	(°C) / (°F)	Display	Displays the temperature unit.

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- Use System version 5 or higher version.

(8) Heater Burnout Detection

Setting level	Setting level Input type		Part
Adjustment level	Thermocouple input	CH1	Yes
	Platinum-resistance thermometer	CH2	Yes
	Common (Common)	All CH	No

Unit type	E5ZN	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5ZN\AdjustmentL evel	Title	Heater Burnout Detection	
Function	is used for Temp Heater burnout d	erature Confletection will	current and sets the heate trollers with Pulse Output function when the HBA U MART Active Part in the a	s. Jsed parar		
Display an	Display and Operation Details					



No.	Item	Setting/ display	Description		
1	Heater Current Val	Display	Continuously displays the heater current.		
2	HB	Display	Continuously displays the output status for heater burnout detection.		
3	Heater Burnout Detection	Setting	Sets the heater burnout detection value.		
4	HBA Used	Display	Displays the setting status (advanced function setting level) for heater burnout detection.		
5	Display Update Indicator	Display	Flashes each time the heater current or HB display is updated.		

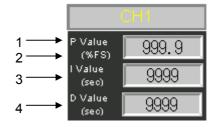
- When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the System Memory List Button on the Initial Tab Page, and select Basics for the \$SB.
- Do not use this SMART Active Part on the initial screen.
- Use System version 5 or higher version.

(9) PID Settings

Setting level	Input type	Channel	Part
Adjustment level	Thermocouple input	CH1	Yes
	Platinum-resistance thermometer	CH2	Yes
	Common(Common)	All CH	No

Unit type	E5ZN	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5ZN\AdjustmentL evel	Title	PID Settings
Function	Sets the PID con				

Display and Operation Details

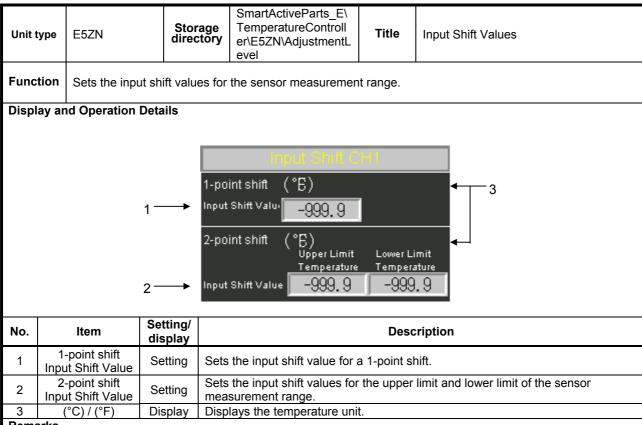


No.	Item	Setting/ display	Description
1	P Value	Setting	Sets the proportional band.
2	(°C) / (°F)	Display	Displays the temperature unit.
3	l Value	Setting	Sets the integral time.
4	D Value	Setting	Sets the derivative time.

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

(10) Input Shift Values

Setting level	Input type	Channel	Part
Adjustment level	Thermocouple input	CH1	Yes
	Platinum-resistance thermometer	CH2	Yes
	Common(Common)	All CH	No



- When using this SMART Active Part, be sure to select Setting System Settings in the menu bar, press the System Memory List Button on the Initial Tab Page, and select Basics for the \$SB.
- Do not use this SMART Active Part on the initial screen.
- Use System version 5 or higher version.

(11) Manual Reset Value

Setting level	Input type	Channel	Part
Adjustment level	Thermocouple input	CH1	Yes
	Platinum-resistance thermometer	CH2	Yes
	Common(Common)	All CH	No

Unit ty	ype E5ZN	Stora direct	SmartActiveParts_E\ TemperatureControll er\E5ZN\AdjustmentL evel	Title	Manual Reset Value	
Funct	Function Sets the manual reset value.					
Displa	Display and Operation Details					
No.	Item	Setting/ display		Desc	cription	
1	Manual Reset Value	Setting	Sets the manual reset value			
Rema	rks					

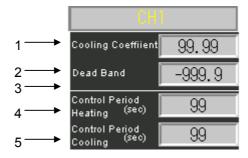
- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

(12) Cooling Coefficient, Dead Band, and Control Period

Setting level	Input type	Channel	Part
Adjustment level	Thermocouple input	CH1	Yes
	Platinum-resistance thermometer	CH2	Yes
	Common(Common)	All CH	No

Unit type	E5ZN	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5ZN\AdjustmentL evel	Title	Cooling Coefficient, Dead Band, and Control Period
Function	Sets the cooling	coefficient, d	ead band, and control pe	eriod.	

Display and Operation Details



No.	Item	Setting/ display	Description		
1	Cooling Coefficient	Setting	Sets the cooling coefficient for heating/cooling control.		
2	Dead Band	Setting	Sets the dead band for heating/cooling control.		
3	(°C) / (°F)	Display	Displays the temperature unit.		
4	Control Period Heating	Setting	Sets the control period for the heating output for heating/cooling control. Sets the control period for standard control.		
5	Control Period Cooling	Setting	Sets the control period for the cooling output for heating/cooling control.		

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- Use System version 5 or higher version.

(13) Dead Band and Hysteresis

Setting level	Input type	Channel	Part
Adjustment level	Thermocouple input	CH1	Yes
	Platinum-resistance thermometer	CH2	Yes
	Common(Common)	All CH	No

Unit t	type E5ZN	Stora direct	age tory	SmartActiveParts_E\ TemperatureControll er\E5ZN\AdjustmentL evel	Title	Dead Band and Hysteresis	
Func	Function Sets the dead band and hysteresis for ON/OFF control.						
Displ	ay and Operation	Details					
	Dead Band -999.9 Hysteresis Heating Hysteresis Cooling 999.9						
No.	Item	Setting/ display	Description				
1	Dead Band	Setting	Sets	the dead band.			
2	Hysteresis Heating	Setting	Sets the hysteresis for the heating output for heating/cooling control. Sets the hysteresis for standard control.				
3	Hysteresis Cooling	Setting	Sets	the hysteresis for the co	oling outpu	ut for heating/cooling control.	
4	(°C) / (°F)	Display	Displays the temperature unit.				

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

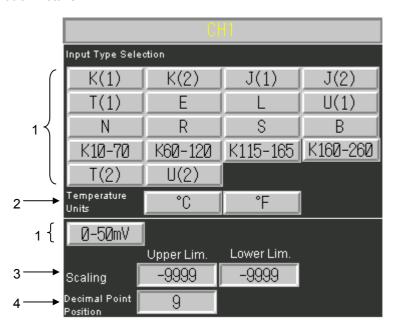
1.1.3 Initial Setting Level

(14) Input 1 Type, Temperature Unit, Scaling, and Decimal Point for Thermocouple Input

Setting level	Input type	Channel	Part
Initial setting level	Thermocouple input	CH1	Yes
-		CH2	Yes
		All CH	No
	Platinum-resistance thermometer	CH1	No
		CH2	No
		All CH	No

Unit type	E5ZN	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5ZN\InitialSetting Level	Title	Input 1 Type, Temperature Unit, Scaling, and Decimal Point
Function	Sets the input type and temperature unit for a Temperature Controller with a Thermocouple Input. When an analog input is selected, sets the scaling and decimal point position.				

Display and Operation Details



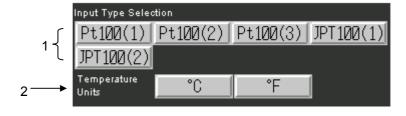
No.	Item	Setting/ display	Description
1	Input Type Selection	Setting	Sets the thermocouple input type. The same input type applies to both channels 1 and 2.
2	Temperature Units	Setting	Sets the temperature unit. The same temperature unit applies to both channels 1 and 2.
3	Scaling Upper Lim. Lower Lim.	Setting	When the input type is set to an analog input (0 to 50 mV), sets the upper and lower limits for scaling. The scaling upper/lower limit settings are made separately for channels 1 and 2.
4	Decimal Point Position	Setting	When the input type is set to an analog input (0 to 50 mV), sets the number of places below the decimal point. The decimal point setting is made separately for channels 1 and 2.

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- Use System version 5 or higher version.

(15) Input 1 Type and Temperature Unit (Platinum-resistance Thermometer)

Setting level	Input type	Channel	Part
Initial setting level	Thermocouple input	CH1	No
		CH2	No
		All CH	No
	Platinum-resistance thermometer	CH1	No
		CH2	No
		All CH	Yes

Unit type	E5ZN	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5ZN\InitialSetting Level	Title	Input 1 Type and Temperature Unit
Function	Sets the input type and temperature unit for a Temperature Controller with a Platinum-resistance Thermometer Input.				
Display and Operation Details					



No.	Item	Setting/ display	Description
1	Input Type Selection	Setting	Sets the input type for a Temperature Controller with a Platinum-resistance Thermometer Input.
2	Temperature Units	Setting	Sets the temperature unit.

- When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the System Memory List Button on the Initial Tab Page, and select Basics for the \$SB.
- Do not use this SMART Active Part on the initial screen.
- Use System version 5 or higher version.

(16) SP Limits

Setting level	Input type	Channel	Part
Initial setting level	Thermocouple input	CH1	Yes
		CH2	Yes
		All CH	No
	Platinum-resistance thermometer	CH1	Yes
		CH2	Yes
		All CH	No

Unit type	E5ZN	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5ZN\InitialSetting Level	Title	SP Limits
Function	Sets the upper and lower limits for the set point.				

Display and Operation Details



No.	Item	Setting/ display	Description
1	SP Limit Upper Limit Lower Limit	Setting	Sets the upper and lower limits for the set point. Can be set anywhere within the input temperature setting range.
2	(°C) / (°F)	Display	Displays the temperature unit.

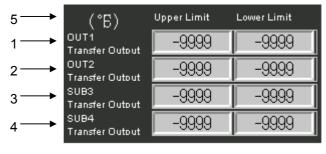
- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

Temperature Controller (E5ZN)

(17) Transfer Output Upper and Lower Limits

Setting level	Input type	Channel	Part
Initial setting level	Thermocouple input	CH1	No
		CH2	No
		All CH	Yes
	Platinum-resistance thermometer	CH1	No
		CH2	No
		All CH	Yes

Unit type	E5ZN	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5ZN\InitialSetting Level	Title	Transfer Output Upper and Lower Limits
Function	This setting is for a Temperature Controller with an Analog Output. This SMART Active Part sets the upper and lower limits of transfer outputs when transfer outputs are set for the control outputs or auxiliary outputs.				
Display and Operation Details					



No.	Item	Setting/ display	Description			
1	OUT1 Transfer Output Upper Limit Lower Limit	Setting	Sets the upper and lower limits for scaling when a transfer output is set for control output 1 (OUT1).			
2	OUT2 Transfer Output Upper Limit Lower Limit	Setting	Sets the upper and lower limits for scaling when a transfer output is set for control output 2 (OUT2).			
3	SUB3 Transfer Output Upper Limit Lower Limit	Setting	Sets the upper and lower limits for scaling when a transfer output is set for auxiliary output 3 (SUB3).			
4	SUB4 Transfer Output Upper Limit Lower Limit	Setting	Sets the upper and lower limits for scaling when a transfer output is set for auxiliary output 4 (SUB4).			

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

(18) PID or ON/OFF Control

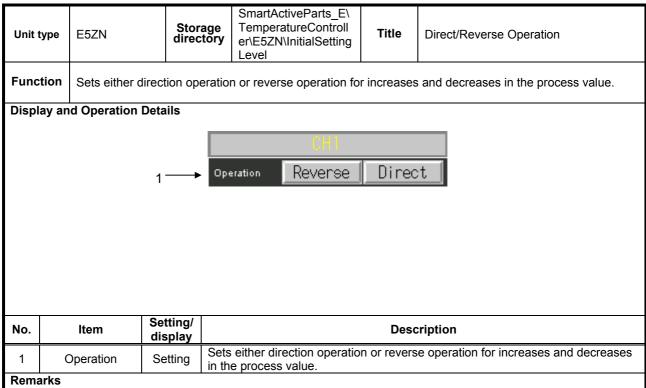
Setting level	Input type	Channel	Part
Initial setting level	Thermocouple input	CH1	Yes
	Platinum-resistance thermometer	CH2	Yes
	Common(Common)	All CH	No

No.	Item Control System	display Setting	Sets either PID or ON/OFF of	ontrol.	
No.	Item	display			
	_	Setting/		Desc	cription
		1	Control ON/OFF	PID	
			CH1		
Displ	ay and Operation	Details			
Func	Sets either F	PID or ON/O	FF control.		
Unit	type E5ZN	Stora direct	SmartActiveParts_E\ TemperatureControll er\E5ZN\InitialSetting Level	Title	PID or ON/OFF Control

- **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB. Do not use this SMART Active Part on the initial screen.
- Use System version 5 or higher version.

(19) Direct/Reverse Operation

Setting level	Input type	Channel	Part
	Thermocouple input	CH1	Yes
	Platinum-resistance thermometer	CH2	Yes
	Common(Common)	All CH	No



- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

(20) Alarm 1 Type, Alarm 1 Open/Close in Alarm, Alarm 1 Hysteresis, Alarm 1 Latch

Setting level	Input type	Channel	Part
Initial setting level	Thermocouple input	CH1	Yes
	Platinum-resistance thermometer	CH2	Yes
	Common(Common)	All CH	No

Unit type	E5ZN	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5ZN\InitialSetting Level	Title	Alarm 1 Type, Open/Close in Alarm, Hysteresis, Latch
Function	Sets the alarm ty	pe, open/clo	se in alarm operation,	latch, and hy	rsteresis for alarm 1.
Display an	nd Operation Deta	nils			
			CH1		
	1 -	→ Alarm	1 Туре 99	Туре(0-	<u>√</u> 2
	3-		1open/ in Alarm Close	0pen	
	4-	Alarm Hyster	1 esis(%) 999.9		
	5-	Alarm	1 Latch OFF	ON	

No.	Item	Setting/ display	Description	
1	Alarm 1 Type	Display	Displays the alarm type that is set.	
2	Alarm 1 Type Setting Button	Setting	When pressed, displays the alarm type setting menu. Select the alarm type from the menu.	
3	Alarm 1 open/close in Alarm	Setting	Sets open in alarm or close in alarm for the alarm output.	
4	Alarm 1 Hysteresis	Setting Display	Sets ON/OFF hysteresis for the alarm output.	
5	Alarm 1 Latch	Setting	Sets whether to latch the alarm output status.	

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

(21) Alarm 2 Type, Alarm 2 Open/Close in Alarm, Alarm 2 Hysteresis, Alarm 2 Latch

Setting level	Input type	Channel	Part
Initial setting level	Thermocouple input	CH1	Yes
	Platinum-resistance thermometer	CH2	Yes
	Common(Common)	All CH	No

Unit t	it type E5ZN Storag directo		age Temp	ActiveParts_E\ eratureControll ZN\InitialSetting	Title	Alarm 2 Type, Open/Close in Alarm, Hysteresis, Latch	
Function Sets the alarm type, open/close in alarm operation, latch, and hysteresis for alarm 2.							
Displ	ay and Operation	Details					
				CH1			
		1 →	Alarm2 Type	99	Гуре(0-)	<u>11)</u> ← 2	
			Alarm2 open/ close in Alarm	Close	0pen		
	Alarm2 (%) 999 9						
	5 —— Alarm2 Latch OFF ON						
		,					
No.	Item	Setting/ display			Desc	cription	
1	Alarm 2 Type	Display	Displays the	e alarm type that i	s set.		
2	Alarm 2 Type Setting Button	Setting	When pressed, displays the alarm type setting menu. Select the alarm type from the menu.				
3	Alarm 2 open/close in Alarm	Setting	Sets open in alarm or close in alarm for the alarm output.				
4	Alarm 2 Hysteresis	Setting Display	Sets ON/OFF hysteresis for the alarm output. Displays the temperature unit.				
5	Alarm 2 Latch	Setting		er to latch the ala		status.	
_	Remarks						

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- Use System version 5 or higher version.

(22) Alarm 3 Type, Alarm 3 Open/Close in Alarm, Alarm 3 Hysteresis, Alarm 3 Latch

Setting level	Input type	Channel	Part
Initial setting level	Thermocouple input	CH1	Yes
	Platinum-resistance thermometer	CH2	Yes
	Common(Common)	All CH	No

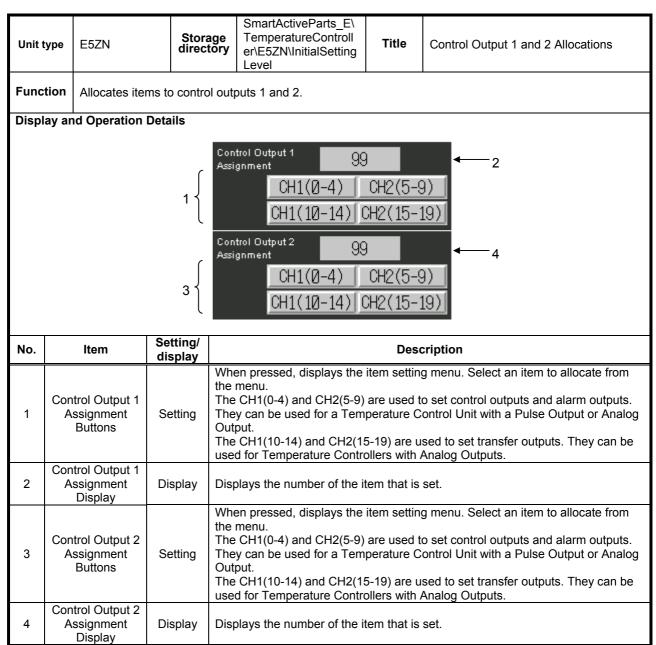
Unit type	E5ZN	Storage directory	Temp	ActiveParts_E\ eratureControll ZN\InitialSetting	Title	Alarm 3 Type, Open/Close in Alarm, Hysteresis, Latch
Function	Sets the alarm ty	/pe, open/clo	ose in al	arm operation, la	atch, and hy	steresis for alarm 3.
Display an	d Operation Deta	ails				
				CH1		
	1-	Alarm	З Туре	99	Туре(0-1	<u>√</u> 2
	3-		3 open/ in Alarm	Close	0pen	
	4-					
	5-	Alarm	3 Latch	OFF	ON	
 	So	tting/				

No.	Item	Setting/ display	Description
1	Alarm 3 Type	Display	Displays the alarm type that is set.
2	Alarm 3 Type Setting Button	Setting	When pressed, displays the alarm type setting menu. Select the alarm type from the menu.
3	Alarm 3 open/close in Alarm	Setting	Sets open in alarm or close in alarm for the alarm output.
4	Alarm 3 Hysteresis	Setting Display	Sets ON/OFF hysteresis for the alarm output. Displays the temperature unit.
5	Alarm 3 Latch	Setting	Sets whether to latch the alarm output status.

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

(23) Control Output 1 and 2 Allocations

Setting level	Input type	Channel	Part
			No
	Platinum-resistance thermometer	CH2	No
	Common(Common)	All CH	Yes



- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- Use System version 5 or higher version.

(24) Auxiliary Output 1 and 2 Allocations

Setting level	Input type	Channel	Part
Initial setting level	Thermocouple input	CH1	No
	Platinum-resistance thermometer	CH2	No
	Common(Common)	All CH	Yes

Unit type	E5ZN	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5ZN\InitialSetting Level	Title	Auxiliary Output 1 and 2 Allocations	
Function	It allocates items to auxiliary outputs 1 and 2.					
Display an	Display and Operation Details					
Auxiliary Output 1 99 1 {						

No.	Item	Setting/ display	Description
1	Auxiliary Output 1 Assignment Buttons	Setting	When pressed, displays the item setting menu. Select an item to allocate from the menu. The CH1(0-4) and CH2(5-9) are used to set control outputs and alarm outputs. They can be used for a Temperature Control Unit with a Pulse Output or Analog Output.
2	Auxiliary Output 1 Assignment Display	Display	Displays the number of the item that is set.
3	Auxiliary Output 2 Assignment Buttons	Setting	When pressed, displays the item setting menu. Select an item to allocate from the menu. The CH1(0-4) and CH2(5-9) are used to set control outputs and alarm outputs. They can be used for a Temperature Control Unit with a Pulse Output or Analog Output.
4	Auxiliary Output 2 Assignment Display	Display	Displays the number of the item that is set.

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

(25) Auxiliary Output 3 and 4 Allocations

Setting level	Input type	Channel	Part
	Thermocouple input	CH1	No
	Platinum-resistance thermometer Common(Common)	CH2	No
		All CH	Yes

Unit t	unco		age ctory	SmartActiveParts_E\ TemperatureControll er\E5ZN\InitialSetting Level	Title	Auxiliary Output 3 and 4 Allocations
Func				a Temperature Controlloutputs 3 and 4.	er with an a	Analog Output.
Displ	ay and Operation	Details				
Auxiliary Output 3 99 1 {					9) 9) 	
No.	Item	Setting/			Desc	ription
Auxiliary Output 1 3 Assignment Buttons When pressed, displays the item setting menu. Select an item to allocate from the menu. The CH1(0-4) and CH2(5-9) are used to set control outputs and alarm outputs They can be used for a Temperature Control Unit with a Pulse Output or Analo Output. The CH1(10-14) and CH2(15-19) are used to set transfer outputs. They can be					D 000	ription
1	3 Assignment	Setting	the n The They Outp The	nenu. CH1(0-4) and CH2(5-9) a can be used for a Temp ut. CH1(10-14) and CH2(15	tem setting are used to erature Co	menu. Select an item to allocate from set control outputs and alarm outputs. Ontrol Unit with a Pulse Output or Analog sed to set transfer outputs. They can be
1 2	3 Assignment		the n They Outp The used	nenu. CH1(0-4) and CH2(5-9) a can be used for a Temp ut.	iem setting are used to erature Co -19) are us llers with A	menu. Select an item to allocate from set control outputs and alarm outputs. Ontrol Unit with a Pulse Output or Analog sed to set transfer outputs. They can be analog Outputs.
	3 Assignment Buttons Auxiliary Output 3 Assignment	Setting	the n They Outp The used Disp Whe the n They Outp The	nenu. CH1(0-4) and CH2(5-9) are can be used for a Temporut. CH1(10-14) and CH2(15 for Temperature Controllays the number of the item pressed, displays the innenu. CH1(0-4) and CH2(5-9) are can be used for a Temporut.	iem setting are used to erature Co -19) are us llers with A em that is s em setting are used to erature Co	menu. Select an item to allocate from set control outputs and alarm outputs. Ontrol Unit with a Pulse Output or Analog sed to set transfer outputs. They can be unalog Outputs. Set. menu. Select an item to allocate from set control outputs and alarm outputs. Ontrol Unit with a Pulse Output or Analog sed to set transfer outputs. They can be

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

(26) Current/Voltage Output

Setting level	Input type	Channel	Part
Initial setting level	Thermocouple input	CH1	No
	Platinum-resistance thermometer	CH2	No
	Common(Common)	All CH	Yes

Unit type	E5ZN	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5ZN\InitialSetting Level	Title	Current/Voltage Output	
Function	and 4.	Sets the current output type for control outputs 1 and 2 and the voltage output type for auxiliary outputs 3				

Display and Operation Details

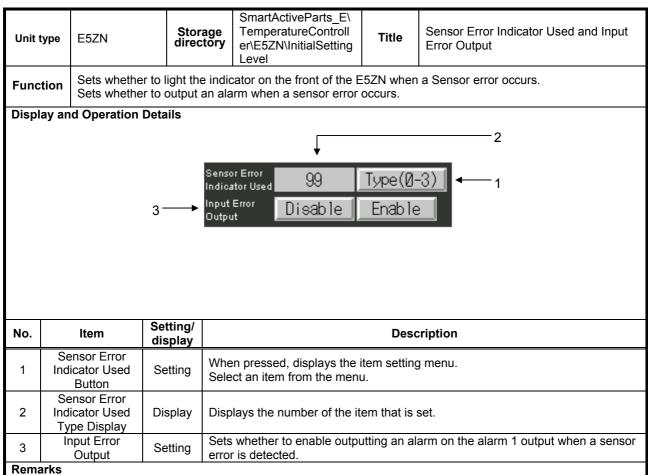


No.	Item	Setting/ display	Description
1	Current Output	Setting	Sets the current output type for control outputs 1 and 2.
2	Voltage Output	Setting	Sets the voltage output type for auxiliary outputs 3 and 4.

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

(27) Sensor Error Indicator Used and Input Error Output

Setting level	Input type	Channel	Part
Initial setting level	Thermocouple input	CH1	No
	Platinum-resistance thermometer	CH2	No
	Common(Common)	All CH	Yes



- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- Use System version 5 or higher version.

(28) Operation after Power ON

Setting level	Input type	Channel	Part
Initial setting level	Thermocouple input	CH1	No
	Platinum-resistance thermometer	CH2	No
	Common(Common)	All CH	Yes

Unit type	E5ZN	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5ZN\InitialSetting Level	Title	Operation after Power ON	
Function	Sets the operating	Sets the operating status to used after the power supply is turned ON.				

Display and Operation Details



No.	Item	Setting/ display	Description
1	Operation at Power ON	Setting	Set STOP to stop the control operation after the power supply is turned ON. Set CONTINUE to continue the operating status that existed when the power supply was turned OFF.

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

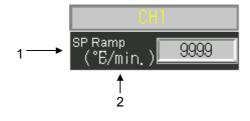
1.1.4 Advanced Function Setting Level

(29) SP Ramp

Setting level	Input type	Channel	Part
Advanced function setting level	Thermocouple input	CH1	No
_	Platinum-resistance	CH2	No
	thermometer	All CH	Yes
	Common(Common)		

Unit type	E5ZN	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5ZN\Advanced_L evel	Title	SP Ramp
Function	Sets the rate of change for the SP ramp.				

Display and Operation Details



No.	Item	Setting/ display	Description
1	SP Ramp	Setting	Sets the maximum allowed change per minute. Set 0 to disable the SP ramp function.
2	(°C /min)/(°F/min)	Display	Displays the temperature unit.

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

(30) HBA Used, Heater Burnout Latch, Heater Burnout Hysteresis

Setting level	Input type	Channel	Part
Advanced function setting level	Thermocouple input	CH1	No
	Platinum-resistance thermometer	CH2	No
	Common(Common)	All CH	Yes

Unit type	E5ZN	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5ZN\Advanced_L evel	Title	HBA Used, Latch, Hysteresis
Function	Turns the heater burnout detection ON/OFF, turns the latch ON/OFF, and sets the hysteresis.				

Display and Operation Details



No.	Item	Setting/ display	Description
1	Use Heater Burnout	Setting	Sets whether to use the heater burnout detection function.
2	Heater Burnout Latch	Setting	Sets whether to latch the heater burnout alarm.
3	Heater Burnout Hysteresis	Setting	Sets the hysteresis for heater burnout detection.

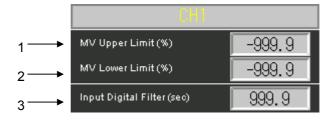
- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

(31) MV Upper/Lower Limits and Input Digital Filter

Setting level	Input type	Channel	Part
Advanced function setting level	Thermocouple input	CH1	No
	Platinum-resistance thermometer	CH2	No
	Common(Common)	All CH	Yes

Unit type	E5ZN	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5ZN\Advanced_L evel	Title	MV Upper/Lower Limits and Input Digital Filter
Function	Sate the upper and lawer limits for the manipulated variable				

Display and Operation Details



No.	Item	Setting/ display	Description
1	MV Upper Limit	Setting	Sets the upper limit of the manipulated variable. If the calculated manipulated variable exceeds the upper limit, it will be restricted to the upper limit.
2	MV Lower Limit	Setting	Sets the lower limit of the manipulated variable. If the calculated manipulated variable falls below the lower limit, it will be restricted to the lower limit.
3	Input Digital Filter	Setting	Sets the time constant for the input digital filter.

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- Use System version 5 or higher version.

(32) Input Shift Type

Setting level	Input type	Channel	Part
Advanced function setting level			No
	Platinum-resistance thermometer	CH2	No
	Common(Common)	All CH	Yes

Unit t	type E5ZN	Storage director	SmartActiveParts_E\ TemperatureControll er\E5ZN\Advanced_L evel	Title	Input Shift Type				
Func	Function Sets the input shift type to a 1-point shift or to a 2-point shift.								
Displa	ay and Operation	n Details							
	1—— Input Shift Type 1-point shift 2-point shift								
No.	Item	Setting/ display		Desc	cription				
1	1 Input Shift Type Setting Sets the input shift type to a 1-point shift or to a 2-point shift.								
	Vhen using this SM		art, be sure to select Settin		n Settings in the menu bar, press the				

- **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB. Do not use this SMART Active Part on the initial screen.
- Use System version 5 or higher version.

Temperature Controller (E5ZN)

(33) Number of Multi-SP Uses, Event Input Allocation, Use Multi-SP

Setting level	Input type	Channel	Part
Advanced function setting level	Thermocouple input	CH1	No
	Platinum-resistance thermometer	CH2	No
	Common(Common)	All CH	Yes

Unit type	E5ZN	Storage directory	Temp	ActiveParts_E\ eratureControll ZN\Advanced_L	Title	Number of Multi-SP Uses, Event Input Allocation, Use Multi-SP			
Function	Function Sets the number of Multi-SP uses, event input allocation, and multi-SP usage.								
Display an	d Operation Deta	iils							
	1 -	No. of SP Us	f Multi- ses	No Multi-SP	Switch between S				
	2-	Event	Input ion	Non	RUN/S1	TOP			
	3-	→ Use Multi-	SP	OFF	ON				

No.	Item	Setting/ display	Description	
1	No. of Multi-SP Uses	Setting	Sets the number of multi-SP set point to use for the event inputs.	
2	Event Input Function	Setting	Sets whether to switch between RUN and STOP for the event input.	
3	Use Multi-SP	Setting	Turned ON to enable switching between SP0 and SP1.	

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

(34) Standby Sequence Restart

Setting level	Input type	Channel	Part
Advanced function setting level	Thermocouple input	CH1	No
	Platinum-resistance thermometer	CH2	No
	Common(Common)	All CH	Yes

Unit type	E5ZN	Storage directory	TemperatureControll er\E5ZN\Advanced_L evel	Title	Standby Sequence Restart
Function	Sets the conditio	n for restarti	ng after clearing the aları	m standby	sequence.
Display an	d Operation Deta	ails			
	1 -	Stand Reset	Condi.A	Condi	.B

No.	Item	Setting/ display	Description
1	Standby Sequer Reset	Setting	Select Condition A or Condition B.

Remarks

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

Temperature Controller (E5ZN)

(35) α

Setting level	Input type	Channel	Part
Advanced function setting level	Thermocouple input	CH1	No
	Platinum-resistance thermometer	CH2	No
	Common(Common)	All CH	Yes

Unit typ	e E5ZN	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5ZN\Advanced_L evel	Title	Alpha		
Functio	Sets the α cons	Sets the α constant for advanced PID control.					
Display	and Operation De	tails					
	1	α	9.99				
No.		etting/		Desc	cription		
1		isplay Setting Set	s alpha set value.				
Remark		, o.u.i.g	o dipila cot falac.				

- When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- Do not use this SMART Active Part on the initial screen.
- Use System version 5 or higher version.

(36) Cold Junction Compensation Method

Setting level	Input type	Channel	Part
Advanced function setting level	Thermocouple input	CH1	No
	Platinum-resistance thermometer	CH2	No
	Common(Common)	All CH	Yes

Unit type	E5ZN	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5ZN\Advanced_L evel	Title	Cold Junction Compensation Method
Function	Sets the cold junc	tion compen	sation method.		
Display and	Display and Operation Details				



No.	Item	Setting/ display	Description
1	Cold Junction Compensation	Setting	Set whether to perform cold junction compensation inside the Temperature Controller or externally.

Remarks

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- Use System version 5 or higher version.

Temperature Controller (E5ZN)

1.1.5 Communications Setting Level

(37) Communications Settings

Setting level	Input type	Channel	Part
Communications setting level	Thermocouple input	CH1	No
	Platinum-resistance thermometer	CH2	No
	Common(Common)	All CH	Yes

Unit type	E5ZN	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5ZN\Comm_Set_ Level	Title	Communications Settings
Function	length: 7 bits, St	ttings are use op bits: 2 bits	ed when connecting an N s, Parity: even.		PT to the Temperature Controller: Data nunicate with any other settings.

Display and Operation Details



		Setting/	-		
No.	Item	display	Description		
1	Data Bit	Setting	Sets the communications data length. A data length of 7 bits is used to connect an NS-series PT to the Temperature Controller.		
2	Stop Bit	Setting	Sets the number of communications stop bits. Two stop bits are used to connect an NS-series PT to the Temperature Controller.		
3	Parity	Setting	Sets the communications parity. Even parity is used to connect an NS-series PT to the Temperature Controller.		
4	Transmission Wait Time	Setting	Sets the communications response wait time.		

- * The communications unit number and communications baud rate are set on the rotary switches on the front panel of the Temperature Controller.
- * The PT and the Temperature Controller will not be able to communicate unless the following settings are used: Data length: 7 bits, Stop bits: 2 bits, Parity: even.
- * When using this SMART Active Part, be sure to select Setting System Settings in the menu bar, press the System Memory List Button on the Initial Tab Page, and select Basics for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.



The following table lists the SMART Active Parts for the E5AR/E5ER Temperature Controllers.

	CH1	le SMART Active Parts for the E5AR/E5ER Temperature Controllers.
controls	CH2	
CONTROIS	CH3	Bank Selection Bank Selection
	CH4	Bank Selection
O		
Operation level	CH1	Operation Monitor for Standard Control
		Operation Monitor for Heating/Cooling Control
		Operation Monitor for Position Proportional Control
		SP Setting
		Manual MV Setting
		Manual MV Settings for Position Proportional Control
	CH2	Operation Monitor for Standard Control
		Operation Monitor for Heating/Cooling Control
		SP Setting
		MV Manual Settings
	CH3	Operation Monitor for Standard Control
		SP Setting
		MV Manual Settings
	CH4	Operation Monitor for Standard Control
		SP Setting
		MV Manual Settings
Adjustment	CH1	Input Shift Values
level		SP Ramp
		Manual Reset Value
		MV Change Rate Limits
		Dead Band and Hysteresis
		MV at Stop and MV at PV Error
		Cooling Coefficient, Dead Band, and Control Period
		Disturbance Settings
	CH2	Input Shift Values
		SP Ramp
		Manual Reset Value
		MV Change Rate Limits
		Dead Band and Hysteresis
		MV at Stop and MV at PV Error
		Cooling Coefficient, Dead Band, and Control Period
		Disturbance Settings
	CH3	Input Shift Values
	0113	SP Ramp
		Manual Reset Value
		MV Change Rate Limits
		Dead Band and Hysteresis
		MV at Stop and MV at PV Error
		Cooling Coefficient, Dead Band, and Control Period
	0114	Disturbance Settings
	CH4	Input Shift Values
		SP Ramp
		Manual Reset Value
		MV Change Rate Limits
		Dead Band and Hysteresis
		MV at Stop and MV at PV Error
		Cooling Coefficient, Dead Band, and Control Period
		Disturbance Settings
Adjustment 2	Common	First Order Lag Operation, Move Average, and Extraction of Square Root Low-cut Point for 4 Point
level		First Order Lag Operation, Move Average, and Extraction of Square Root Low-cut Point for 2 Point
		First Order Lag Operation, Move Average, and Extraction of Square Root Low-cut Point for 1 Point
		Position Proportional Control Adjustment
		Analog Parameter Control Rate
	I	Analog i arameter control nate

Temperature Controller (E5□R)

CH1	LSP and Alarm Settings
OIII	LSP Setting
CH2	LSP and Alarm Settings
CITZ	LSP Setting
CH3	LSP and Alarm Settings
CHIS	LSP Setting
CHA	· · · · · · · · · · · · · · · · · · ·
CH4	LSP and Alarm Settings
CHI	LSP Setting
	PID Settings, MV Upper/Lower Limits, Automatic Selection Range Upper/Lower Limits
	PID Settings, MV Upper/Lower Limits, Automatic Selection Range Upper/Lower Limits
	PID Settings, MV Upper/Lower Limits, Automatic Selection Range Upper/Lower Limits
	PID Settings, MV Upper/Lower Limits, Automatic Selection Range Upper/Lower Limits
	Straight-line Approximation
channels	Broken-line Approximation (1 to 10)
	Broken-line Approximation (11 to 20)
	Remote SP Upper/Lower Limits
	Input 1 Type, Temperature Unit, Scaling, and Decimal Point
channels	Input 2 Type, Temperature Unit, Scaling, and Decimal Point
	Input 3 Type, Temperature Unit, Scaling, and Decimal Point
	Input 4 Type, Temperature Unit, Scaling, and Decimal Point
	Sensor Induction Noise Reduction
CH1	Forward/Reverse Operation
	SP Limits
CH2	Forward/Reverse Operation
	SP Limits
CH3	Forward/Reverse Operation
	SP Limits
CH4	Forward/Reverse Operation
	SP Limits
All	Output Types
channels	Control Mode
	Position Proportional Control Initial Settings and Extended Settings
All	Control/Transfer Output 1 and 2 Allocations
channels	Control/Transfer Output 3 and 4 Allocations
	Event Input 1 Allocation
	Event Input 2 Allocation
	Event Input 3 Allocation
	Event Input 4 Allocation
	I Event Input 5 Allocation
	Event Input 6 Allocation
	Event Input 6 Allocation
	Event Input 6 Allocation Auxiliary Output 1 Allocation
	Event Input 6 Allocation Auxiliary Output 1 Allocation Auxiliary Output 2 Allocation
	Event Input 6 Allocation Auxiliary Output 1 Allocation Auxiliary Output 2 Allocation Auxiliary Output 3 Allocation
	Event Input 6 Allocation Auxiliary Output 1 Allocation Auxiliary Output 2 Allocation Auxiliary Output 3 Allocation Auxiliary Output 4 Allocation
	Event Input 6 Allocation Auxiliary Output 1 Allocation Auxiliary Output 2 Allocation Auxiliary Output 3 Allocation Auxiliary Output 4 Allocation Transfer Output 1 Upper/Lower Limits
	Event Input 6 Allocation Auxiliary Output 1 Allocation Auxiliary Output 2 Allocation Auxiliary Output 3 Allocation Auxiliary Output 4 Allocation Transfer Output 1 Upper/Lower Limits Transfer Output 2 Upper/Lower Limits
	Event Input 6 Allocation Auxiliary Output 1 Allocation Auxiliary Output 2 Allocation Auxiliary Output 3 Allocation Auxiliary Output 4 Allocation Transfer Output 1 Upper/Lower Limits Transfer Output 2 Upper/Lower Limits Transfer Output 3 Upper/Lower Limits
	Event Input 6 Allocation Auxiliary Output 1 Allocation Auxiliary Output 2 Allocation Auxiliary Output 3 Allocation Auxiliary Output 4 Allocation Transfer Output 1 Upper/Lower Limits Transfer Output 2 Upper/Lower Limits Transfer Output 3 Upper/Lower Limits Transfer Output 4 Upper/Lower Limits Transfer Output 4 Upper/Lower Limits
	Event Input 6 Allocation Auxiliary Output 1 Allocation Auxiliary Output 2 Allocation Auxiliary Output 3 Allocation Auxiliary Output 4 Allocation Transfer Output 1 Upper/Lower Limits Transfer Output 2 Upper/Lower Limits Transfer Output 3 Upper/Lower Limits Transfer Output 4 Upper/Lower Limits Enable Settings for First Order Lag Operation, Move Average, and Extraction of
	Event Input 6 Allocation Auxiliary Output 1 Allocation Auxiliary Output 2 Allocation Auxiliary Output 3 Allocation Auxiliary Output 4 Allocation Transfer Output 1 Upper/Lower Limits Transfer Output 2 Upper/Lower Limits Transfer Output 3 Upper/Lower Limits Transfer Output 4 Upper/Lower Limits Enable Settings for First Order Lag Operation, Move Average, and Extraction of Square Root Low-cut Point for 4 Point
	Event Input 6 Allocation Auxiliary Output 1 Allocation Auxiliary Output 2 Allocation Auxiliary Output 3 Allocation Auxiliary Output 4 Allocation Transfer Output 1 Upper/Lower Limits Transfer Output 2 Upper/Lower Limits Transfer Output 3 Upper/Lower Limits Transfer Output 4 Upper/Lower Limits Transfer Output 4 Upper/Lower Limits Enable Settings for First Order Lag Operation, Move Average, and Extraction of Square Root Low-cut Point for 4 Point Enable Settings for First Order Lag Operation, Move Average, and Extraction of
	Event Input 6 Allocation Auxiliary Output 1 Allocation Auxiliary Output 2 Allocation Auxiliary Output 3 Allocation Auxiliary Output 4 Allocation Transfer Output 1 Upper/Lower Limits Transfer Output 2 Upper/Lower Limits Transfer Output 3 Upper/Lower Limits Transfer Output 4 Upper/Lower Limits Enable Settings for First Order Lag Operation, Move Average, and Extraction of Square Root Low-cut Point for 4 Point Enable Settings for First Order Lag Operation, Move Average, and Extraction of Square Root Low-cut Point for 2 Point
	Event Input 6 Allocation Auxiliary Output 1 Allocation Auxiliary Output 2 Allocation Auxiliary Output 3 Allocation Auxiliary Output 4 Allocation Transfer Output 1 Upper/Lower Limits Transfer Output 2 Upper/Lower Limits Transfer Output 3 Upper/Lower Limits Transfer Output 4 Upper/Lower Limits Transfer Output 4 Upper/Lower Limits Enable Settings for First Order Lag Operation, Move Average, and Extraction of Square Root Low-cut Point for 4 Point Enable Settings for First Order Lag Operation, Move Average, and Extraction of
	CH4 CH1 CH2 CH3 CH4 All channels CH1 CH2 CH3 CH4 All channels CH1 CH2 CH3 CH4 All channels CH1 CH2 CH3 CH4 All channels

te Judgment Deviation
Output Method, and MV
•
t Potentiometer Input Error,
e Judgment Deviation
Output Method, and MV
,
Input Error, and
e Judgment Deviation
Output Method, and MV
•
Input Error, and
e Judgment Deviation
Output Method, and MV
·
Input Error, and
•
•

1. E5AR/E5ER

1.1 Operation Controls

(1) Bank Selection

Setting level	Channel	Part
Operation level	CH1	Yes
	CH2	Yes
	CH3	Yes
	CH4	Yes
İ	All CH	No

- System Memory List Button on the Initial Tab Page, and select Basics for the \$SB.
- Do not use this SMART Active Part on the initial screen.
- Use System version 5 or higher version.

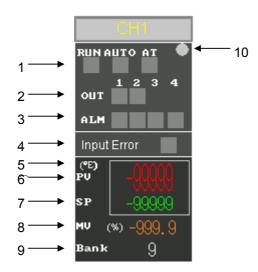
1.2 Operation Level

(2) Operation Monitor for Standard Control

Setting level	Channel	Part
Operation Level	CH1	Yes
	CH2	Yes
	CH3	Yes
	CH4	Yes
	All CH	No

Unit type	E5AR/E5ER	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5[]R\	Title	Operation Monitor for Standard Control
Function	Continuously monitors operating status on a face plate.				

Display and Operation Details



No.	Item	Setting/ display	Description		
1	RUN AUTO	Display	Displays the run/stop, auto/manual, and autotuning status.		
	AT				
2	OUT	Display	Displays the output status of control outputs 1 and 2.		
3	ALM	Displays the output status of alarm outputs 1, 2, 3, and 4.			
4	Input Error	Display	Displays the input error status.		
5	(°C) / (°F)	Displays the temperature unit.			
6	PV	Display	Displays the process value.		
7	SP	Display	Displays the set point.		
8	MV	Display	Displays the manipulated variable.		
9	Bank	Display	Display Displays the bank number.		
10	Display Update Indicator	Display	Flashes each time the display is updated.		

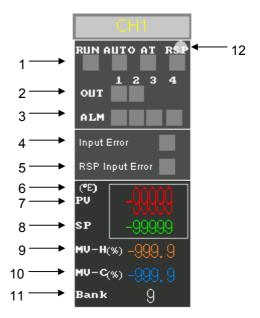
- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

(3) Operation Monitor for Heating/Cooling Control

Setting level	Channel	Part
Operation Level	CH1	Yes
	CH2	Yes
	CH3	No
	CH4	No
	All CH	No

Unit type	E5AR/E5ER	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5[]R\	Title	Operation Monitor for Heating/Cooling Control
Function	Continuously monitors operating status on a face plate.				

Display and Operation Details



No.	Item	Setting/ display	Describuon		
1	RUN AUTO AT RSP	Display	Displays the run/stop, auto/manual, autotuning, and remote SP status.		
2	OUT	Display	Displays the output status of control outputs 1 and 2.		
3	ALM	Displays the output status of alarm outputs 1, 2, 3, and 4.			
4	Input Error	Display	Displays the input error status.		
5	RSP Input Error	Display	Displays the RSP input error status.		
6	(°C) / (°F)	Display Displays the temperature unit.			
7	PV	Display	Displays the process value.		
8	SP	Display	Displays the set point.		
9	MV-H	Display	Displays the manipulated variable for heating.		
10	MV-C	Display Displays the manipulated variable for cooling.			
11	Bank	Display	Display Displays the bank number.		
12	Display Update Indicator	Display	y Flashes each time the display is updated.		

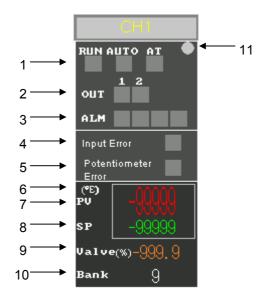
- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

(4) Operation Monitor for Position Proportional Control

Setting level	Channel	Part
Operation Level	CH1	Yes
	CH2	No
	CH3	No
	CH4	No
	All CH	No

Unit type	E5AR/E5ER	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5[]R\	Title	Operation Monitor for Position Proportional Control
Function	Continuously monitors operating status on a face plate. The face plate is for position proportional control.				

Display and Operation Details



No.	Item	Setting/ display	Description		
	RUN				
1	AUTO	Display	Displays the run/stop, auto/manual, and autotuning status.		
	AT				
2	OUT	Display	Displays the output status of control outputs 1 and 2.		
3	ALM	Display	Displays the output status of alarm outputs 1, 2, and 3.		
4	Input Error	Display			
5	Potentiometer Error	Display			
6	(°C) / (°F)	Display	Displays the temperature unit.		
7	PV	Display	Displays the process value.		
8	SP	Display	Displays the set point.		
9	Valve	Display	Displays the percentage the valve is open.		
10	Bank	Display Displays the bank number.			
11	Display Update Indicator	Display	Flashes each time the display is updated.		

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

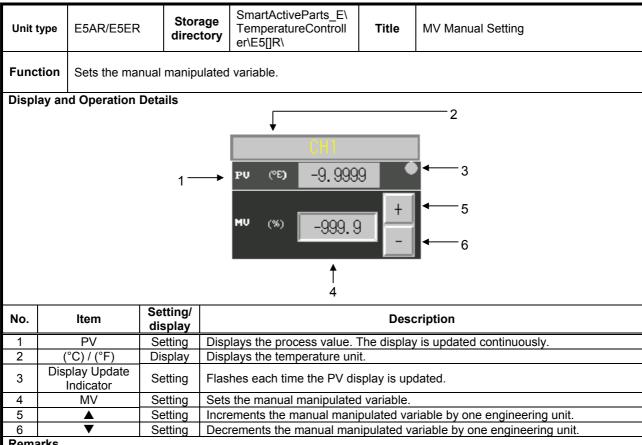
(5) SP Setting

Setting level	Channel	Part
Operation Level	CH1	Yes
	CH2	Yes
	CH3	Yes
	CH4	Yes
	All CH	No

- * When using this SMART Active Part, be sure to select Setting System Settings in the menu bar, press the System Memory List Button on the Initial Tab Page, and select Basics for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

(6) Manual MV Setting for Standard or Heating/Cooling Control

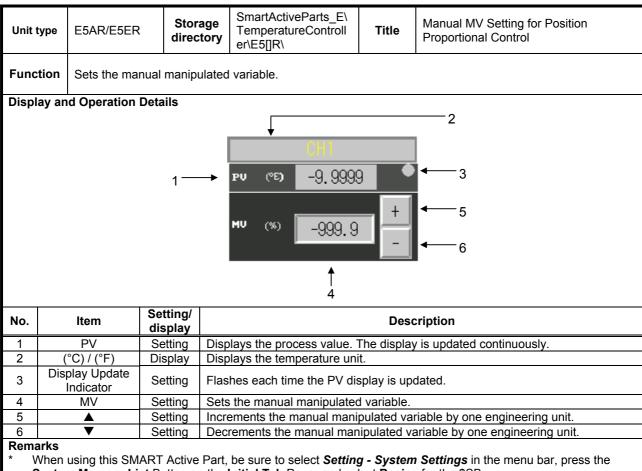
Setting level	Channel	Part
Operation Level	CH1	Yes
	CH2	Yes
	CH3	Yes
	CH4	Yes
	All CH	No



- When using this SMART Active Part, be sure to select Setting System Settings in the menu bar, press the System Memory List Button on the Initial Tab Page, and select Basics for the \$SB.
- Do not use this SMART Active Part on the initial screen.
- Use System version 5 or higher version.

(7) Manual MV Setting for Position Proportional Control

Setting level	Channel	Part
Operation Level	CH1	Yes
	CH2	No
	CH3	No
	CH4	No
	All CH	No

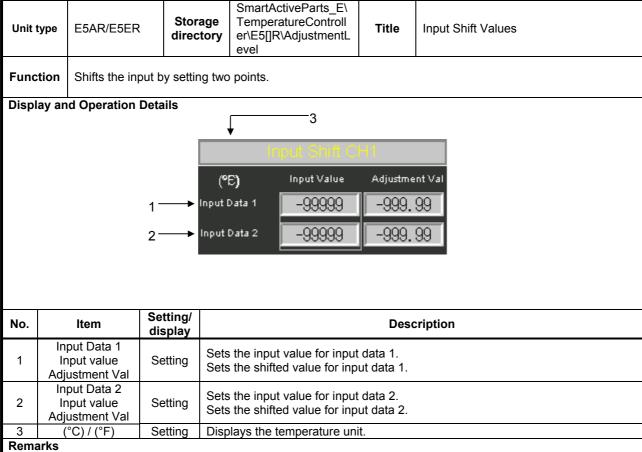


- System Memory List Button on the Initial Tab Page, and select Basics for the \$SB.
- Do not use this SMART Active Part on the initial screen.
- Use System version 5 or higher version.

1.1.2 Adjustment Level

(8) Input Shift Values

Setting level	Channel	Part
Adjustment level	CH1	Yes
	CH2	Yes
	CH3	Yes
	CH4	Yes
	All CH	No



- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

(9) SP Ramp Time Unit, SP Ramp Rise Value, and SP Ramp Fall Value

Setting level	Channel	Part
Adjustment level	CH1	Yes
	CH2	Yes
	CH3	Yes
	CH4	Yes
	All CH	No

Unit t	type E5AR/E5ER	Stor		SmartActiveParts_E\ TemperatureControll er\E5[]R\AdjustmentL evel	Title	SP Ramp
Func	Sets the SP ramp time unit, SP ramp rise value, and SP ramp fall value.					
Displa	ay and Operation	Details				
	SP Ramp Time Unit /min. /Hr SP Ramp Rise Value(op) SP Ramp Fall Value(op) 99999 99999					
No.	Item	Setting/ display			Desc	cription
1	SP Ramp Time Unit	P Ramp Time Setting Sets the time unit for the SP ramp settings				
2	SP Ramp Rise Value	· 1 Semino 1				
3	SP Ramp Fall Value	Ramp Fall Setting Sets the SP ramp fall value.				
	Vhen using this SM			be sure to select Setting		Settings in the menu bar, press the

- System Memory List Button on the Initial Tab Page, and select Basics for the \$SB.
- Do not use this SMART Active Part on the initial screen.
- Use System version 5 or higher version.

(10) Manual Reset Value

Setting level	Channel	Part
Adjustment level	CH1	Yes
	CH2	Yes
	CH3	Yes
	CH4	Yes
	All CH	No

Unit t	ype E5AR/E5ER	Stora direct		Title	Manual Reset Value
Funct	Function Sets the manual reset value.				
Displa	ay and Operation	Details			
	Manual Reset Val. 999.9				
No.	No. Item Setting/ Description				
1	1 Manual Reset Val. Setting Sets the manual reset value.				
Rema	ırks	<u></u>			

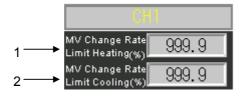
- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

(11) MV Change Rate Limits

Setting level	Channel	Part
Adjustment level	CH1	Yes
	CH2	Yes
	CH3	Yes
	CH4	Yes
	All CH	No

Unit type	E5AR/E5ER	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5[]R\AdjustmentL evel	Title	MV Change Rate Limits
Function	Function Sets the maximum allowed change widths in the manipulated variables per second.				

Display and Operation Details



No.	Item	Setting/ display	Description
1	MV Change Rate Limit Heating	Setting	Sets the maximum allowed change width in the heating manipulated variables per second for heating/cooling control. Sets the maximum allowed change width in the manipulated variables per second for standard control. Set 0.0 to disable this function.
2	MV Change Rate Limit Heating	Setting	Sets the maximum allowed change width in the cooling manipulated variables per second for heating/cooling control. Set 0.0 to disable this function.

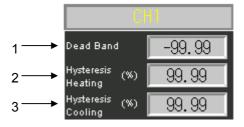
- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

(12) Dead Band and Hysteresis

Setting level	Channel	Part
Adjustment level	CH1	Yes
	CH2	Yes
	CH3	Yes
	CH4	Yes
	All CH	No

Unit type	E5AR/E5ER	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5[]R\AdjustmentL evel	Title	Dead Band and Hysteresis	
Function	nction Sets the dead band and hysteresis for ON/OFF control.					

Display and Operation Details



No.	Item	Setting/d isplay	Description
1	Dead Band	Setting	Sets the dead band.
2	Hysteresis Heating	Setting	Sets the hysteresis for the heating output for heating/cooling control. Sets the hysteresis for standard control.
3	Hysteresis Cooling	Setting	Sets the hysteresis for the cooling output for heating/cooling control.

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

(13) MV at Stop and MV at PV Error

Setting level	Channel	Part
Adjustment level	CH1	Yes
	CH2	Yes
	CH3	Yes
	CH4	Yes
	All CH	No

Unit type	E5AR/E5ER	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5[]R\AdjustmentL evel	Title	MV at Stop and MV at PV Error
Function	Sets the MV for when the control operation is stopped and the MV for when a PV or remote SP input error occurs.				

Display and Operation Details



No.	Item	Setting/ display	Description
1	MV at Stop	Setting	Sets the manipulated variable when the control operation stops.
2	MV at PV Error	Setting	Sets the MV for when a PV or remote SP input error occurs.

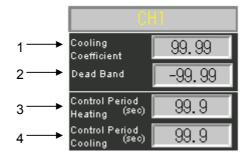
- When using this SMART Active Part, be sure to select Setting System Settings in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB. Do not use this SMART Active Part on the initial screen.
- Use System version 5 or higher version.

(14) Cooling Coefficient, Dead Band, and Control Period

Setting level	Channel	Part
Adjustment level	CH1	Yes
	CH2	Yes
	CH3	Yes
	CH4	Yes
	All CH	No

Unit type	E5AR/E5ER	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5[]R\AdjustmentL evel	Title	Cooling Coefficient, Dead Band, and Control Period	
Function	Function Sets the cooling coefficient, dead band, and control period.					

Display and Operation Details



No.	Item	Setting/ display	Description
1	Cooling Coefficient	Setting	Sets the cooling coefficient for heating/cooling control.
2	Dead Band	Setting	Sets the dead band for heating/cooling control.
3	Control Period Heating	Setting	Sets the control period for the heating output for heating/cooling control. Sets the control period for standard control.
4	Control Period Cooling	Setting	Sets the control period for the cooling output for heating/cooling control.

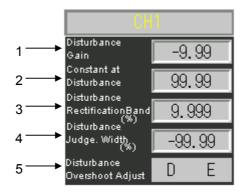
- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- Use System version 5 or higher version.

(15) Disturbance Gain, Constant at Disturbance, Disturbance Rectification Band, Disturbance Judgment Width, and Disturbance Overshoot Adjustment

Setting level	Channel	Part
Adjustment level	CH1	Yes
	CH2	Yes
	CH3	Yes
	CH4	Yes
	All CH	No

Unit type	E5AR/E5ER	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5[]R\AdjustmentL evel	Title	Disturbance Settings
Function	Sets adjustments for disturbance. These settings are valid when the disturbance overshoot adjustment function has been enabled. The disturbance overshoot adjustment function is enabled in the Extended control setting level.				

Display and Operation Details



No.	Item	Setting/ display	Description
1	Disturbance Gain	Setting	Sets the disturbance gain.
2	Constant at Disturbance	Setting	Sets the time constant for disturbance.
3	Disturbance Rectification Band	Setting	Sets the disturbance rectification band.
4	Disturbance Judge. Width	Setting	Sets the judgment width for disturbance.
5	Disturbance Overshoot Adjust	Display	Displays whether the disturbance overshoot adjustment function is enabled. Use a SMART Active Part in the Extended control setting level to make this setting.

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

1.1.3 Adjustment 2 Level

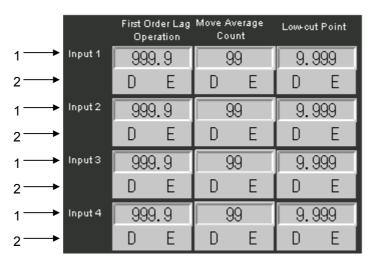
(16) First Order Lag Operation, Move Average, and Extraction of Square Root Low-cut Point

There are SMART Active Parts for 1 point, 2 points, and 4 points.

Setting level	Channel	Part
Adjustment level	CH1	No
	CH2	No
	CH3	No
	CH4	No
	All CH	Yes

Unit type	E5AR/E5ER	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5[]R\AdjustmentL evel	Title	First Order Lag Operation, Move Average, and Extraction of Square Root Low-cut Point for 4 Points
Function	Sets the first order lag operation, move average, and extraction of square root low-cut point for inputs 1, 2, 3, and 4. This SMART Active Part will function when the first order lag operation, move averages, and extraction of				

Display and Operation Details



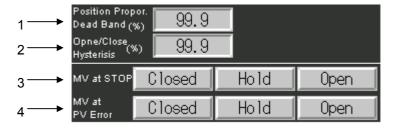
No.	Item	Setting/ display	Description
1	First Order Lag Operation, Move Average Counts, and Low-cut Points for Input 1, Input 2, Input 3, and Input 4	Setting	Sets the first order lag operation, move average count, and extraction of square root low-cut points for each input.
2	First Order Lag Operation, Move Average Counts, and Low-cut Points for Input 1, Input 2, Input 3, and Input 4 Enabled/Disabled Display	Display	Displays whether the first order lag operation, move average count, and extraction of square root low-cut point is enabled or disabled for each input. The settings to enable these functions are made with a SMART Active Part in the control initial setting level 2.

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

(17) Dead Band, Open/Close Hysteresis, MV at Stop, and MV at PV Error for Position Proportional Control

Setting level	Channel	Part
Adjustment level	CH1	No
	CH2	No
	CH3	No
	CH4	No
	All CH	Yes

Unit type	E5AR/E5ER	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5[]R\AdjustmentL evel	Title	Position Proportional Control Adjustment
Function	Sets the dead band, open/close hysteresis, MV at stop, and MV at PV error for position proportional control.				
Display and Operation Details					



No.	Item	Setting/ display	Description	
1	Position Propor. Dead Band	Setting	Sets the dead band for holding the output for position proportional control.	
2	Open/Close Hysteresis	Setting	Sets the open/close hysteresis for position proportional control.	
3	MV at Stop	Setting	Sets the MV to open, hold, or close for when operation stops.	
4	MV at PV Error	Setting	Sets the MV to open, hold, or close for when an error occurs.	

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- Use System version 5 or higher version.

(18) Analog Parameter Control Rate

Setting level	Channel	Part
Adjustment level	CH1	No
	CH2	No
	CH3	No
	CH4	No
	All CH	Yes

Unit type	E5AR/E5ER	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5[]R\AdjustmentL evel	Title	Analog Parameter Control Rate
Function	Sets the rate to u	use for propo	ortional control.		
Display an	d Operation Deta	ils			
		1	Analog Paramet 9.	999	

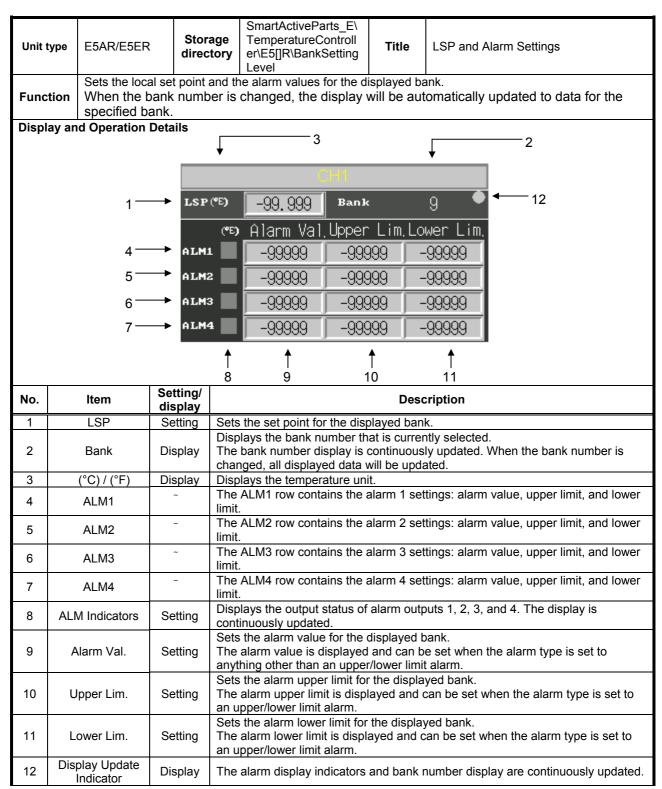
No.	Item	Setting/ display	Description	
1	Analog Paramet (Control Rate)	Setting	Sets the rate to use for proportional control.	

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

1.1.4 Bank Setting Level

(19) LSP and Alarm Settings

Setting level	Channel	Part
Bank setting level	CH1	Yes
	CH2	Yes
	CH3	Yes
	CH4	Yes
	All CH	No



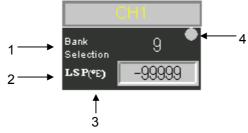
Remarks

- * When using this SMART Active Part, be sure to select Setting System Settings in the menu bar, press the System Memory List Button on the Initial Tab Page, and select Basics for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

(20) SP Setting

Setting level	Channel	Part
Bank setting level	CH1	Yes
	CH2	Yes
	CH3	Yes
	CH4	Yes
	All CH	No

Unit type	E5AR/E5ER	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5[]R\BankSetting Level	Title	LSP Setting		
Function	Sets the local set point for the displayed bank. When the bank number is changed, the LSP display will be automatically updated to data for the specified bank.						
Display and Operation Details							



No.	Item	Setting/ display	Description		
1	Bank Selection	Display	Displays the bank number that is currently selected.		
2	LSP	Setting	Sets the local set point for the displayed bank.		
3	(°C) / (°F)	Display	Displays the temperature unit.		
4	Display Update Indicator	Display	Flashes each time the display is updated. The display is periodically updated.		

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- Use System version 5 or higher version.

1.1.5 PID Setting Level

(21) PID Settings, MV Limits, Automatic Selection Range

Setting level	Channel	Part
PID setting level	CH1	Yes
	CH2	Yes
	CH3	Yes
	CH4	Yes
	All CH	No

Unit type	E5AR/E5ER	Storage directory	SmartActivePa TemperatureCo er\E5[]R\PIDSe evel	ontroll	Title	PID Settings, MV Limits, Automatic Selection Range				
Function		Sets parameters for PID control. When the PID set monitor number is changed, all displayed data will be updated.								
Display an	d Operation Deta	ails								
				CH1						
	1	PID Set Mon	itor g			8				
	2	P Value (%F	໑ 999.99	l Value	(sec) 9	999.9				
		D Value (sec	9999.9							
	3──	MV Upper	Limit (%)		-	999.9				
	4 →		Limit (%)		-	999.9				
	5──	Upper Limi		(°E)	-	99999				
	6→	Auomatic S Upper Limi	Selection Range t DV	(°E)	-	99999				
				↑						
				7						

No.	Item	Setting/ display	Description	
1	PID Set Monitor	Setting	Displays the PID set that has been selected.	
2	P Value I Value D Value	Setting	Sets the proportional band, integral time, and derivative time for the displayed PID set.	
3	MV Upper Limit	Setting	Sets the upper limit of the manipulated variable for the displayed PID set.	
4	MV Lower Limit	Setting	Sets the lower limit of the manipulated variable for the displayed PID set.	
5	Automatic Selection Range Upper Limit PV	Setting	Sets the upper limit of the selected by the displayed PID set.	
6	Automatic Selection Range Upper Limit DV	Setting	Sets the upper limit of the selected by the displayed PID set.	
7	(°C) / (°F)	Display	Displays the temperature unit.	
8	Display Update Indicator	Display	Flashes each time the PID set display is updated. When the PID set is changed, all displayed data will be updated.	

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

1.1.6 Approx_setting

(22) Straight-line Approximation

Setting level	Channe	l Part
Approx_setting	CH1	No
	CH2	No
	CH3	No
	CH4	No
	All CH	Yes

Unit t	type E5AR/E5E	Stor		Tempe er\E5[ActiveParts_E\ eratureControll R\Approx_setti	Title	Straight-line Approximation		
Func	Sets the characteristics for straight-line approximation. This SMART Active Part will function when the data is enabled. The settings to enable these functions are made with a SMART Active Part in the control initial setting level 2.								
Displ	Display and Operation Details								
			Stra	iight Lin	e Input	Output			
		4		rox. 1 ta 1	-9.999	-9.999			
		2		ta 2	-9.999	-9.999			
		2	Val	18 2					
		3			Disable	Enable	•		
				iight Lind rox.2	- Impar	Output	=		
		4		ta 1	-9.999	-9.999			
5			Dat	ta 2	-9.999	-9.999	1		
6→ Disable Enable									
No.	Item	Setting/ display				Desc	cription		
1	Straight-line Approx. 1 Data 1 Input Data 1 Output	Setting	Sets the input and output values for data 1 for straight-line approximation 1.						
2	Straight-line Approx. 1 Data 2 Input Data 2 Output	Setting	Sets	the inp	ut and output va	lues for dat	ta 2 for straight-line approximation 1.		
3	Straight-line Approx. 1 Enable/Disable Display	Display	Displays whether straight-line approximation 1 is enabled. The setting to enable this function is made with a SMART Active Part in the control initial setting level 2.						
4	Straight-line Approx. 2 Data 1 Input Data 1 Output	Setting	Sets the input and output values for data 1 for straight-line approximation 2.						
5	Straight-line Approx. 2 Data 2 Input Data 2 Output	Setting	Sets the input and output values for data 2 for straight-line approximation 2.						
6	Straight-line Approx. 2 Enable/Disable Display	Display	The	setting			nation 2 is enabled. ade with a SMART Active Part in the		

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- Use System version 5 or higher version.

(23) Broken-line Approximation (1 to 10)

Setting level	Channe	I Part
Approx_setting	CH1	No
	CH2	No
	CH3	No
	CH4	No
	All CH	Yes

Unit	type E5AR/E5ER	Storaç directo							
Func	Sets the characteristics for broken-line approximation. Up to 20 points can be set. Points 11 to 20 are set with a separate SMART Active Part. This SMART Active Part will function when the data is enabled.								
Displ	Display and Operation Details								
	Broken Line Approximation Data Input Output Data Input Output								
	1	→ Data	-9.999 -9.999 6 -9.999 -9.999 - 1						
	·								
			-9.999 -9.999 7 -9.999 -9.999						
		3	-9. 999 -9. 999 8 -9. 999 -9. 999						
		4	-9.999 -9.999 3 -9.999 -9.999						
		5	-9.999 -9.999 10 -9.999 -9.999						
		, <u>I</u>							
	2	→	Disable Enable						
No.	Item	Setting/	Description						
	Broken-line	display							
	Approximation Data 1								
	Broken-line								
	Approximation Data 2								
	Broken-line Approximation Data 3								
	Broken-line								
	Approximation Data 4								
	Broken-line								
	Approximation Data 5								
1	Broken-line Approximation Data 6	Setting	Set the input and output values for broken-line approximation data 1 to 10.						
	Broken-line	coung	cot the input and calput values for broken into approximation data. I to 10.						
	Approximation Data 7								
	Broken-line								
	Approximation Data 8 Broken-line								
	Approximation Data 9								
	Broken-line								
	Approximation Data								
	Approximation Data 10								
	Approximation Data 10 Input								
	Approximation Data 10		Displays whather healters line accessing the control of the contro						
2	Approximation Data 10 Input Output Broken-line Approximation	Display	Displays whether broken-line approximation is enabled. The setting to enable this function is made with a SMART Active Part in the						
2	Approximation Data 10 Input Output Broken-line	Display	Displays whether broken-line approximation is enabled. The setting to enable this function is made with a SMART Active Part in the control initial setting level 2.						

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- Use System version 5 or higher version.

(24) Broken-line Approximation (11 to 20)

Setting level	Channe	l Part
Approx_setting	CH1	No
	CH2	No
	CH3	No
	CH4	No
	All CH	Yes

Unit 1	type E5AR/E5ER	Storage directory er\Es		Title	Broken-line Approximation (11 to 20)			
	Function Sets the characteristics for broken-line approximation. Up to 20 points can be set. Points 1 to 10 are set with a separate SMART Active Part. This SMART Active Part will function when the data is enabled.							
Displ	Display and Operation Details							
	Broken Line Approximation Data Input Output 1							
No.	Item	Setting/ display		Des	scription			
1	Broken-line Approximation Data 11 Broken-line Approximation Data 12 Broken-line Approximation Data 13 Broken-line Approximation Data 14 Broken-line Approximation Data 15 Broken-line Approximation Data 16 Broken-line Approximation Data 17 Broken-line Approximation Data 17 Broken-line Approximation Data 18 Broken-line Approximation Data 18 Broken-line Approximation Data 19 Broken-line Approximation Data 20 Input Output	Setting	Set the input and output va	alues for br	oken-line approximation data 11 to 20.			
2	Broken Line Approximation Enable/Disable Display	Setting	Displays whether broken-line approximation is enabled. The setting to enable this function is made with a SMART Active Part in the control initial setting level 2.					

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

1.1.7 Input Initial Setting Level

(25) Remote SP Upper/Lower Limits

Setting level	Channe	l Part
Input initial setting level	CH1	Yes
	CH2	Yes
	CH3	Yes
	CH4	Yes
	All CH	No

Unit type	E5AR/E5ER	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5[]R\InputInitialS ettingLevel	Title	Remote SP Upper/Lower Limits
Function	Sets the upper and lower limits of the remote SP.				

Display and Operation Details



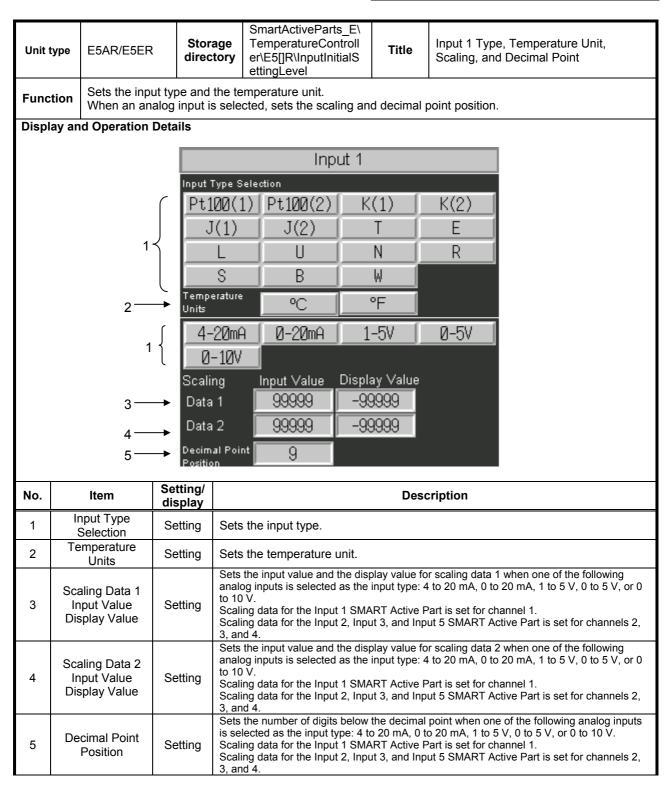
No.	Item	Setting/ display	Description
1	RSPH	Setting	Sets the upper limit of the input range for input 2.
2	RSPL	Setting	Sets the lower limit of the input range for input 2.

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

(26) Input 1 Type, Temperature Unit, Scaling, and Decimal Point

There are four different SMART Active Parts, one each for input 1, input 2, input 3, and input 4.

Setting level	Channel	Part
Input initial setting level	CH1	No
	CH2	No
	CH3	No
	CH4	No
	All CH	Yes



- When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB. Do not use this SMART Active Part on the initial screen.
- Use System version 5 or higher version.

(27) Sensor Induction Noise Reduction

Setting level	Channe	l Part
Input initial setting level	CH1	No
	CH2	No
	CH3	No
	CH4	No
	All CH	Yes

Unit type	E5AR/E5ER	Storage directory	TemperatureControll er\E5[]R\InputInitialS ettingLevel	Title	Sensor Induction Noise Reduction	
Function	Function Sets noise reduction of inductive noise from the power supply impressed on the input.					
Display an	d Operation Deta	ails				
		1	Sen.Induction Noise Reduct.			

No.	Item	Setting/ display	Description
1	Sensor Induction Noise Reduction	Setting	Sets 50 or 60 Hz.

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

1.1.8 Control Initial Setting Level

(28) Direct/Reverse Operation

Setting level	Channel	Part
Control initial setting level	CH1	Yes
	CH2	Yes
	CH3	Yes
	CH4	Yes
	All CH	No

Unit type	E5AR/E5ER	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5[]R\Controllnitial SettingLevel	Title	Direct/Reverse Operation	
Function Sets either direction operation or reverse operation for increases and decreases in the process value.						
Display ar	nd Operation De	tails				
			CH1			
1> Operation Reverse Direct						
					_	
	•	Satting/				
No.	Hem	Setting/		Desc	cription	

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

(29) SP Limits

Setting level	Channel	Part
Control initial setting level	CH1	Yes
	CH2	Yes
	CH3	Yes
	CH4	Yes
	All CH	No

Unit type	E5AR/E5ER	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5[]R\ControlInitial SettingLevel	Title	SP Limits	
Function						

Display and Operation Details



No.	Item	Setting/ display	Description
1	SP Limits Upper Limit Lower Limit	Setting	Sets the upper and lower limits for the set point. Can be set anywhere within the input temperature setting range.
2	(°C) / (°F)	Display	Displays the temperature unit.

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

(30) Closed/Floating, Travel Time, PV Dead Band, Operation at Potentiometer Input Error for Position Proportional Control

Setting level	Channel	Part
Control initial setting level	CH1	No
	CH2	No
	CH3	No
	CH4	No
	All CH	Yes

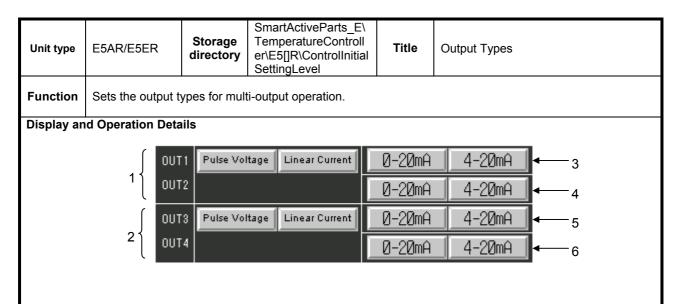
Unit type	E5AR/E5ER	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5[]R\ControlInitial SettingLevel	Title	Position Proportional Control Initial Settings and Extended Settings	
Function	Function Sets the control method and control parameters for position proportional control.					
Display an	Display and Operation Details					
	1 2 3 4 5	PV C	ting PLUHI	CLOSE 99 999 Enab 1		

No.	Item	Setting/ display	Description
1	Closed/Floating	Setting	Sets the control method for position proportional control.
2	Travel Time	Setting	Sets the time from a completely open valve to a completely closed valve.
3	PV Dead Band	Setting	Sets the process value dead band.
4	(°C) / (°F)	Display	Displays the temperature unit.
5	Operation at potentiometer input error	Setting	Sets the operation for when there is an input error for the potentiometer. Disable: Operation stopped. Enable: Operation continues.

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

(31) Output Types

Setting level	Channel	Part
Control initial setting level	CH1	No
	CH2	No
	CH3	No
	CH4	No
	All CH	Yes



No.	Item	Setting/ display	Description
1	OUT1 and OUT2	Setting	Sets the output type for outputs 1 and 2 to a pulse or linear output.
2	OUT3 and OUT4	Setting	Sets the output type for outputs 3 and 4 to a pulse or linear output.
3	OUT1 Current	Setting	Displayed when a linear current output has been set. Select 0 to 20 mA or 4 to 20 mA.
4	OUT2 Current	Setting	Displayed when a linear current output has been set. Select 0 to 20 mA or 4 to 20 mA.
5	OUT3 Current	Setting	Displayed when a linear current output has been set. Select 0 to 20 mA or 4 to 20 mA.
6	OUT4 Current	Setting	Displayed when a linear current output has been set. Select 0 to 20 mA or 4 to 20 mA.

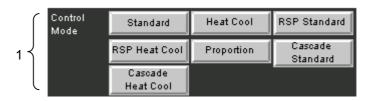
- * When using this SMART Active Part, be sure to select Setting System Settings in the menu bar, press the System Memory List Button on the Initial Tab Page, and select Basics for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

(32) Control Mode

Setting level	Channel	Part
Control initial setting level	CH1	No
	CH2	No
	CH3	No
	CH4	No
	All CH	Yes

Unit type	E5AR/E5ER	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5[]R\ControlInitial SettingLevel	Title	Control Mode
Function	Sets the control method. Set standard or heating/cooling control for a Temperature Controller with 1 Input				

Display and Operation Details



No.	Item	Setting/ display	Description
1	Control Mode	Setting	Sets the mode when a button is pressed.

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

1.1.9 Initial Setting 2 Level

(33) Control/Transfer Output 1 and 2 Allocations

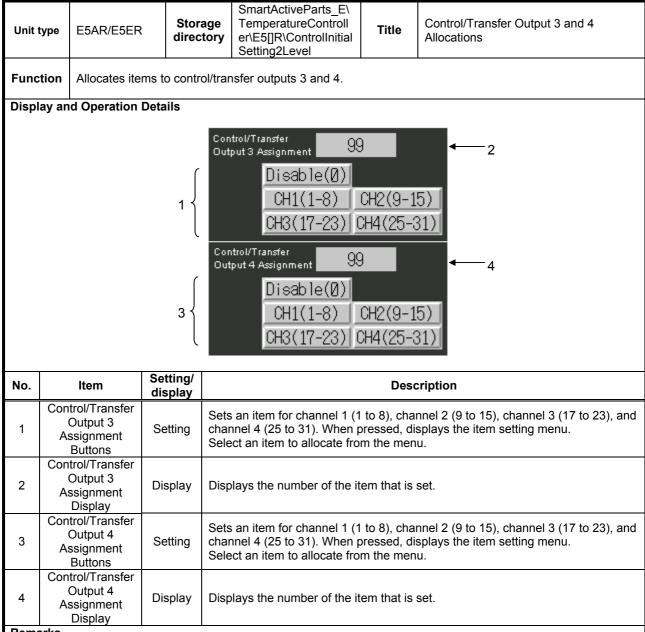
Setting level	Channel	Part
Control initial setting 2 level	CH1	No
	CH2	No
	CH3	No
	CH4	No
	All CH	Yes

_							
Unit	type E5AR/E5ER	Storag director		Title	Control/Transfer Output 1 and 2 Allocations		
Func	Function Allocates items to control/transfer outputs 1 and 2.						
Displ	Display and Operation Details						
		1 {	CH3(17-23) (CH3(17-23) (CH3(17	CH2(9-1 CH4(25-3) CH2(9-1	31) ← 4 5)		
No.	Item	Setting/ display		Desc	cription		
1	Control/Transfer Output 1 Assignment Buttons	Setting c		oressed, di	nnel 2 (9 to 15), channel 3 (17 to 23), and splays the item setting menu.		
2	Control/Transfer Output 1 Assignment Display	Display D	isplays the number of the it	em that is	set.		
3	Control/Transfer Output 2 Assignment Buttons	Setting c	ets an item for channel 1 (1 nannel 4 (25 to 31). When p elect an item to allocate fro	oressed, di	nnel 2 (9 to 15), channel 3 (17 to 23), and isplays the item setting menu.		
4	Control/Transfer Output 2 Assignment Display	Display D	isplays the number of the it	em that is	set.		
Rema	arks						

- When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the System Memory List Button on the Initial Tab Page, and select Basics for the \$SB.
- Do not use this SMART Active Part on the initial screen.
- Use System version 5 or higher version.

(34) Control/Transfer Output 3 and 4 Allocations

Setting level	Channel	Part
Control initial setting 2 level	CH1	No
	CH2	No
	CH3	No
	CH4	No
	All CH	Yes



- * When using this SMART Active Part, be sure to select Setting System Settings in the menu bar, press the System Memory List Button on the Initial Tab Page, and select Basics for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

(35) Event Input 1 Allocation

There are six different SMART Active Parts, one each for event input 1, event input 2, event input 3, event input 4, event input 5, and event input 6.

Setting level	Channel	Part
Initial setting 2 level	CH1	No
	CH2	No
	CH3	No
	CH4	No
	All CH	Yes

Unit t	ype E5AR/E5ER	Stora direct	nge Tem	rtActiveParts_E\ peratureControll f[]R\ControlInitial ng2Level	Title	Event Input 1 Allocation	
Func	tion Allocates a f	Allocates a function to the event input.					
Displa	ay and Operation	Details				_	
				—		2	
	Event Input 1 Assignment 99 Disable (0) CH1(1-7) CH2(8-12) CH3(14-18) CH4(20-24)						
No.	Item	Setting/ display			Desc	cription	
1	Event Input 1 Assignment Buttons	Setting	channel 4		ressed, di	nnel 2 (8 to 12), channel 3 (14 to 18), and splays the item setting menu. u.	
2	Event Input 1 Assignment Display	ent Input 1 ssignment Display Displays the number of the item that is set.					
Rema	ırks						

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

(36) Auxiliary Output 1 Allocation and Auxiliary Output 1 Open/Close Setting

There are four different SMART Active Parts, one each for auxiliary output 1, auxiliary output 2, auxiliary output 3, and auxiliary output 4.

Setting level	Channel	Part
Control initial setting 2 level	CH1	No
_	CH2	No
	CH3	No
	CH4	No
	All CH	Yes

		Stora direct	ige	SmartActiveParts_E\ TemperatureControll er\E5[]R\ControlInitial Setting2Level	Title	Auxiliary Output 1 Allocation	
Function	Allocates an item to the auxiliary output. Sets open in alarm or close in alarm for the auxiliary output.						
Display ar	nd Operation [Details					
						2	
Aux. Output 99 Disable(0) CH1(1-7) AllCH(8-15) CH2(16-22) CH3(23-29) CH4(30-36) Aux. Output 1 Open in Alarm Close Open					7) -15) 22)		
				tput 1 Close	CH4(30-3	36)	
No.	ltem	Setting/		tput 1 Close	CH4(30-; Oper	36)	
Au	Item ux. Output 1 Assignment Buttons	Setting/ display	Sets a	utput 1 Close Alarm Close an item for channel 1 (1	Oper Description 7), all cannel 4 (30)	cription channel (8 to 15), channel 2 (16 to 22), 0 to 36). When pressed, displays the item	
1 Au	ux. Output 1	Setting/ display Setting	Sets a change setting Selection	an item for channel 1 (1 nel 3 (23 to 29), and chang menu.	Description of the control of the co	and an arription shannel (8 to 15), channel 2 (16 to 22), to 36). When pressed, displays the item u.	

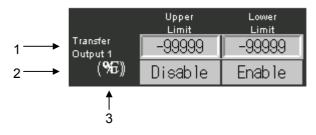
- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- Use System version 5 or higher version.

(37) Transfer Output 1 Upper/Lower Limits

There are four different SMART Active Parts, one each for the upper/lower limits for transfer output 1, transfer output 2, transfer output 3, and transfer output 4.

Setting level	Channel	Part
Control initial setting 2 level	CH1	No
_	CH2	No
	CH3	No
	CH4	No
	All CH	Yes

Unit type	E5AR/E5ER	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5[]R\ControlInitial Setting2Level	Title	Transfer Output 1 Upper/Lower Limits
Function	Sets the upper and lower limits for the transfer output and a transfer output has been allocated to an				
Display and Operation Details					



No.	Item	Setting/ display	Description
1	Transfer Output 1 Upper Limit Lower Limit	Setting	Sets the upper limit and lower limit of the transfer output. Setting the upper and lower limits also enables scaling the transfer output. The upper/lower limit settings can be input only when a transfer output has been enabled. They cannot be input when the transfer output is disabled.
2	Transfer Output 1 Enable/Disable Display	Display	Enable: The enable indicator will light when control/transfer output 1 is allocated to a transfer output. Disable: The disable indicator will light when control/transfer output 1 is allocated to a transfer output.
3	(°C) / (°F)	Display	Displays the temperature unit.

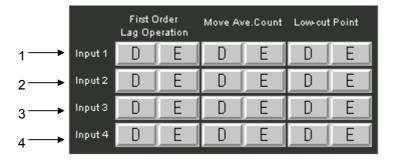
- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

(38) Enable Settings for First Order Lag Operation, Move Average, and Extraction of Square Root Low-cut Point

Setting level	Channel	Part
Control initial setting 2 level	CH1	No
	CH2	No
	CH3	No
	CH4	No
	All CH	Yes

Unit type	E5AR/E5ER	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5[]R\ControlInitial Setting2Level	Title	Enable Settings for First Order Lag Operation, Move Average, and Extraction of Square Root Low-cut Point for 4 Points
Function	Enables/disables the first order lag operation, move average count, and extraction of square root low-cut point for inputs 1, 2, 3, and 4.				

Display and Operation Details



No.	ltem	Setting/ display	Description
1	Input 1 First Order Lag Operation Move Ave. Count Low-cut Point Enable/Disable Buttons	Setting	Enables or disables the first order lag operation, move average count, and extraction of square root low-cut point for input 1.
2	Input 2 First Order Lag Operation Move Ave. Count Low-cut Point Enable/Disable Buttons	Setting	Enables or disables the first order lag operation, move average count, and extraction of square root low-cut point for input 2.
3	Input 3 First Order Lag Operation Move Ave. Count Low-cut Point Enable/Disable Buttons	Setting	Enables or disables the first order lag operation, move average count, and extraction of square root low-cut point for input 3.
4	Input 4 First Order Lag Operation Move Ave. Count Low-cut Point Enable/Disable Buttons	Setting	Enables or disables the first order lag operation, move average count, and extraction of square root low-cut point for input 4.

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

(39) Enable Settings for Straight-line and Broken-line Approximation

Setting level	Channel	Part
Control initial setting 2 level	CH1	No
	CH2	No
	CH3	No
	CH4	No
	All CH	Yes

Unit type	E5AR/E5ER	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5[]R\Controllnitial Setting2Level	Title	Enable Settings for Straight-line and Broken-line Approximation
Function	Enables/disables	s straight-line	approximation and brok	en-line app	proximation.
Display an	d Operation Deta	nils			
	1		aight Line Disable	Enab 1	e
	2		aightLine Disable	Enable	e
	3		Disable Disable	Enab 1	e

No.	Item	Setting/ display	Description
1	Straight-line Approx. 1 Enable/Disable	Setting	Enables/disables straight-line approximation 1.
2	Straight-line Approx. 2 Enable/Disable	Setting	Enables/disables straight-line approximation 2.
3	Broken-line Approx. Enable/Disable	Setting	Enables/disables broken-line approximation.

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- Use System version 5 or higher version.

1.1.10 Alarm Setting Level

(40) Alarm 1 Type, Alarm 1 Latch, and Alarm 1 Hysteresis

There are four different SMART Active Parts, one each for alarm 1, alarm 2, alarm 3, and alarm 4.

Setting level	Channe	l Part
Alarm settinglevel	CH1	Yes
	CH2	Yes
	CH3	Yes
	CH4	Yes
	All CH	No

Unit t	type E5AR/E5ER	Stor direc	age Tempe	ActiveParts_E\ eratureControll R\AlarmSettin	Title	Alarm 1 Type, Latch, and Hysteresis				
Func	Sets the alar	rm type, late	ch, and hyster	esis for alarm 1.						
Displa	Display and Operation Details									
	CH1									
		2	Alarm 1 Type		Туре(0-)	<u>11)</u> ← 1				
		3	Alarm 1 Latch	OFF OFF	ON					
		4	Alarm 1 Hysteresis	99.99						
No.	Item	Setting/			Desc	ription				
1		display	Diaplaya tha	alarm time that						
	Alarm 1 Type Alarm 1 Type	Display	Displays the alarm type that is set.							
2	Alailii i type	Setting	When pressed, displays the alarm type setting menu. Select the alarm type from							

Remarks

2

3

When using this SMART Active Part, be sure to select Setting - System Settings in the menu bar, press the System Memory List Button on the Initial Tab Page, and select Basics for the \$SB.

Sets whether to latch the alarm output status.

Sets ON/OFF hysteresis for the alarm output.

Do not use this SMART Active Part on the initial screen.

Setting

Setting

Display

the menu.

Use System version 5 or higher version.

Buttons

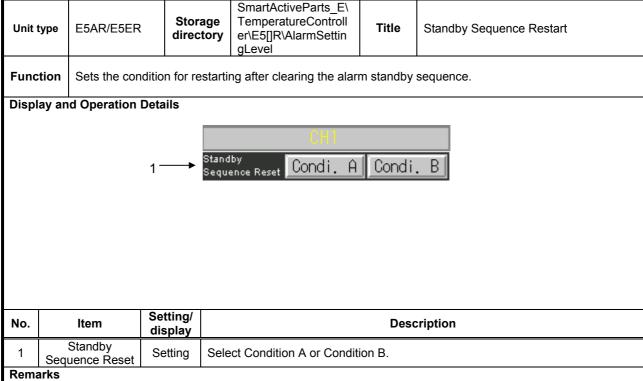
Alarm 1 Latch

Alarm 1

Hysteresis

(41) Standby Sequence Restart

Setting level	Channel	Part
Alarm setting level	CH1	Yes
	CH2	Yes
	CH3	Yes
	CH4	Yes
	All CH	No



- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

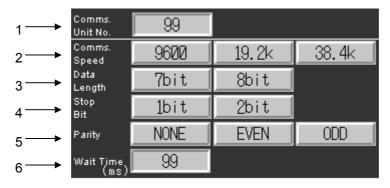
1.1.11 Communications Setting Level

(42) Communications Settings

Setting level	Channel	Part
Communications setting level	CH1	No
	CH2	No
	CH3	No
	CH4	No
	All CH	Yes

Unit type	E5AR/E5ER	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5[]R\Communicat ionsSettingLevel	Title	Communications Settings
Function	Sets the communications unit number and communications settings. The following settings are used when connecting an NS-series PT to the Temperature Controller: Data				

Display and Operation Details



No.	Item	Setting/ display	Description
1	Comms. Unit No.	Setting	Sets the communications unit number. Set a different unit number for each Temperature Controller.
2	Comms. Speed	Setting	Sets the baud rate. Set the NS-series PT and all connected Temperature Controllers to the same setting.
3	Data Length	Setting	Sets the communications data length. A data length of 7 bits is used to connect an NS-series PT to the Temperature Controller.
4	Stop Bit	Setting	Sets the number of communications stop bits. Two stop bits are used to connect an NS-series PT to the Temperature Controller.
5	Parity	Setting	Sets the communications parity. Even parity is used to connect an NS-series PT to the Temperature Controller.
6	Wait Time	Setting	Sets the transmission wait time.

- * The PT and the Temperature Controller will not be able to communicate unless the following settings are used: Data length: 7 bits, Stop bits: 2 bits, Parity: even.
- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

1.1.12 Advanced Function Setting Level

(43) Number of Enabled Channels

Setting level	Channel	Part
Advanced function setting level	CH1	No
	CH2	No
	CH3	No
	CH4	No
	All CH	Yes

Unit	type E5AR/E5ER	Stora		Title	Number of Enabled Channels			
Func	Function Sets the number of channels to enable for a Temperature Controller with more than one input.							
Displ	lay and Operation	Details						
	1 — Enabled No. of Chan. 99							
No.	Item	Setting/ display			cription			
1	Enabled No. of Chan.	Setting	Sets the number of channels Temperature Controllers with Temperature Controllers with	n Two Inpu	standard, or remote SP standard, or remote SP heating/cooling control. Set 1 or 2 for all other types of control.			
D	Remarks							

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

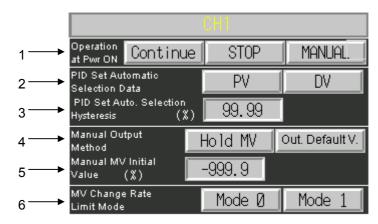
1.1.13 Extended Control Setting Level

(44) Operation at Power ON, PID Automatic Selection, PID Automatic Selection Hysteresis, Manual Output Method, and MV Change Rate Limit Mode

Setting level	Channel	Part
Extended control setting level	CH1	Yes
	CH2	Yes
	CH3	Yes
	CH4	Yes
	All CH	No

Unit type	E5AR/E5ER	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5[]R\ExtendedSe ttingLevel	Title	Operation at Power ON, PID Automatic Selection, Manual Output, and MV Change Rate
Function	Sets the operation at power ON PID automatic selection PID automatic selection hysteresis manual				

Display and Operation Details



No.	Item	Setting/ display	Description
1	Operation at Power ON	Setting	Sets the operation to use when the power supply is turned ON. Set CONTINUE to continue the operating status that existed when the power supply was turned OFF. Set STOP to stop the control operation after the power supply is turned ON. Set MANUAL to enter manual mode.
2	PID Set Automatic Selection Data	Setting	Sets whether to use the process value or deviation for the PID automatic selection.
3	PID Set Automatic Selection Hysteresis	Setting	Sets the hysteresis for switching the PID set.
4	Manual Output Method	Setting	Sets the MV output method when switching from automatic to manual.
5	Manual MV Initial Value	Setting	Sets the initial value of the MV when outputting the initial value is set.
6	MV Change Rate Limit Mode	Setting	Sets whether to use mode 0 or mode 1 for the MV change rate limit.

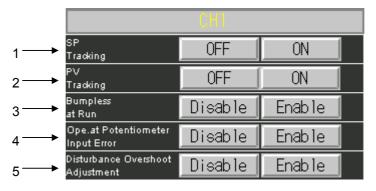
- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- Use System version 5 or higher version.

(45) Enable Settings for SP Tracking, PV Tracking, Bumpless at Run, Operation at Potentiometer Input Error, and Disturbance Overshoot Adjustment

Channel	Part
CH1	Yes
CH2	Yes
CH3	Yes
CH4	Yes
All CH	No
	CH1 CH2 CH3 CH4

Unit type	E5AR/E5ER	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5[]R\ExtendedSe ttingLevel	Title	Enable Settings for Tracking, Bumpless at Run, Operation at Potentiometer Input Error, and Disturbance Overshoot Adjustment
Function	Enables/Disables SP tracking, PV tracking, bumpless at run operation, operation at potentiometer inpurerror, and disturbance overshoot adjustment.				

Display and Operation Details



No.	Item	Setting/ display	Description
1	SP Tracking ON/OFF	Setting	Sets the operation when switching from remote SP mode to local SP mode. OFF: Local SP not affected by remote SP. ON: Remote SP used initially for local SP.
2	PV Tracking ON/OFF	Setting	Sets whether the local SP is to follow the PV during manual mode. OFF: Local SP does not follow PV. ON: Local SP follows PV.
3	Bumpless at Run Enable/Disable	Setting	Sets whether to use bumpless operation when switching from stop to run status. Disable: Do not use bumpless operation. Enable: Use bumpless operation.
4	Ope. at Potentiometer Input Error Enable/Disable	Setting	Sets whether to stop or continue operation when an input error occurs for the potentiometer. Disable: Stop control operation. Enable: Switch to floating control and continue control operation.
5	Disturbance Overshoot Adjustment Enable/Disable	Setting	Disable: Disable disturbance overshoot adjustment. Enable: Enable disturbance overshoot adjustment.

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

(46) α , AT Calculated Gain, AT Hysteresis, and Tentative AT Execute Judgment Deviation

Setting level	Channel	Part
Extended control setting level	CH1	Yes
-	CH2	Yes
	CH3	Yes
	CH4	Yes
	All CH	No

Unit t	type E5AR/E5ER	Stora		eControll	Title	α, AT Calculated Gain, AT Hysteresis, and Tentative AT Execute Judgment Deviation
Func	Sets the α , λ	AT calculate	ed gain, AT hystere	esis, and ten	tative AT	execute judgment deviation.
Displ	ay and Operation	Details				
				CH1		
	1 -	α		9.99		
	2-	—→ AT Ca	alculated Gain	99.9		
	3-	→ AT H ₃	/steresis (%)	9.9		
	4 -	→ Limit Ampli	Cycle MV itude (%)	99.9		
	5-	Temp Judge	. A.T. Excution ement Deviation(※)	999.9	9	
	1					
No.	Item	Setting/ display			Desc	cription
1	α	Setting	Sets the α consta	ant for advar	nced PID o	control.
2	AT Calculated Gain	Setting	Sets the gain when calculating PID constants using autotuning.			
3	AT Hysteresis	Sets the hysteres	sis for the lin	nit cycle or	peration during autotuning.	
Limit Cycle MV				le of the limi	t cycle ope	eration during autotuning.
	Temp. A.T.					

Remarks

5

* When using this SMART Active Part, be sure to select **Setting - System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.

Sets the judgment deviation for executing tentative AT when autotuning.

* Do not use this SMART Active Part on the initial screen.

Setting

* Use System version 5 or higher version.

Execution

Judgement Deviation

(47) Cold Junction Compensation Method

Setting level	Channel	Part
Extended control setting level	CH1	No
	CH2	No
	CH3	No
	CH4	No
	All CH	Yes

Unit type E5AR/E5ER Storage directory E1NE5[]R\ExtendedS ettingLevel Title Cold Junction Compensation Method ettingLevel Function Sets the cold junction compensation method for input 1, input 2, input 3, and input 4. Display and Operation Details Input 1 Cold Junction Compensation External Internal Internal Internal Internal Internal Input 3 Cold Junction Compensation External Internal Interna						<u>.</u>
Display and Operation Details 1	Unit type	E5AR/E5ER	_	TemperatureControll er\\E5[]R\ExtendedS	Title	Cold Junction Compensation Method
Input 1 Cold Junction Compensation External Internal Input 2 Cold Junction Compensation External Internal Input 3 Cold Junction Compensation External Internal Input 4 External Internal	Function	Sets the cold jun	ction compe	nsation method for input	1, input 2,	input 3, and input 4.
cold Junction Compensation External Internal Input 2	Display an	d Operation Deta	ails			
		1—————————————————————————————————————	Cold Junct Input 2 Cold Junct Input 3 Cold Junct Input 4	ion Compensation Exter	nal∫Ir nal∫Ir	nternal nternal

No.	Item	Setting/ display	Description
1	Input 1 Cold Junction Compensation	Setting	Set whether to perform cold junction compensation inside the Temperature Controller or externally for input 1.
2	Input 2 Cold Junction Compensation	Setting	Set whether to perform cold junction compensation inside the Temperature Controller or externally for input 2.
3	Input 3 Cold Junction Compensation	Setting	Set whether to perform cold junction compensation inside the Temperature Controller or externally for input 3.
4	Input 4 Cold Junction Compensation	Setting	Set whether to perform cold junction compensation inside the Temperature Controller or externally for input 4.

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.



1.1 E5AN, E5EN, E5DN, and E5GN

			ESEN, ESDN, and ESGN Temperature Controllers.
Operation level	Temperature Controllers	E5AN/E5EN	Operation Monitor for Standard Control
	with Thermocouples		Operation Monitor for Heating/Cooling Control
		E5011	SP and Alarm Settings
		E5CN	Operation Monitor for Standard Control
			Operation Monitor for Heating/Cooling Control
			SP and Alarm Settings
		E5GN	Operation Monitor for Standard Control
			SP and Alarm Settings
		All E5[]N	SP Setting
	Temperature Controllers	E5AN/E5EN	Operation Monitor for Standard Control
	with Platinum-resistance		Operation Monitor for Heating/Cooling Control
	Thermometers		SP and Alarm Settings
		E5CN	Operation Monitor for Standard Control
			Operation Monitor for Heating/Cooling Control
			SP and Alarm Settings
		E5GN	Operation Monitor for Standard Control
			SP and Alarm Settings
		ALL E5[]N	SP Setting
Adjustment level	Temperature Controllers	ALL E5[]N	Multi-SP Settings
-	with Thermocouples	_	-
	Temperature Controllers	ALL E5[]N	Multi-SP Settings
	with Platinum-resistance		
	Thermometers		
	Temperature Controllers	ALL E5[]N	Heater Burnout Detection
	with Thermocouples or		PID Settings
	Platinum-resistance		Input Shift Values
	Thermometers		Manual Reset Value
			Cooling Coefficient, Dead Band, and Control
			Period
			Dead Band and Hysteresis
Initial setting level	Temperature Controllers	ALL E5[]N	Input Type, Temperature Unit, Scaling, and
	with Thermocouples		Decimal Point
			SP Limits
	Temperature Controllers	ALL E5[]N	Input Type and Temperature Unit
	with Platinum-resistance		SP Limits
	Thermometers		
	Temperature Controllers	ALL E5[]N	PID or ON/OFF Control
	with Thermocouples or		Direct/Reverse Operation
	Platinum-resistance		Control Mode
	Thermometers		ST and ST Stable Range
			Alarm 1 Type, Open/Close in Alarm, Latch,
			Hysteresis
			Alarm 2 Type, Open/Close in Alarm, Latch,
			Hysteresis
			Alarm 3 Type, Open/Close in Alarm, Latch,
			Hysteresis
Advanced function	Temperature Controllers	ALL E5[]N	SP Ramp
setting level	with Thermocouples	1	
	Temperature Controllers	ALL E5[]N	SP Ramp
	with Platinum-resistance		
	Thermometers	1	
	Temperature Controllers	ALL E5[]N	Multi-SP ON/OFF
	with Thermocouples or		HBA Used, Latch, Hysteresis
	Platinum-resistance		MV Upper/Lower Limits and Input Digital Filter
	Thermometers		Standby Sequence Restart
			α
			Input Error Output
			Cold Junction Compensation Method
Communications	ALL E5[]N	ALL E5[]N	Communications Settings
	1	·	

1.1.1 Operation Level

(1) Operation Monitor for E5AN/E5EN Standard Control

Setting level	Input type	Part
Operation level	Thermocouple input	Yes
	Platinum-resistance thermometer Y	
	Common(Common)	No

Unit type	E5AN, E5EN	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5[]N\OperationLe vel	Title	Operation Monitor for Standard Control
Function	Continuously mo	nitors opera	ting status on a face plate	Э.	
Display a	nd Operation Deta	ails			
		1 - 2 - 3 - 4 - 5 - 6 - 7 - 8 - 9 - 10 -	RUN AT 1 2 3 OUT ALM HB Input Error Crrent Value Exceeds (°E) PU SP -9999 MV1 (%) -999.		-11
No.		tting/		Desc	cription

No.	Item	Setting/ display	Description
1	RUN AUTO	Display	Displays the run/stop and autotuning status.
2	OUT	Display	Displays the output status of control output 1.
3	ALM	Display	Displays the output status of alarm outputs 1, 2, and 3.
4	HB	Display	Displays the heater burnout output status.
5	Input Error	Display	Displays the input error status.
6	Current Value Exceeds	Display	Displays the status of a current value exceeded error.
7	(°C) / (°F)	Display	Displays the temperature unit.
8	PV	Display	Displays the process value.
9	SP	Display	Displays the set point.
10	MV1	Display	Displays the manipulated variable of output 1.
11	Display Update Indicator	Display	Flashes each time the display is updated.

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

(2) Operation Monitor for E5AN/D5EN Heating/Cooling Control

Setting level	Input type	Part
Operation level	Thermocouple input	Yes
	Platinum-resistance thermometer	Yes
	Common(Common)	No

Unit type	E5AN, E5EN	Stora direc		ntroll Title	Operation Monitor for Heating/Cooling Control		
Function	Continuously monitors operating status on a face plate.						
Display	and Operation	Details					
RUN AT ■ 12							
			1	2 3	. <u>-</u>		
			2 → OUT				
			3 → ALM				
			4 → HB				
			5 → Input Error	_			
			6 Current Va	lue 🔛			
			7 → (°E)	0000			
			8 PU	-9999			
	9 → sp _9999						
	10						
	11> MU2 (%) -999.9						
	*** (**) **** 333.8						
No.	Item	Setting/ display		De	escription		
	RUN	alopiuy					
1	AUTO AT	Display	Displays the run/stop	and autotuning	status.		
2	OUT	Display	Displays the output status of control outputs 1 and 2.				
3	ALM	Display	Displays the output sta				
4	HB	Display	Displays the heater bu		atus.		
5	Input Error	Display	Displays the input erro	or status.			
6	Current Value Exceeds	Display	Displays the status of		exceeded error.		
7	(°C) / (°F)	Display	Displays the temperat				
8	PV	Display	Displays the process v	/alue.			
9	SP	Display					
10	MV1	Display					
11	MV2	Display	Displays the manipulated variable of output 2.				
12 D	isplay Update Indicator	Display	Flashes each time the	display is upda	ated.		

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

(3) SP and Alarm Settings for E5AN/E5EN

Setting level	Input type	Part
Operation level	Thermocouple input	Yes
	Platinum-resistance thermometer	Yes
	Common(Common)	No

Unit type	E5AN, E5EN	Storage directory	SmartActivePa TemperatureCo er\E5[]N\Opera vel	ontroll	Title	SP and Ala	arm Settings
Function		set point and the alarm values for outputting alarms. utput status is continuously updated.					
Display and	d Operation Deta	ils					
	1	SP (°E)	-9999			•	10
	2→	(°E)	Alarm Val.	Upper	Lim, Lo	wer Lim.	
	3→	ALM1	-9999	-999	99	-9999	
	4	ALM2	-9999	-999	99	-9999	
	5 →	ALM3	-9999	-999	99	-9999	
		<u>†</u>	<u>†</u>	†		†	-
		J	,		,	J	

No.	Item	Setting/ display	Description
1	SP	Setting	Sets the set point.
2	(°C) / (°F)	Display	Displays the temperature unit.
3	ALM1	~	The ALM1 row contains the alarm 1 settings: alarm value, upper limit, and lower limit.
4	ALM2	~	The ALM2 row contains the alarm 2 settings: alarm value, upper limit, and lower limit.
5	ALM3	~	The ALM3 row contains the alarm 3 settings: alarm value, upper limit, and lower limit.
6	Alarm Indicators	Display	Displays the output status of alarm outputs 1, 2, and 3. The display is continuously updated.
7	Alarm Val.	Setting	Sets the alarm value. The alarm value is displayed and can be set when the alarm type is set to anything other than an upper/lower limit alarm.
8	Upper Lim.	Setting	Sets the alarm upper limit. The alarm upper limit is displayed and can be set when the alarm type is set to an upper/lower limit alarm.
9	Lower Lim.	Setting	Sets the alarm lower limit. The alarm lower limit is displayed and can be set when the alarm type is set to an upper/lower limit alarm.
10	Display Update Indicator	Display	The alarm indicator display is continuously updated. This indicator flashes each time the data is updated.

- When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB. Do not use this SMART Active Part on the initial screen.
- Use System version 5 or higher version.

(4) Operation Monitor for E5CN Standard Control

Setting level	Input type	Part
Operation level	Thermocouple input	Yes
	Platinum-resistance thermometer	Yes
	Common(Common)	No

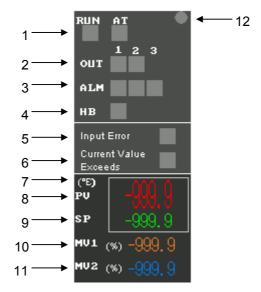
		direc	TemperatureControll er\E5[]N\OperationLe vel Title Operation Monitor for Standard Control					
Functio	Function Continuously monitors operating status on a face plate.							
Display	Display and Operation Details							
1 — TIN AT 2 — OUIT 3 — ALM 4 — HB 5 — Input Error 6 — Exceeds 7 — (°E) 9 — SP — 9999 10 — MU1 (%) – 999, 9								
No.	Item	Setting/ display	Description					
1	RUN AT	Display	Displays the run/stop and autotuning status.					
2	OUT	Display	Displays the output status of control output 1.					
3	ALM	Display	Displays the output status of alarm outputs 1 and 2.					
4	HB	Display	Displays the heater burnout output status.					
5	Input Error	Display	Displays the input error status.					
6	Current Value Exceeds	Display	Displays the status of a current value exceeded error.					
7	(°C) / (°F)	Display	Displays the temperature unit.					
8	PV	Display	Displays the process value.					
9	SP	Display	Displays the set point.					
10	MV	Display	Displays the manipulated variable of output 1.					
11 [Display Update Indicator Display Flashes each time the display is updated.							

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- Use System version 5 or higher version.

(5) Operation Monitor for E5CN Heating/Cooling Control

Setting level	Input type	Part
Operation level	Thermocouple input	Yes
	Platinum-resistance thermometer	Yes
	Common(Common)	No

Unit type	E5CN	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5[]N\OperationLe vel	Title	Operation Monitor for Heating/Cooling Control
Function	Continuously monitors operating status on a face plate.				
Display an	Display and Operation Details				

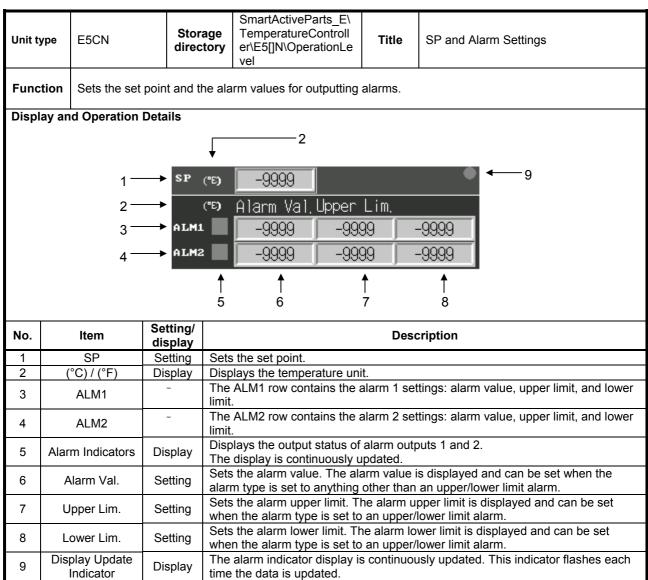


No.	Item	Setting/ display	Description			
1	RUN AT	Display	Displays the run/stop and autotuning status.			
2	OUT	Display	Displays the output status of control outputs 1 and 2.			
3	ALM	Display	Displays the output status of alarm output 1.			
4	HB	Display	Displays the heater burnout output status.			
5	Input Error	Display	Displays the input error status.			
6	Current Value Exceeds	Display	Displays the status of a current value exceeded error.			
7	(°C) / (°F)	Display	Displays the temperature unit.			
8	PV	Display	Displays the process value.			
9	SP	Display	Displays the set point.			
10	MV1	Display	Displays the manipulated variable of output 1.			
11	MV2	Display	Displays the manipulated variable of output 2.			
12	Display Update Indicator	Display	Flashes each time the display is updated.			

- When using this SMART Active Part, be sure to select Setting System Settings in the menu bar, press the System Memory List Button on the Initial Tab Page, and select Basics for the \$SB.
- Do not use this SMART Active Part on the initial screen.
- Use System version 5 or higher version.

(6) SP and Alarm Settings for E5CN

Setting level	Input type	Part
Operation	Thermocouple input	Yes
level	Platinum-resistance thermometer	Yes
	Common(Common)	No



- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

(7) Operation Monitor for E5GN Standard Control

Setting level	Part	
Operation level	Thermocouple input	Yes
	Platinum-resistance thermometer	Yes
	Common(Common)	No

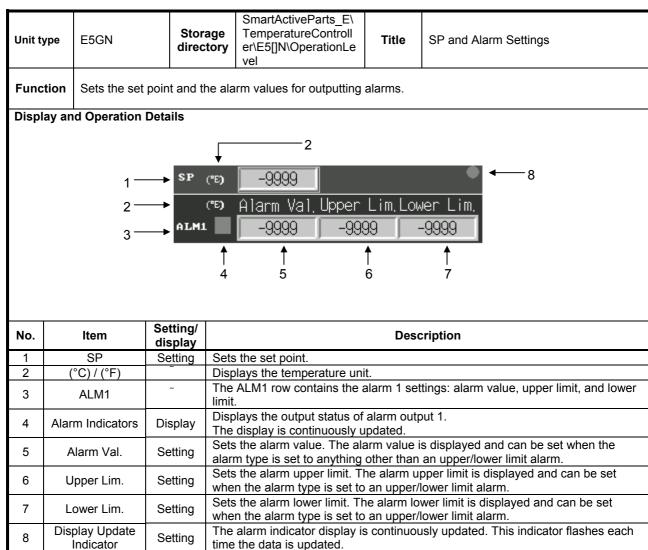
Unit type	E5GN	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5[]N\OperationLe vel	Title	Operation Monitor for Standard Control
Function	Continuously mo	nitors opera	ting status on a face plate	Э.	
Display an	d Operation Deta	ils			
		1 - 2 - 3 - 4 - 5 - 6 - 7 - 8 -	RUN AT 1 2 3 OUT ALM Input Error ("E) PU SP -9999 MU1 (%) -999.		-9

No.	Item	Setting/ display	Description
1	RUN AT	Display	Displays the run/stop and autotuning status.
2	OUT	Display	Displays the output status of control output 1.
3	ALM	Display	Displays the output status of alarm output 1.
4	Input Error	Display	Displays the input error status.
5	(°C) / (°F)	Display	Displays the temperature unit.
6	PV	Display	Displays the process value.
7	SP	Display	Displays the set point.
8	MV1	Display	Displays the manipulated variable.
9	Display Update Indicator	Display	Flashes each time the display is updated.

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

(8) SP and Alarm Settings for E5GN

Setting level	Input type	Part
Operation level	Thermocouple input	Yes
	Platinum-resistance thermometer	Yes
	Common(Common)	No



- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

(9) SP Setting

Setting level	Input type	Part
Operation level	Thermocouple input	Yes
	Platinum-resistance thermometer	Yes
	Common(Common)	No

Unit type	E5AN, E5EN, E5CN, E5GN	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5[]N\OperationLe vel	Title	SP Setting
Function	Sets the set poin	t.			

Display and Operation Details



No.	Item	Setting/ display	Description
1	SP	Setting	Sets the set point.
2	(°C) / (°F)	Display	Displays the temperature unit.

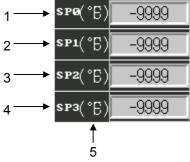
- When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

1.1.2 Adjustment Level

(10) Multi-SP Settings

Setting level	Part	
Adjustment level	ent level Thermocouple input Y	
	Platinum-resistance thermometer	Yes
	Common(Common)	No

Unit type	E5AN, E5EN, E5CN, E5GN	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5[]N\AdjustmentL evel	Title	Multi-SP Settings		
Function	Sets the set poin	Sets the set points for multi-SP operation.					
Display and Operation Details							
1 → SPO (°B) -9999							



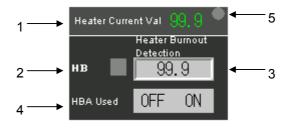
No.	Item	Setting/ display	Description
1	SP0	Setting	Sets set point 0.
2	SP1	Setting	Sets set point 1.
3	SP2	Setting	Sets set point 2.
4	SP3	Setting	Sets set point 3.
5	(°C) / (°F)	Display	Displays the temperature unit.

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

(11) Heater Burnout Detection

Setting level	Input type	Part
Adjustment level	Thermocouple input	No
	Platinum-resistance thermometer	No
	Common(Common)	Yes

Unit type	E5AN, E5EN, E5CN	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5[]N\AdjustmentL evel	Title	Heater Burnout Detection	
Function	This SMART Act	tive Part will	current and sets the heate function when heater bur MART Active Part in the a	nout detec	tion is enabled.	
Display an	Display and Operation Details					



No.	Item	Setting/ display	Description
1	Heater Current Val	Display	Continuously displays the heater current.
2	HB	Display	Continuously displays the output status for heater burnout detection.
3	Heater Burnout Detection	Setting	Sets the heater burnout detection value.
4	HBA Used	Display	Displays the setting status (advanced function setting level) for heater burnout detection.
5	Display Update Indicator	Display	Flashes each time the heater current or HB display is updated.

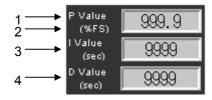
- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

(12) PID Settings

Setting level	Setting level Input type			
Adjustment level	Thermocouple input	No		
	Platinum-resistance thermometer	No		
	Common(Common)	Yes		

Unit type	E5AN, E5EN, E5CN, E5GN	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5[]N\AdjustmentL evel	Title	PID Settings
Function	Sets the PID con	istants.			

Display and Operation Details



No.	Item	Setting/ display	Description
1	P Value	Setting	Sets the proportional band.
2	(°C) / (°F)	Display	Displays the temperature unit.
3	l Value	Setting	Sets the integral time.
4	D Value	Setting	Sets the derivative time.

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

(13) Input Shift Values

Setting level	Input type	Part
Adjustment level	Thermocouple input	No
	Platinum-resistance thermometer	No
	Common(Common)	Yes

Unit type	Init type E5AN, E5EN, Storage TemperatureCo		SmartActiveParts_E\ TemperatureControll er\E5[]N\AdjustmentL evel	Title	Input Shift Values		
Function	Sets the input shift values for the sensor measurement range.						
Display an	d Operation Deta	ails					
	1 ⁻ 2 ⁻	Input 9	nt shift (°E) Shift Value —999.9 t shift (°E) Upper Limit Temperature Shift Value —999.9	Lower Lim Temperat -999.	ure		

No.	Item	Setting/ display	Description
1	1-point shift Input Shift Value	Setting	Sets the input shift value for a 1-point shift.
2	2-point shift Input Shift Value Upper Limit Temperature Lower Limit Temperature	Setting	Sets the input shift values for the upper limit and lower limit of the sensor measurement range.
3	(°C) / (°F)	Display	Displays the temperature unit.

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

(14) Manual Reset Value

Setting level	Input type	Part
Adjustment level	Thermocouple input	No
	Platinum-resistance thermometer	No
	Common(Common)	Yes

Unit ty	E5AN, E5EN E5CN, E5GI			Controll	Title	Manual Reset Value	
Funct	Function Sets the manual reset value.						
Displa	ay and Operation	Details					
		1-	Manual Reset Val ^(%)	999	9.9		
No.	Item	Setting/ display	Description				
1	Manual Reset Val	Setting	Sets the manual reset value.				

Remarks

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

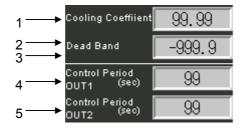
Val.

(15) Cooling Coefficient, Dead Band, and Control Period

Setting level	Input type	Part
Adjustment level	Thermocouple input	No
	Platinum-resistance thermometer	No
	Common(Common)	Yes

Unit type	E5AN, E5EN, E5CN, E5GN	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5[]N\AdjustmentL evel	Title	Cooling Coefficient, Dead Band, and Control Period
Functio	n Sets the cooling	coefficient, c	dead band, and control pe	eriod.	

Display and Operation Details



No.	Item	Setting/ display	Description			
1	Cooling Coefficient	Setting	Sets the cooling coefficient for heating/cooling control.			
2	Dead Band	Setting	Sets the dead band for heating/cooling control.			
3	(°C) / (°F)	Display	Displays the temperature unit.			
4	Control Period OUT1	Setting	Sets the control period for the control output OUT1 for heating/cooling control. Sets the control period for the control output OUT1 for standard control.			
5	Control Period OUT2	Setting	Sets the control period for the control output OUT2 for heating/cooling control. The control period for OUT2 is used only for heating/cooling control.			

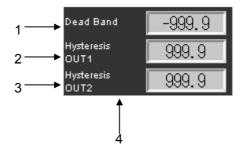
- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

(16) Dead Band and Hysteresis

Setting level	Input type	Part
Adjustment level	Thermocouple input	No
	Platinum-resistance thermometer	No
	Common(Common)	Yes

Unit type	E5AN, E5EN, E5CN, E5GN	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5[]N\AdjustmentL evel	Title	Dead Band and Hysteresis
Function	Sets the dead ba	and and hyst	eresis for ON/OFF contro	ol.	

Display and Operation Details



No.	Item	Setting/ display	Description
1	Dead Band	Setting	Sets the dead band.
2	Hysteresis OUT1	Setting	Sets the hysteresis for the control output OUT1 for heating/cooling control. Sets the hysteresis for the control output OUT1 for standard control.
3	Hysteresis OUT2	Setting	Sets the hysteresis for the control output OUT2 for heating/cooling control.
4	(°C) / (°F)	Display	Displays the temperature unit.

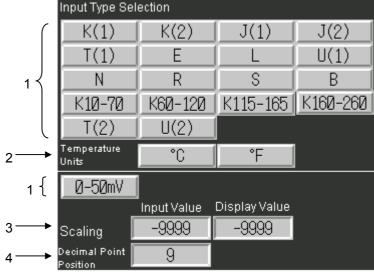
- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

1.1.3 Initial Setting Level

(17) Input Type, Temperature Unit, Scaling, and Decimal Point for Thermocouple Inputs

Setting level	Input type	Part
Initial setting level	Thermocouple input	Yes
	Platinum-resistance thermometer	No
	Common(Common)	No

Unit type	E5AN, E5EN, E5CN, E5GN	Storage directory	SmartActiveParts TemperatureConi er\E5[]N\InitialSet Level	troll Ti	tle	Input Type	, Temperature Unit, Scaling al Point	
Function	Function Sets the input type and temperature unit for a Temperature Controller with a Thermocouple Input. When an analog input is selected, sets the scaling and decimal point position.							
Display an	Display and Operation Details							
	Input Type Selection							
	(K(1) K(2) J(1) J(2)							
		T(1)	E	L		U(1)		

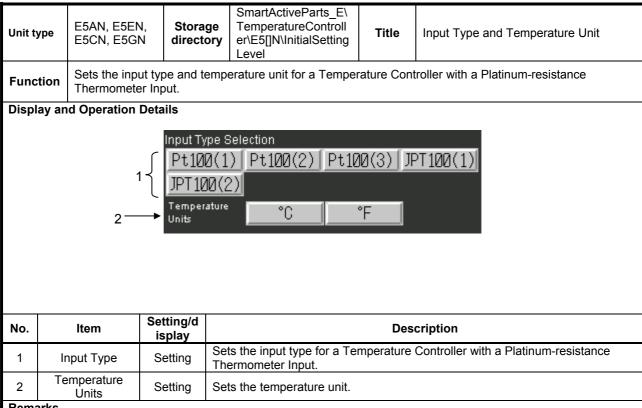


No.	Item	Setting/ display	Description		
1	Input Type	Setting	Sets the thermocouple input type. The same input type applies to both channels 1 and 2.		
2	Temperature Units	Setting	Sets the temperature unit.		
3	Scaling Input Value Display Value.	Setting	When the input type is set to an analog input (0 to 50 mV), sets the upper and lower limits for scaling.		
4	Decimal point position	Setting	When the input type is set to an analog input (0 to 50 mV), sets the number of places below the decimal point.		

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- Use System version 5 or higher version.

(18) Input 1 Type and Temperature Unit for Platinum-resistance Thermometer Input

Setting level	Input type	Part
Initial setting level	Thermocouple input	No
	Platinum-resistance thermometer	Yes
	Common(Common)	No



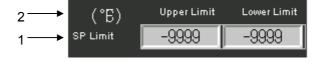
- When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the System Memory List Button on the Initial Tab Page, and select Basics for the \$SB.
- Do not use this SMART Active Part on the initial screen.
- Use System version 5 or higher version.

(19) SP Limits

Setting level	Input type	Part
Initial setting level	Thermocouple input	Yes
	Platinum-resistance thermometer	Yes
	Common(Common)	No

Unit type	E5AN, E5EN, E5CN, E5GN	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5[]N\InitialSetting Level	Title	SP Limits
Function	Sets the upper a	nd lower limi	ts for the set point.		

Display and Operation Details



No.	Item	Setting/ display	Description
1	SP Limit Upper Limit Lower Limit	Setting	Sets the upper and lower limits for the set point. Can be set anywhere within the input temperature setting range.
2	(°C) / (°F)	Display	Displays the temperature unit.

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- Use System version 5 or higher version.

(20) PID or ON/OFF Control

Setting level	Input type	Part
Initial setting level	Thermocouple input	No
	Platinum-resistance thermometer	No
	Common(Common)	Yes

Unit ty	/pe E5AN, E5EN E5CN, E5GN			Title	PID or ON/OFF Control			
Func	tion Sets either F	PID or ON/C	PFF control.					
Displ	ay and Operation	Details						
		1	Control ON/OFF	PID				
		Setting/						
No.	Item	Item Setting/ Description						
1	1 Control System Setting Sets either PID or ON/OFF control.							
	Remarks							

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

Setting level	Input type	Part
Initial setting level	Thermocouple input	No
	Platinum-resistance thermometer	No
	Common(Common)	Yes

ι	Jnit type	E5AN, E5EN, E5CN, E5GN	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5[]N\InitialSetting Level	Title	Direct/Reverse Operation	
ı	unction	Sets either direction operation or reverse operation for increases and decreases in the process value.					

Display and Operation Details

(21) Direct/Reverse Operation



No.	Item	Setting/ display	Description
1	Operation	Setting	Sets either direction operation or reverse operation for increases and decreases in the process value.

- When using this SMART Active Part, be sure to select Setting System Settings in the menu bar, press the System Memory List Button on the Initial Tab Page, and select Basics for the \$SB.
- Do not use this SMART Active Part on the initial screen.
- Use System version 5 or higher version.

(22) Control Mode

Setting level	Input type	Part
Initial setting level	Thermocouple input	No
	Platinum-resistance thermometer	No
	Common(Common)	Yes

Unit ty	/pe E5AN, E5EN E5CN, E5GN			Title	Control Mode				
Func	Sets standard control or heating/cooling control.								
Displa	ay and Operation	Details							
		1 → Co Mo	ntrol Standard	Heat Cool					
No.	Item	Setting/ display		Desc	cription				
1	1 Control Mode Setting Sets standard control or heating/cooling control.								
Remarks									

- When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the System Memory List Button on the Initial Tab Page, and select Basics for the \$SB.
- Do not use this SMART Active Part on the initial screen.
- Use System version 5 or higher version.

(23) ST ON/OFF and ST Stable Range

Setting level	Input type	Part
Initial setting level	Thermocouple input	No
	Platinum-resistance thermometer	No
	Common(Common)	Yes

Unit type	E5AN, E5EN, E5CN, E5GN	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5[]N\InitialSetting Level	Title	ST ON/OFF and ST Stable Range		
Function	Turns the ST function ON and OFF, and sets the ST stable range.						
Display an	Display and Operation Details						
1 OFF ON							
	2	→ ST	e Range 999.9				

1 → ST	OFF	ON
2 → ST Stable Range	999.9	
	3	

No.	Item	Setting/ display	Description
1	ST ON/OFF	Setting	Turns the ST function ON and OFF.
2	ST Stable Range	Setting	Sets the ST stable range.
3	(°C) / (°F)	Display	Displays the temperature unit.

- When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB. Do not use this SMART Active Part on the initial screen.
- Use System version 5 or higher version.

(24) Alarm 1 Type, Alarm 1 Open/Close in Alarm, Alarm 1 Hysteresis, Alarm 1 Latch

Setting level	Input type	Part
Initial setting level	Thermocouple input	No
	Platinum-resistance thermometer	No
	Common(Common)	Yes

Unit ty		E5AN, E5EN, E5CN, E5GN Stora		•		Alarm 1 Type, Open/Close in Alarm, Hysteresis, Latch			
Funct	Function Sets the alarm type, open/close in alarm operation, latch, and hysteresis for alarm 1.								
Displa	ay and Operation	Details							
	Alarm1 Type 99 Type(0-11) 3								
No.	Item	Setting/ display			Desc	cription			
1	Alarm 1 Type	Display	Displays	the alarm type that	is set.				
2	Alarm 1 Type Setting Button	Setting	When pressed, displays the alarm type setting menu. Select the alarm type from the menu.						
3	Alarm 1 open/close in Alarm	Setting	Sets open in alarm or close in alarm for the alarm output.						
4	Alarm 1 Hysteresis (°C) / (°F)	Setting Display	Sets ON/OFF hysteresis for the alarm output. Displays the temperature unit.						
5	Alarm 1 Latch	Setting	Sets who	Sets whether to latch the alarm output status.					

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

(25) Alarm 2 Type, Alarm 2 Open/Close in Alarm, Alarm 2 Hysteresis, Alarm 2 Latch

Setting level	Input type	Part
Initial setting level	Thermocouple input	No
	Platinum-resistance thermometer	No
	Common(Common)	Yes

Unit type	E5AN, E5EN, E5CN	Storage directory			Title	Alarm 2 Type, Open/Close in Alarm, Latch, Hysteresis
Function	ction Sets the alarm type, open/close in alarm operation, latch, and hysteresis for alarm 2.					
Display an	d Operation Deta	ails				
	1-	Alarm:	2 Туре	99	Туре(0-)	<u>√</u> 2
	3-	_	2open/ in Alarm	Close	0pen	
	4 -	Alarm: Hyster	2 esis (%)	999.9		
	5-	Alarm:	2 Latch	0FF	ON	

No.	Item	Setting/ display	Description
1	Alarm 2 Type	Display	Displays the alarm type that is set.
2	Alarm 2 Type Setting Button	Setting	When pressed, displays the alarm type setting menu. Select the alarm type from the menu.
3	Alarm 2 open/close in Alarm	Setting	Sets open in alarm or close in alarm for the alarm output.
4	Alarm 2 Hysteresis (°C) / (°F)	Setting Display	Sets ON/OFF hysteresis for the alarm output. Displays the temperature unit.
5	Alarm 2 Latch	Setting	Sets whether to latch the alarm output status.

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

(26) Alarm 3 Type, Alarm 3 Open/Close in Alarm, Alarm 3 Hysteresis, Alarm 3 Latch

Setting level	Input type	Part
Initial setting level	Thermocouple input	No
	Platinum-resistance thermometer	No
	Common(Common)	Yes

Unit ty			SmartActiveParts_E\ TemperatureControll er\E5[]N\InitialSetting Level		Title	Alarm 3 Type, Open/Close in Alarm, Hysteresis, Latch			
Funct	Function Sets the alarm type, open/close in alarm operation, latch, and hysteresis for alarm 3.								
Displa	Display and Operation Details								
Alarm3 Type 99 Type(0-11) Alarm3 open/close in Alarm Close Open Alarm3 (%) 999.9 Alarm3 Latch OFF ON									
No.	Item	Setting/ display			Desc	cription			
1	Alarm 3 Type	Display	Displa	ays the alarm type that i	is set.				
2	Alarm 3 Type Setting Button	Setting	When pressed, displays the alarm type setting menu. Select the alarm type from the menu.						
3	Alarm 3 open/close in Alarm	Setting	Sets open in alarm or close in alarm for the alarm output.						
4	Alarm 3 Hysteresis (°C) / (°F)	Setting Display	Sets ON/OFF hysteresis for the alarm output. Displays the temperature unit.						
5 Rema	Alarm 3 Latch	Setting	Sets	whether to latch the ala	rm output s	status.			

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- Use System version 5 or higher version.

1.1.4 Advanced Function Setting Level

(27) SP Ramp

Setting level	Input type	Part
CPU Bus Units Setting level	Thermocouple input	Yes
	Platinum-resistance thermometer	Yes
	Common(Common)	No

Unit type	E5AN, E5EN, E5CN, E5GN	Storage SmartActiveParts_E\ TemperatureControll er\E5[]N\AdvancedFu nctionSettingLevel		Title	SP Ramp	
Function	Sets the rate of change for the SP ramp.					

Display and Operation Details



No.	Item	Setting/ display	Description	
1	SP Ramp	Setting	Sets the maximum allowed change per minute. Set 0 to disable the SP ramp function.	
2	(°C/min)/(°F/min)	Display	Displays the temperature unit.	

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- Use System version 5 or higher version.

(28) Multi-SP ON/OFF

Setting level	Input type	Part
Advanced function setting level	Thermocouple input	No
	Platinum-resistance thermometer	No
	Common(Common)	Yes

Unit ty	Init type E5AN, E5EN, E5CN, E5GN Storage directory				Title	Multi-SP ON/OFF		
Func	Function Sets whether the set point can be switched.							
Displ	ay and Ope	ration Deta	ils					
		1 -	→ Mu	lti-SP	OFF [ON		
No.	Item		tting/ splay	Description				
1	Multi-S	D S		Sets whether the set point can be switched. Set ON to enable switching.				
'	Multi-0			Set OFF to disable switching.				
Rema	Remarks							

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

(29) HBA Used, Heater Burnout Latch, Heater Burnout Hysteresis

Setting level	Input type	Part
Advanced function setting level	Thermocouple input	No
	Platinum-resistance thermometer	No
	Common(Common)	Yes

Unit type	E5AN, E5EN, E5CN	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5[]N\AdvancedFu nctionSettingLevel	Title	HBA Used, Latch, Hysteresis		
Function	Function Turns the heater burnout detection ON/OFF, turns the latch ON/OFF, and sets the hysteresis.						

Display and Operation Details



No.	Item	Setting/ display	Description
1	HBA Used	Setting	Sets whether to use the heater burnout detection function.
2	Heater Burnout Latch	Setting	Sets whether to latch the heater burnout alarm.
3	Heater Burnout Hysteresis	Setting	Sets the hysteresis for heater burnout detection.

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- Use System version 5 or higher version.

(30) MV Upper/Lower Limits and Input Digital Filter

Setting level	Input type	Part
Advanced function setting level	Thermocouple input	No
	Platinum-resistance thermometer	No
	Common(Common)	Yes

Unit type	E5AN, E5EN, E5CN, E5GN	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5[]N\AdvancedFu nctionSettingLevel	Title	MV Upper/Lower Limits and Input Digital Filter			
Function	Sets the upper and lower limits for the manipulated variable							
Display an	Display and Operation Details							



No.	Item	Setting/ display	Description
1	MV Upper Limit	Setting	Sets the upper limit of the manipulated variable. If the calculated manipulated variable is greater than the upper limit, it will be restricted to the upper limit.
2	MV Lower Limit	Setting	Sets the lower limit of the manipulated variable. If the calculated manipulated variable falls below the lower limit, it will be restricted to the lower limit.
3	Input Digital Filter	Setting	Sets the time constant for the input digital filter.

- When using this SMART Active Part, be sure to select Setting System Settings in the menu bar, press the System Memory List Button on the Initial Tab Page, and select Basics for the \$SB.
- Do not use this SMART Active Part on the initial screen.
- Use System version 5 or higher version.

(31) Standby Sequence Restart

Setting level	Input type	Part
Advanced function setting level	Thermocouple input	No
	Platinum-resistance thermometer	No
	Common(Common)	Yes

Unit type	E5AN, E5EN, E5CN, E5GN	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5[]N\AdvancedFu nctionSettingLevel	Title	Standby Sequence Restart	
Function						

Display and Operation Details



No.	Item	Setting/ display	Description
1	Standby Sequence Reset	Setting	Select Condition A or Condition B.

- When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

(32) α

Setting level	Input type	Part
Advanced function setting level	Thermocouple input	No
	Platinum-resistance thermometer	No
	Common(Common)	Yes

1 1	α Se	etting Sets	s $lpha$ set value.					
No.	dis	tting/ splay		Desc	ription			
	1 — Φ α 9.99							
p.w, w.	1 -		9,99					
Display a	 nd Operation Deta	ails						
Function	Sets the α const	ant for adva	nced PID control.					
Unit type	E5AN, E5EN, E5CN, E5GN	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5[]N\AdvancedFu nctionSettingLevel	Title	α			

- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- Use System version 5 or higher version.

(33) Input Error Output

Setting level	Input type	Part
Advanced function setting level	Thermocouple input	No
	Platinum-resistance thermometer	No
	Common(Common)	Yes

Unit ty	e5AN, E5EN E5CN, E5G		age Temp etory er\E5	tActiveParts_E\ eratureControll []N\AdvancedFu nSettingLevel	Title	Input Error Output			
Func	Function Sets whether to output an alarm when a sensor input error occurs.								
Displ	ay and Operation	Details							
			Output Input Error	OFF (ON				
				,		_			
No.	Item	Setting/ display		Description					
1	Output Input	Setting		Sets whether to enable outputting an alarm on the alarm 1 output when a sensor error is detected. Set ON to enable output and OFF to disable output.					

- When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

(34) Cold Junction Compensation Method

Setting level	Input type	Part
Advanced function setting level	Thermocouple input	No
	Platinum-resistance thermometer	No
	Common(Common)	Yes

Unit type	E5AN, E5EN, E5CN, E5GN	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5[]N\AdvancedFu nctionSettingLevel	Title	Cold Junction Compensation Method				
Function	Sets the cold jun		nsation method.						
Display an	Display and Operation Details								



No.	Item	Setting/ display	Description
1	Cold Junction Compensation Method	Setting	Set whether to perform cold junction compensation inside the Temperature Controller or externally.

- When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- Do not use this SMART Active Part on the initial screen.
- Use System version 5 or higher version.

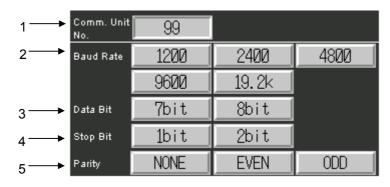
1.1.5 Communications Setting Level

(35) Communications Settings

Setting level	Input type	Part
Communications Settings	Thermocouple input	No
level	Platinum-resistance thermometer	No
	Common(Common)	Yes

Unit type	E5AN, E5EN, E5CN, E5GN	Storage directory	SmartActiveParts_E\ TemperatureControll er\E5[]N\Communicat ionsSettingLevel	Title	Communications Settings
Function	The following set length: 7 bits, Sto	ttings are use op bits: 2 bits	s, Parity: even.	IS-series F	ings. PT to the Temperature Controller: Data nunicate with any other settings.

Display and Operation Details



No.	Item	Setting/ display	Description
1	Comms. Unit No.	Setting	Sets the communications unit number. Set a different unit number for each Temperature Controller.
2	Baud Rate	Setting	Sets the baud rate. Set the NS-series PT and all connected Temperature Controllers to the same setting.
3	Data Bit	Setting	Sets the communications data length. A data length of 7 bits is used to connect an NS-series PT to the Temperature Controller.
4	Stop Bit	Setting	Sets the number of communications stop bits. Two stop bits are used to connect an NS-series PT to the Temperature Controller.
5	Parity	Setting	Sets the communications parity. Even parity is used to connect an NS-series PT to the Temperature Controller.

- * The PT and the Temperature Controller will not be able to communicate unless the following settings are used: Data length: 7 bits, Stop bits: 2 bits, Parity: even.
- * When using this SMART Active Part, be sure to select **Setting System Settings** in the menu bar, press the **System Memory List** Button on the **Initial Tab** Page, and select **Basics** for the \$SB.
- * Do not use this SMART Active Part on the initial screen.
- * Use System version 5 or higher version.

1.1 Smart Active Parts (from Ver5 or Earlier)

1.1.1 SP Setting 00 to 15

Model	E5ZN-DRT	Location	peratu		rts_E\Tem ller\E5ZN\	Title	SP Setting 00 to 15	
Function	on E5ZN-DRT by pres performed when it is	Performs reading and writing from and to SP for the maximum 16 temperature controllers connected to the E5ZN-DRT by pressing buttons. Reading and writing from and to E5ZN temperature controller cannot be performed when it is not connected to the E5ZN-DRT or a communication error has been occurred.						
[Image								
	E	ZN Temper:	ature Cor	ntroller	SP Sett	ing		
	Inpu	ıt Value	100	C	Copy to Al	1	— 1 — 2	
		Sext	Input		Set	Input		
	<u>00ch1</u>			Ø8ch1			3	
	<u>00ch2</u>			Ø8ch2				
	01ch1			Ø9ch1				
	01ch2			09ch2				
	<u>Ø2ch1</u> Ø2ch2			10ch1 10ch2				
	Ø3ch1			11ch1				
	Ø3ch2			11ch2				
	04ch1		Ö					
	Ø4ch2			12ch2				
	Ø5ch1			13ch1				
	Ø5ch2			13ch2				
	<u>06ch1</u>			14ch1				
	<u>06ch2</u>	-		14ch2				
	07ch1			15ch1				
	07ch2			15ch2			4	
		Read (Set->	Input\	Wr	i te	5	
	_						6	
		Setting/						
No.	Item	Display				Detail	S	
1	Copy to All Device (Copy to All)	Setting			•	•	value for each Ch.	
2	Set Value (Set)	Display	be updated	d when re	ading or wr	iting value		
3	Input Value (Input)	5				•	rature controller.	
4	Read				t value disp	-		
5	Write	Setting	Write input values to the SP. After writing the values, those will be read to the columns under Set.					
6	Set -> Input	Setting	Sets value	s under S	Set to the In	put.		
[Note] Set 6 s	seconds or more for Comn	n.Time-Out i	n the PT w	hen usinç	g those Sma	art Active	Parts.	

1.1.2 PID Setting (Unit 0 to 7)

Model	E5ZN-DRT	Location	r5toearlier		PID Setting (Unit 0 to 7)
Function	buttons. Reading and	writing from		ntroller o	nnected to E5ZN-DRT by pressing annot be performed when it is not .

[Image]

Input Value	E5ZN	√ Tempera	iture Cont	roller PI	D Setting	g (Unit 0	to 7)				
Set Value	Input	Lipput Maluo Harris Har									
00ch1 8.0 233 40 16.0 466 80 00ch2 8.0 233 40 16.0 466 80 01ch1 4.0 116 20 16.0 466 80 01ch2 2.0 58 10 16.0 466 80 02ch1 0.0 0 0 8.0 233 40 02ch1 0.0 0 0 8.0 233 40 03ch2 0.0 0 0 0 0 0 0 03ch2 0.0 0 0 0 0 0 0 0 04ch1 0.0 0 0 0 0 0 0 0 0 05ch2 0.0 0 0 0 0 0 0 0 0 0 0 0 07ch2 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 <td< td=""><td>[</td><td colspan="10">Set Value Input Value</td></td<>	[Set Value Input Value									
00ch2 8.0 233 40 16.0 466 80 01ch1 4.0 116 20 16.0 466 80 01ch2 2.0 58 10 16.0 466 80 02ch1 0.0 0 0 8.0 233 40 02ch2 0.0 0 0 8.0 233 40 03ch2 0.0 0 0 0.0 0 0 0 03ch1 0.0 0 0 0.0 0 0 0 0 03ch2 0.0 0 0 0 0 0 0 0 0 04ch1 0.0 0		Р	I	D	Р	I	D				
Ø1ch1 4.0 116 20 16.0 466 80 Ø1ch2 2.0 58 10 16.0 466 80 Ø2ch1 0.0 0 0 8.0 233 40 Ø2ch2 0.0 0 0 8.0 233 40 Ø3ch1 0.0 0 0 0.0 0 0 Ø3ch2 0.0 0 0 0.0 0 0 Ø4ch1 0.0 0 0 0 0 0 0 Ø5ch1 0.0 0 0 0 0 0 0 0 Ø6ch2 0	00ch1										
01ch2 2.0 58 10 16.0 466 80 02ch1 0.0 0 0 8.0 233 40 02ch2 0.0 0 0 0 233 40 03ch1 0.0 0 0 0 0 0 0 03ch2 0.0 0	00ch2										
02ch1 0.0 0 0 8.0 233 40 02ch2 0.0 0 0 8.0 233 40 03ch1 0.0 0 0 0.0 0 0 03ch2 0.0 0 0 0.0 0 0 04ch1 0.0 0 0 0.0 0 0 04ch2 0.0 0 0 0 0 0 0 05ch1 0.0 0 0 0 0 0 0 0 0 06ch2 0 <td>01ch1</td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td>	01ch1										
02ch2 0.0 0 0 8.0 233 40 03ch1 0.0 0 0 0.0 0 0 03ch2 0.0 0 0 0 0 0 0 04ch1 0.0 <	Ø1ch2	2.0	58	10	16.0	466	80				
Ø3ch1 Ø.0 Ø </td <td>Ø2ch1</td> <td>0.0</td> <td>0</td> <td>0</td> <td>8.0</td> <td>233</td> <td>40</td> <td></td>	Ø2ch1	0.0	0	0	8.0	233	40				
03ch2 0.0 0 0.0 0 0 04ch1 0.0 0 0 0.0 0 0 04ch2 0.0 0 0 0 0 0 05ch1 0.0 0 0 0 0 0 05ch2 0.0 0 0 0 0 0 06ch1 0 0 0 0 0 0 07ch1 0 0 0 0 0 0	Ø2ch2	0.0	0	0	8.0	233	40				
04ch1 0.0 0 0.0 0 04ch2 0.0 0 0 0.0 0 05ch1 0.0 0 0 0 0 05ch2 0.0 0 0 0 0 06ch1 07ch1 07ch2	Ø3ch1	0.0	0	0	0.0	0	0				
04ch2 0.0 0 0.0 0 0 05ch1 0.0 0 0 0.0 0 0 05ch2 0.0 0 0 0 0 0 06ch1 0 0 0 0 0 07ch1 0 0 0 0 0	Ø3ch2	0.0	0	0	0.0	0	0				
Ø5ch1 Ø.0 Ø Ø Ø Ø Ø Ø5ch2 Ø.0 Ø Ø Ø Ø Ø Ø Ø6ch1 Ø </td <td>Ø4ch1</td> <td>0.0</td> <td>0</td> <td>0</td> <td>0.0</td> <td>0</td> <td>0</td> <td></td>	Ø4ch1	0.0	0	0	0.0	0	0				
05ch2 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Ø4ch2	0.0	0	0	0.0	0					
06ch1 06ch2 07ch1 07ch2	Ø5ch1	0.0	0	0	0.0						
06ch2 07ch1 07ch2		0.0	0	0	0.0	0	0				
07ch1 07ch2	Ø6ch1										
07ch2 4	-										
4	=										
D = 1/	07ch2										
kead Set ->Input \ Write 5	D	- 0-1		0-4 \1-		1.1.	1				
	R	eaa		Set ->In	put \	WI	rite	— 5			

No.	Item	Setting/ Display	Details
1	Copy to All	Setting	The set input values on top to the input values for each Ch.
2	Set Value	Display	Displays the read values in the PID from E5ZN temperature controller. The value will be updated when reading or writing values.
3	Input Value	Setting	Set PID to be written to the E5ZN temperature controller. Text and background color will be changed if a value out of range has been set.
4	Read	Setting	Reads values set for PID to the columns under Set Value.
5	Write	Setting	Writes input values to PID in the E5ZN temperature controller. Those will be read to columns under Set Value after writing values.
6	Set -> Input	Setting	Sets set values to input values.

[Note]

- 1. Set 6 seconds or more for Comm. Time-Out in the PT when using those Smart Active Parts. Also, select **Settings-Unit** & **Scale** Setting and set 0.1 for the scale at the unit No. 1000 when using those parts library.
- 2. Please use E5ZN Temperature Controller PID Setting (Unit 08 to 15) for Temperature Controller unit 08 to 15.

1.1.3 RUN/STOP Command

Model	E5ZN-DRT	Location	erature r5toea		5ZN\Ve	Title	RUN/ST		
Function	controllers connect executed for all	Executes control start (RUN) and control stop (STOP) commands for the maximum 16 temperature controllers connected to the E5ZN-DRT. Control start (RUN) and control stop (STOP) commands can be executed for all temperature controllers at once and for each unit by word (Ch) individually. These commands cannot be executed for E5ZN temperature controller which is not connected or a communication error is occurred.							
[Image]									
	E52	'N Tempera	ture Contr	oller RUN	I/STOP C	ommand		_ 1	
	RUN AL	L R	UN /	STOR	ALL	ST0	P —	_ 2	
	<u>00ch1</u> 00c RUN RI		<u>Ø1ch2</u>		00ch2 STOP	101ch1 STOP	Ø1ch2	3	
	RUN RI 192ch1 192c			STOR 102ch1	02ch2	03ch1	STOP Ø3ch2	– 4	
	RUN RI		RUN	STOP	STOP	STOP	STOP	·	
	Ø4ch1 Ø4c					Ø5ch1	Ø5ch2		
	RUN RI		RUN	STOP	STOP	STOP	STOP		
	Ø8ch1 Ø8c			Ø8ch1		Ø9ch1	Ø9ch2		
	RUN RI		RUN	STOP	STOP	STOP	STOP		
	10ch1 10c	h2 11ch1	11ch2	10ch1	10ch2	11ch1	11ch2		
	RUN RI		RUN	STOP	STOP	STOP	STOP		
	12ch1 12c			12ch1	12ch2	13ch1	13ch2		
	RUN RI [14ch1] [14c		RUN 15ch2	STOP 14ch1	STOP 14ch2	STOP 15ch1	STOP 15ch2		
	RUN RI		RUN	STOP	STOP	STOP	STOP		
No.	Item	Setting/ Display				Detai	ls		
1	RUN ALL	Setting	connected	to E5ZN-DF	RT.	,	•	temperature	
2	ALL STOP	Setting	Executes step control command (STOP) for all temperature controllers						controllers
3	RUN Setting Executes start control (RUN) for word in an appropriate Unit No.								
4	STOP	Setting	Executes s	top control	(STOP) fo	or word in	an appro	priate Unit No.	
	4 STOP Setting Executes stop control (STOP) for word in an appropriate Unit No. [Note] Set 6 seconds or more for <i>Comm.Time-Out</i> in the PT when using those Smart Active Parts.								

Temperature Controller (from Ver5 or earlier)

1.1.4 AT Execute/Stop

Model	E5ZN-DRT	Location	perat	rtActivePar ureContro toearlier			AT Exec	cute/Stop		
Function	Executes AT Exec E5ZN-DRT. AT exe each unit by word which is not connec	ecute/Stop c Ch) individua	ommands ally. These	can be execute comman	kecuted fo ds cannot	or all temp	perature o	controllers at onc	e and for	
[Image]	_									
	E5ZN Tei	nperature (Controll	er AT Ex	ecute/St	op Comma	and			
	Execute A	11 Execu	ute	St	op All	Sto	р —	1 2		
	00ch1) 00ch	2 Ø1ch1	Ø1ch2	<u>00ch1</u>	<u>00ch2</u>	Ø1ch1	Ø1ch2	3		
	Exec. Exec	Exec.	Exec.	Stop	Stop	Stop	Stop			
	Ø2ch1 Ø2ch	2 Ø 3ch1	Ø3ch2	Ø2ch1	√ <u>Ø2ch2</u>	Ø3ch1	Ø3ch2	4		
	Exec. Exec	. Exec.	Exec.	Stop	Stop	Stop	Stop			
	04ch1 04ch	2 Ø 5ch1	Ø5ch2	Ø4ch1	Ø4ch2	Ø5ch1	Ø5ch2			
	Exec. Exec	Exec.	Exec.	Stop	Stop	Stop	Stop			
	06ch1 06ch	2 Ø 7ch1	Ø7ch2	Ø6ch1	Ø6ch2	Ø7ch1	Ø7ch2			
	Exec. Exec	Exec.	Exec.	Stop	Stop	Stop	Stop			
	Ø8ch1 Ø8ch	2 Ø 9ch1	Ø9ch2	Ø8ch1	Ø8ch2	Ø9ch1	Ø9ch2			
	Exec. Exec	Exec.	Exec.	Stop	Stop	Stop	Stop			
	10ch1 10ch	2 11ch1	11ch2	10ch1	10ch2	11ch1	11ch2			
	Exec. Exec	Exec.	Exec.	Stop	Stop	Stop	Stop			
	12ch1 12ch	2 [13ch1]	13ch2	12ch1	12ch2	13ch1	13ch2			
	Exec. Exec	Exec.	Exec.	Stop	Stop	Stop	Stop			
	14ch1 14ch	2 [15ch1]	15ch2	14ch1	14ch2	15ch1	15ch2			
	Exec. Exec	Exec.	Exec.	Stop	Stop	Stop	Stop			
No.	Item	Setting/ Display				Deta				
1	Execute All	Setting	Executes AT execute command for the maximum 16 temperature controllers connected to the E5ZN-DRT.							
2	Stop All	Setting	Executes AT stop command for the maximum 16 temperature controllers connected to the E5ZN-DRT.							
3	Execute	Setting	Executes AT execute command for word in an appropriate Unit No.							
4	Stop	Setting	Executes	AT stop c	ommand f	or word in	an appro	priate Unit No.		
[Note] Set 6 seco	nds or more for Com n	n.Time-Out i	n the PT v	hen using	those Sm	art Active	Parts.			

1.1.5 Auto/Manual

Model	E5ZN-DRT	Location	n peratur Ver5toe		Title	Auto/Manual				
Function	Auto/Manual comm (Ch) individually. T	Executes Auto/Manual commands for the maximum 16 temperature controllers connected to the E5ZN-DRT. Auto/Manual commands can be executed for all temperature controllers at once and for each unit by word (Ch) individually. These commands cannot be executed for E5ZN temperature controller which is not connected or a communication error is occurred.								
[Image]										
	E5ZN	Temperat	ure Contro	ller Auto/Manua	1 Comman	nd				
		\rightarrow			_	1				
	Auto Al		Auto /	Manual All		ual 2				
	00ch1/ 00c	n2 Ø1ch	1 Ø1ch2	<u>00ch1 00ch2</u>	<u> Ø1ch1</u>] Ø1ch2 - 3				
	Auto Au	to Aut	o Auto	Manu. Manu.	Manu.	Manu.				
	Ø2ch1 Ø 2c	n2] Ø 3ch	1 Ø3ch2	02ch1 02ch2	Ø 3ch1	<u>03ch2</u> 4				
	Auto Au	to Aut	o Auto	Manu. Manu.	Manu.	Manu.				
	04ch1 04c	n2 Ø 5ch	1 Ø5ch2	0 4ch1 0 4ch2	Ø 5ch1					
	Auto Au	to Aut	o Auto	Manu, Manu,	Manu.	Manu.				
	Ø6ch1 Ø6c	n2 0 7ch	1 07ch2	Ø6ch1 Ø6ch2	07ch1	07ch2				
	Auto Auto Auto Manu, Manu, Manu, Manu,				Manu.					
	Ø8ch1 Ø8c	n2 0 9ch	1 Ø9ch2	Ø8ch1 Ø8ch2		<u> </u>				
	Auto Au	to Aut	o Auto	Manu. Manu.	Manu.	Manu.				
	10ch1 10c	n2 11ch	1 11ch2	10ch1 10ch2	11ch1	11ch2				
	Auto Au	to Aut	o Auto	Manu. Manu.	Manu.	Manu.				
	12ch1 12c	n2 13ch	1 13ch2	12ch1 12ch2	13ch1	13ch2				
	Auto Au	to Aut	o Auto	Manu. Manu.	Manu.	Manu.				
	14ch1 14c	n2 15ch	1 15ch2	14ch1 14ch2	15ch1	15ch2				
	Auto Au	to Aut	o Auto	Manu, Manu,	Manu.	Manu.				
-										
No.		Setting/ Display			Detai	ils				
1	Auto All	Setting		tomatic operation connected to the E5		for the maximum 16 temperature				
2		Setting	controllers c	onnected to the E52	ZN-DRT.	the maximum 16 temperature				
3		Setting				for word in an appropriate Unit No.				
4	Manual	Setting	Executes ma	anual operation con	mand for	word in an appropriate Unit No.				
Set 6 sec	[Note] Set 6 seconds or more for <i>Comm.Time-Out</i> in the PT when using those Smart Active Parts.									

1.1.6 Setting Area 0 for Unit 0

Model	E5ZN-DR	Γ	Loc	cation	perati	tActiveParts_E\ToureController\E52 oearlier		itle	Setting Ar	ea 0 for l	Unit 0	
Function Performs reading and writing from and to setting area o for temperature controller connected by pressing buttons. Reading and writing from and to E5ZN temperature controller cannot when it is not connected to the E5ZN-DRT or a communication error has been occurred library for each unit.											ot be performed	
[lmage]	[lmage]											
	E5ZN Temperature Controller Setting Area 0 for Unit 0											
	[CH1		CH2				H1	T CI-	12	— 1 — 2	
			p y t		Input		Set	Input		Input	— 2 — 3	
SP		90	100	70	200	Temperature					— 4	
Alai	rm Value1	0	80	0	0	Input Offset	0.0	0.	0.0	0.0		
∐рре Lоме		0	90 70	0	0	Upper Limit Tem. Offset	0.0	0.	0.0	0.0		
	rm Value2 er Limit2	0	0	0	0	Lower Limit Tem. Offset	0.0	0.	0.0	0.0		
	er Limit2	Ö	ă	Ö	ă	PropotionalB	4.0	8.	0 8.0	16.0		
	rm Value3	Ö	ă	Ö	Ŏ	IntegralTime	116			466		
	ualMani.V	0.0	0.0	0.0	0.0	Derivative T	20		0 40	80		
	ter Burn.	0.0	0.0	0.0	0.0	Cooling Coe.	5.00			20.00		
SPØ		0	0	0	0	Dead Band	0.0			0.0		
SP1		0	0	0	0	Manua 1RstVa 1	0.0	0.	0.0	0.0		
						Heating Hysteresis	5.0	10.	0 10.0	20.0		
						Cooling Hysteresis	5.0	10.	0 10.0	20.0	5 6	
	CH1/CH2				ÇH1				H2		_	
	Read		Se	t->Inpu	ut [Write /	Set-	>Input	Wri	te —	— <u>9</u>	
			Sattii	1							·	

No.	Item	Setting/ Display	Details
1	CH1 Set	Display	Displays value for setting area o read from CH1. The value will be updated when reading/writing.
2	CH1 Input	Setting	Sets value for setting area 0 to the CH1. T Text and background color will be changed if a value out of range has been set.
3	CH2 Set	Display	Displays value for setting area o read from CH2. The value will be updated when reading/writing.
4	CH2 Input	Setting	Sets value for setting area 0 to the CH1. T Text and background color will be changed if a value out of range has been set.
5	CH1/CH2 Read	Setting	Reads setting area 0 settings in the CH1/2 and displays them in the columns under Set.
6	CH1 Set -> Input	Setting	Set values displayed in the columns under Set to appropriate columns under Input.
7	CH1 Write	Setting	Writes input values for CH1 to setting area 0. The values will be read columns under Set after writing those.
8	CH2 Set-> Input	Setting	Set values displayed in the columns under Set to appropriate columns under Input.
9	CH2 Write	Setting	Writes input values for CH2 to setting area 0. The values will be read columns under Set after writing those.

[Note]
Set 6 seconds or more for *Comm.Time-Out* in the PT when using those Smart Active Parts.
Select *Settings-Unit & Scale* Setting and set 0.1 for the scale at the unit No. 1000 when using those parts.

1.1.7 Setting Area 0 (Unit 0 to 15)

Model	E5ZN-DRT	Location	SmartActiveParts_E\Tem peratureController\E5ZN\ Ver5toearlier Setting Area 0 (Unit 0 to 15)
Function	n by pressing buttons when it is not conne	s. Reading ar	m and to setting area o for temperature controller connected to E5ZN-DRT and writing from and to E5ZN temperature controller cannot be performed 5ZN-DRT or a communication error has been occurred.
[Image]			
			1
	No. $1 \square / \boxed{E5ZN}$	l Temperatu	re Controller Setting Area 0 (Unit 0 to 15)
		4	H2 CH1 CH2 3
		npyt Se <i>t</i>	Input Set Input 4
	SP / Ø	/0 /15	5 15 Temperature 1
	Alarm Value1 0	0 15) In bar ouser
	Upper Limit1 0 Lower Limit1 0	0 20 0 10	
	Alarm Value2 0	0 0	Lower Limit an an an
	Upper Limit2 0	0 0	y William Offset
	Lower Limit2 0 Alarm Value3 0	0 0	
	ManualMani.V 0.0	0.0 0.0	
	Heater Burn. 0.0	0.0 0.0	
	SP Ø Ø	0 0	
l	SP 1 0	0 0	1 0 ManualRstVal 0.0 0.0 0.0 0.0
			Heating Hysteresis 0.0 10.0 0.0 10.0
	_		Cooling and to a decomposition of
	CH1/CH2		QA1
	Read /	Set->In	put Write / Set->Input Write — 10
No.	Item	Setting/	Details
1	Unit No.	Display Setting	nput unit No. to be displayed/set.
		,	Displays value for setting area o read from CH1. The value will be updated
2	CH1 Set	Display	when reading/writing.
3	CH1 Input		Sets value for setting area 0 to the CH1. T Text and background color will be changed if a value out of range has been set.
4	CH2 Set	Dienlay	Displays value for setting area o read from CH2. The value will be updated when reading/writing.
5	CH2 Input	Setting	Sets value for setting area 0 to the CH1. T Text and background color will
	·	١	pe changed if a value out of range has been set. Reads setting area 0 settings in the CH1/2 and displays them in the
6	CH1/CH2 Read		columns under Set.
7	CH1 Set -> Input		Set values displayed in the columns under Set to appropriate columns under Input.
8	CH1 Write	Setting	Writes input values for CH1 to setting area 0. The values will be read
9	CH2 Set-> Input	Setting	Set values displayed in the columns under Set to appropriate columns
10	CH2 Write	Setting	Unites input values for CH2 to setting area 0. The values will be read
		(columns under Set after writing those.

Temperature Controller (from Ver5 or earlier)

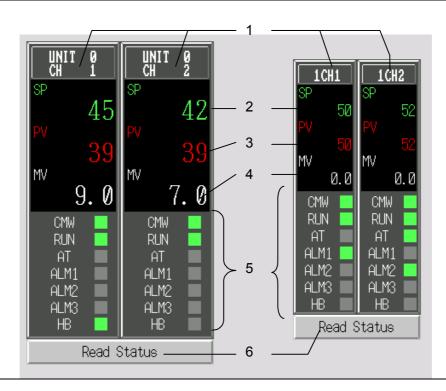
[Note]

Set 6 seconds or more for *Comm.Time-Out* in the PT when using those Smart Active Parts.
Select *Settings-Unit & Scale Setting* and set 0.1 for the scale at the unit No. 1000 when using those parts.

1.1.8 FrontPanel(L) Unit 0 / FrontPanel(S) Unit 0

Model	E5ZN-DRT	Location	SmartActiveParts_E\Temp eratureController\E5ZN\Ve r5toearlier/FrontPanel(L) FrontPanel(S)	Title	FrontPanel(L) Unit 0 / FrontPanel(S) Unit 0			
Function	,	status of the E5ZN temperature controller connected to the E5ZN-DRT. The status cannot be resonant connected to the E5ZN or a communication error had been occurred.						

[lmage]



No.	Item	Setting/ Display	Details
1	Unit No./CH type	Display	Displays unit No. and CH type which is being monitored.
2	SP	Display	Sets SP read from CH1/CH2 of the E5ZN temperature controller. The value will be updated when performing read status.
3	PV (Present Value)	Display	Sets the present value read from CH1/CH2 of the E5ZN temperature controller. The value will be updated when performing read status.
4	MV (Manipulated Variable)	Display	Sets manipulated variable read from CH1/CH2 of the E5ZN temperature controller. The value will be updated when performing read status.
5	Status	Display	Sets status read from CH1/CH2 in the E5ZN temperature controller. The value will be updated when performing read status.
6	Read Status	Setting	Read SP, present value, manual manipulated variable, and status from CH1/CH2 in the E5ZN temperature controller.

[Note]

Set 6 seconds or more for *Comm.Time-Out* in the PT when using those Smart Active Parts.
Select *Settings-Unit & Scale Setting* and set 0.1 for the scale at the unit No. 1000 when using those parts.

Temperature Controller (from Ver5 or earlier)

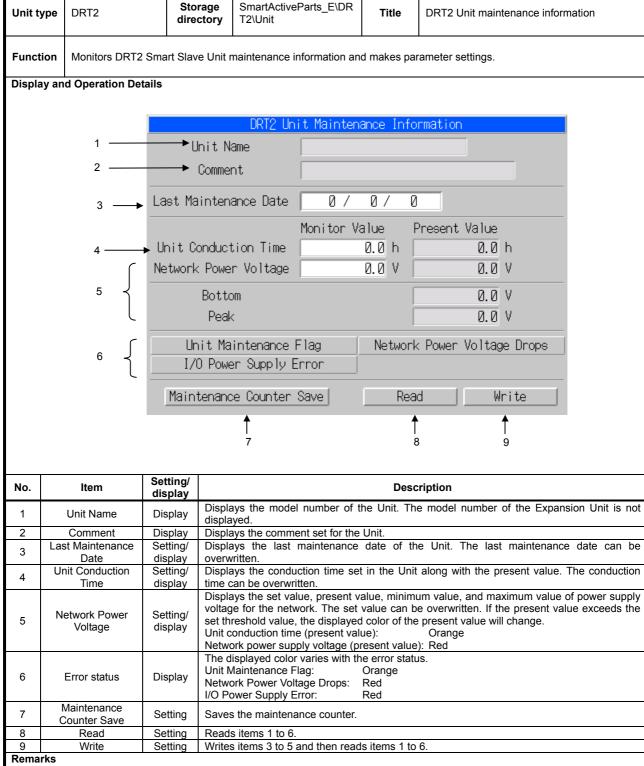
1.1.9 PV Hold

Model	E5ZN-DRT	Location	SmartActiveParts_E\Temp eratureController\E5ZN\Ve r5toearlier/PVHold	Title	PV Hold				
Functio	Executes PV hold or for E5ZN temperatu	ommand, read re controller w	nds PV for each unit and display which is not connected or a com	/s them imunication	This command cannot be executed on error is occurred.				
[Image	;]								
			E5ZN PV Hold V Hold Execution	<u> </u>					
Value Walue Walu									
		Read	id	— 3					
 	Г	Setting/							
No.		Display		Details					
1	PV Hold Execution	Setting to	Executes PV hold command for all E5ZN temperature controllers connected to the E5ZN-DRT.						
2	PV Hold Value (Value)	Display Di	Displays PV hold value read from the E5ZN temperature controller.						
3	Read	Setting R	Reads PV hold value saved in ar	n E5ZN te	emperature controller.				
	[Note] Set 6 seconds or more for <i>Comm.Time-Out</i> in the PT when using those Smart Active Parts.								



1.1. DRT2

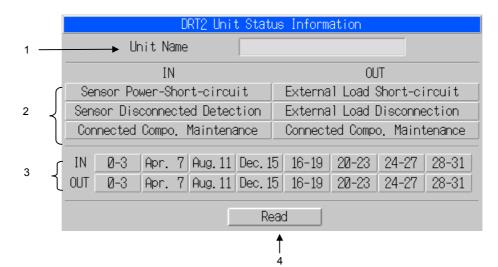
1.1.1 Unit Maintenance Information



- When the Smart Active Parts is reused, the unit number must be specified. If there is more than one slave unit in the DeviceNet, specify the slave unit numbers.
- Use this display in system version 5.

1.1.2 Unit Status Information

Unit type	DRT2	Storage directory	SmartActiveParts_E\DR T2\Unit	Title	DRT2 Unit status information				
Function	Function Monitors the Unit status of a DRT2 Smart Slave.								
Display and Operation Details									



No.	Item	Setting/ display	Description
1	Unit Name	Display	Displays the model number of the Unit. The model number of the Expansion Unit is not displayed.
2	Status summary	Display	The corresponding item will change color if the Unit has an error. The status summary displayed varies with the Unit. If the Unit monitored has no status, the status summary will not be displayed. IN Sensor Power-Short-circuit: Red IN Sensor Disconnected Detection: Red IN Connected Compo. Maintenance: Orange OUT External Load Short-circuit: Red OUT External Load Disconnection: Red OUT Connected Compo. Maintenance: Orange
3	Bit summary	Display	Displays the errors four bits at a time. The corresponding item will change in color if the Unit has an error. The status summary displayed varies with the Unit. If the Unit monitored does not support the status bits, the status summary will not be displayed. IN Sensor Power-Short-circuit: Red IN Sensor Disconnected Detection: Red IN Connected Compo. Maintenance: Orange OUT External Load Short-circuit: Red OUT External Load Disconnection: Red OUT Connected Compo. Maintenance: Orange Errors other than Connected Compo. Maintenance error will be displayed in red when they occur.
4	Read	Setting	Reads items 1 to 3. When reading the items starts, a progress dialog will be displayed, which will automatically close when the items are read.

- * When using this Smart Active Parts, be sure to select Setting **System Setting** in the menu bar, press the **System Memory List** on the Initial Tab Page, and select **Basic Operation** for \$SB. Smart Active Parts cannot be used on the popup screen.
- * Do not use the above display for the start screen.
- * When the Smart Active Parts is reused, the unit number must be specified. If there is more than one slave unit in the DeviceNet, specify the slave unit number.

1.1.3 Input Information Monitor

Unit type	DRT2	2	Storage directory	SmartActiveParts_E\DR T2\IN	Title	DRT2 input information monitor					
Function	Displ	ays and sets	4 bits of input in	formation.							
Display and Operation Details											
9 10											
				DRT2 IN Informa	tion Moni	tor			<u> </u>		
1		→ Unit	Name			Re	ad	W	rite [
		Bit	I/O Cor	mments Set	Value	P. V.	Unit	S	Dis		
		0			0	0					
		1			0	0					
		2			0	0					
		3	A		_ 0	0			•		
		T	3		4	5	6	7	T 8	1	
		2	3		'	ວ	O	1	Ø		

No.	Item	Setting/ display	Description
1	Unit Name	Display	Displays the model number of the Unit. The model number of the Expansion Unit is not displayed.
2	Bit	Display	Displays the bits along with the ON/OFF status of the bits. A bit that is ON will be displayed in yellow.
3	I/O Comments	Display	Displays the I/O comments set for the bits.
4	Set Value	Setting/ display	Displays maintenance monitor set values. The values can be overwritten.
5	P.V.	Setting/ display	Displays the present maintenance values of the maintenance counter. The values can be overwritten. If the present value exceeds the set threshold value, the displayed color of the present value will change to orange.
6	Unit	Display	Displays the maintenance unit (in seconds/times) set for each bit.
7	S	Display	Displays the status of sensor power short-circuiting. The indicator display varies with the Unit. If the Unit does not support sensor power short-circuit detection, the indicator will not turn ON. The indicator will change to red if a short-circuit has been detected.
8	Dis	Display	The indicator displays the status of sensor disconnection. The indicator display varies with the Unit. If the Unit does not support sensor disconnection detection, the indicator will not turn ON. The indicator will flash in red if the sensor is not connected.
9	Read	Setting	Reads items 1 to 8. When reading the items starts, a progress dialog will be displayed, which will automatically close when the items are read.
10	Write	Setting	Writes items 4 to 5 and then reads items 1 to 8.

- When using this Smart Active Parts, be sure to select **Setting System Setting** in the menu bar, press the **System Memory List**
- on the Initial Tab Page, and select *Date* and *Time for \$SW*.

 Monitors are available for bits 0 to 3, 4 to 7, 8 to 11, 12 to 15, 16 to 19, 20 to 23, 24 to 27, or 28 to 31. Select the Smart Active Parts appropriate for the conditions (e.g., environment resistance, inputs, and outputs) of the Unit connected.

1.1.4 Output Information Monitor

Unit t	ype DRT2		rage ctory	SmartActiveParts_E\I T2\OUT	OR Title	DRT2 outpu	ıt informa	tion moni	itor		
Funct	tion Displays and s	sets 4 bits of	output	information.							
Displa	ay and Operation De	etails									
						•		40			
	9 10										
				DRT2 OUT In	formation Mc	nitor 🔻		<u></u>			
	1	Unit Name				Re	ead	Wr	ite		
	Bit		I/0 G	omments	Set Value	P. V.	Unit	S	Dis		
	0				0	0					
	1				0	0					
	2				0	0					
	3				0	0					
				†			*	A	A		
	2		 3		4	 5	6	7	 8		
	2		3		•	· ·	· ·	•	Ü		
		Setting/									
No.	Item	display				cription					
1	Unit Name	Display	Displa displa	ays the model number	of the Unit. Th	ne model num	ber of th	e Expans	sion Unit	is not	
2	Bit	Display	Displa	ays the bits along with the	he ON/OFF stat	us of the bits.	A bit that i	s ON will	be displa	yed in	
3	I/O Comments	Display	yellov Displa	v. ays the I/O comments s	et for the bits.						
4	Set Value	Setting/ display	Displa	ays maintenance monito	or set values. Ti	ne values can	be overwi	ritten.			
	511	Setting/		ays the present mainte							
5	P.V.	display		ritten. If the present vant value will change to		e set threshold	d value, th	ne displa	yed color	of the	
6	Unit	Display	Displa	ays the maintenance un	its (seconds/tim						
7	S	Display		ays the status of sensor If the Unit does not sup							
	turn ON. The indicator will change to red if a short-circuit has been detected.										
8	The indicator displays the status of sensor disconnection. The indicator display varies B Dis Display The Unit does not support sensor disconnection detection, the indicator will										
			turn C	N. The indicator will flast items 1 to 8. When re	ish in red if the	sensor is not c	onnected				
9	Read	Setting	will au	utomatically close when	the items are r	ead.		will be o	пъргауец,	WITICIT	
10	Write	Setting	Writes	s items 4 to 5 and then	reads items 1 to	8.		-	•		

- When using this Smart Active Parts, be sure to select Setting System Setting in the menu bar, press the System Memory List
- on the Initial Tab Page, and select *Date* and *Time for \$SW*.

 Monitors are available for bits 0 to 3, 4 to 7, 8 to 11, 12 to 15, 16 to 19, 20 to 23, 24 to 27, or 28 to 31. Select the Smart Active Parts appropriate for the conditions (e.g., environment resistance, inputs, and outputs) of the Unit connected.

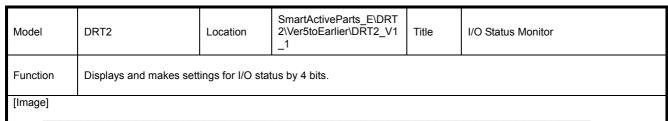
1.1.5 Monitor Time Information

Unit typ	e DRT2		rage ctory	SmartActiveParts_E\DR Title DRT2 monitor time information						
Functio	n Displays and s	sets 4 bits of	ON tim	ing information for output to	input.					
Display	and Operation De	etails								
						7	8			
						i	Ĭ			
DRT2 Monitor Information										
1 Unit Name Read Write										
		Bit		I/O Comments	Set Va	alue	P. V.	Unit		
		0				0	0	ms		
		1				П	Й	ms		
						_				
		2				0	0	ms		
		3				0	0	ms		
		†		†	†		†	†		
		2		3	4		5	6		
No.	Item	Setting/			Desc	ription	1			
		display	Dienla	ays the model number of t				the Eyna	neion Unit is not	
1	Unit Name	Display	displa		ii e Uliit. III	e 111001	ei ilullibei Ol	ше схра	ISIOII OIIILIS IIOL	
2	Bit	Display		ays the bits.						
3	I/O Comments	Display	Displa	rys the I/O comments set fo	r the bits.					
4	Set Value	Setting/ display		ays set values. The values o						
5	P.V.	Setting/	Displays the present values. The values can be overwritten. If the present value exceeds the							
-		display		reshold value, the displayed	color of the	prese	nt value will ch	nange to c	range.	
6	Unit	Display		ays the units. is items 1 and 3 to 5. When i	cooding the	itomo o	tarta a proces	oo dialaa	will be displayed	
7	Read	Setting		will automatically close who				ss dialog	wiii be displayed,	
8	Write	Setting		item 4 and then reads item			<u> </u>			
Remark	s									

^{*} Monitors are available for bits 0 to 3 or 4 to 7. Select the Smart Active Parts appropriate for the conditions (e.g., environment resistance, inputs, and outputs) of the Unit connected.

1.1.6 Smart Slave

Model		DRT2	Location	SmartActiveParts_E\DRT 2\Ver5toEarlier\DRT2_V1 _1		Title	Unit Status Monitor		
Function	n	Makes settings for unit	status moni	tor and parame	eters.				
[Image]			DD	TO ID10 Um	:+ Ctatus Mar	o!ton			
		11-		T2-ID16 Unit Status Monitor					
	1		t Name		Last Mainter		2		
		DRT2-ID16				/ 0			
	_	Netwo	ork Power	Voltage(V		St	duction Time(Hour) 4		
	3	Present V.	Peak	Bottom	Monitor Val	Present \	'alue Monitor Value		
		23.9	24. 1	23.9	21.0	2684357	5.2 30000000.0		
	5			Unit	Status				
		Basic I/O Un	nit Power	Voltage	Sensor D	isconnec	ted Detection		
		Expansion I/O	Unit Pow	er Voltage	Sensor	Power Sh	mort-circuit		
		Netwrok Power	Vol. Mon	itor Error	Operatio	on Time N	Monitor Error		
		Unit	1aintenan	ce	Connected	Compone	nt Maintenance		
	6 00 01 02 03 04 05 06 07 08 09 10 11 12 13 14 15								
		Read	d Status	[N	lrite	Re	eet		
			7		8		9		
No.		Item	Setting/ Display			De	ails		
1		Unit Name	S/D				name can be changed.		
2	La	st Maintenance Date	Display	date cannot b		nance was	last performed to be written to the Unit. The		
3	N	letwork Power Voltage	S/D		ent value (Preser er Voltage. The m		bottom, monitor value (Monitor Val.) for the can be set.		
4	U	nit Conduction Time	S/D	Displays present value and monitor value for the Unit Conduction Time. Monitor value set.					
5		Unit Status	S/D	Displays unit	status. For details	s, refer to the	e Manual of each unit.		
6		I/O Status (00 to 15) Displa		Disconnection detected, short-circuit, operation time monitor error, and connected component maintenance under unit status flag are touch switches. When they are pressed, start reading each I/O status and display. (Applicable items vary from units.) The red arrow indicates the contents of I/O status which is being displayed.					
7		Read Status	Read Status Setting		Reads unit status from 1 to 5 above mentioned at once when it is pressed.				
8		Write	Setting	Writes unit name, network power voltage, and monitor value for the unit conduction time.					
9		Reset	Setting	Resets peak conduction tir		network p	ower voltage and present value for uni		
		gs-Unit & Scale Setting of unit status flag differ					g those parts.		



	DRT2-IDØ8C I/O Status Monitor							
Bit	I/O Comments	Mode	Set Val.	Present Val	SD	De		
4 I/0_1		F	56	56		ON	R+9	
5		F	52	268435752		ON	Rs + 10	
6		T	4465	12		OFF	W + 11	
7		F	7789	268435752		ON		
1	2	3	4	5	6 7	8		

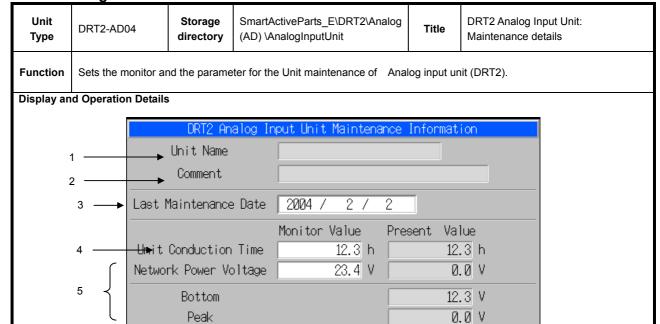
No.	Item	Setting/ Display	Details
1	Bit	Display	Displays an appropriate bit and ON/OFF status with lamp.
2	I/O comments	S/D	Displays I/O comments set for bits. This can be changed.
3	Mode	S/D	Displays maintenance mode either Time (T) or Frequency (F).
4	Set value (Set V.)	S/D	Displays the monitor value for maintenance. The value can be changed.
5	Present Value (Present Val)	S/D	Displays the present value in the maintenance counter. The value can be changed.
6	Short-circuit (S)	Display	Displays short-circuit detection flag for environment-resistive units. When using IN unit, it detects sensor power sort-circuit. When using OUT unit, it detects external load short-circuit.
7	Disconnected (D)	Display	Displays the detected sensor disconnected flag for IN unit.
8	Disconnection Detected (D.D.)	Display	Displays whether the sensor disconnected detection flag for IN unit has been set or not. This setting can be changed
9	Read	Setting	Reads an appropriate 4-bit data at once.
10	Reset	Setting	Resets present value in the maintenance counter.
11	Write	Setting	Writes information, such as I/O comments, maintenance mode, set value/present value in the maintenance counter, for an appropriate 4-bit data at once.

[Note]

Please use an appropriate Smart Active Parts in accordance with units to be connected (environment-resistive unit, IN unit, and OUT unit etc...).
This is not supported for an expansion unit.

1.2. Analog

1.2.1 Analog Unit Maintenance Details



Read

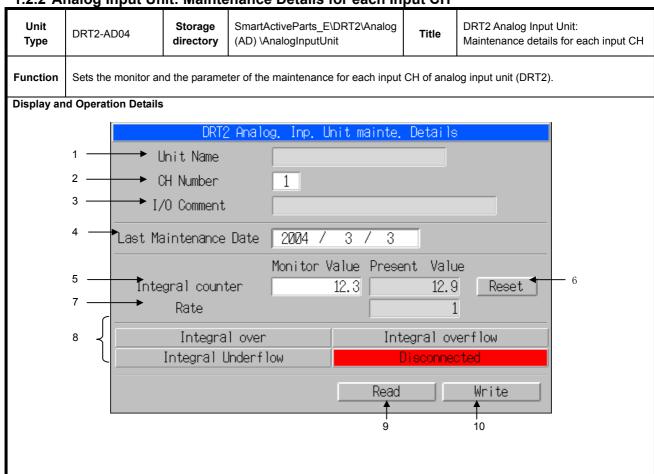
Write

Unit error

No.	Item	Setting/ display	Description
1	Style	Display	Displays the unit style.
2	Details	Display	Displays the details set on the unit.
3	Last maintenance day	Setting/ display	Displays the last maintenance day recorded on the unit. It can be overwritten.
4	Unit energizing time	Setting/ display	Displays the set value and the present value of the unit energizing time. The set value can be overwritten.
5	Network power supply voltage	Setting/ display	Displays the set value, present value, minimum value, and maximum value of the network power supply voltage. The set value can be overwritten. When the value exceeds the set threshold, the present value will be displayed in one of the following colors. Unit energizing time (present value): orange Network power supply voltage (present value): red
6	Error	Display	The display color changes when an error occurs. Unit error: red
7	Read	Setting	Reads the item 1 to 6.
8	Write	Setting	After writing the item 3 to 5, reads the item 1 to 6.

- * When the Smart Active Part is reused, the unit number must be specified. If there is more than one slave unit in the DeviceNet, specify the slave unit numbers.
- Use this display in system version 5 or later.

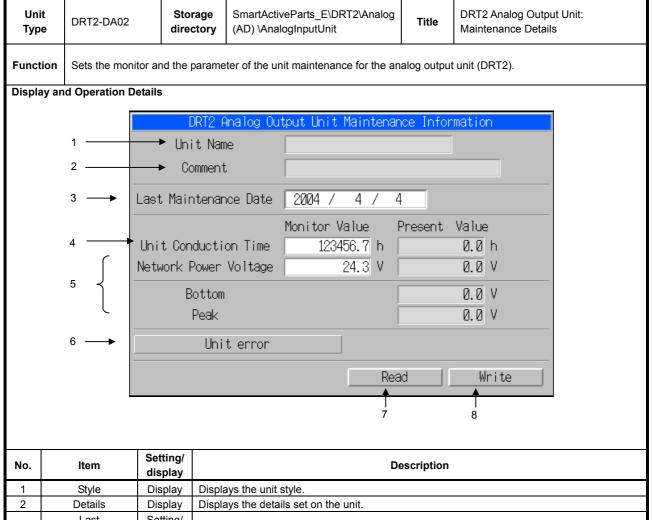
1.2.2 Analog Input Unit: Maintenance Details for each Input CH



		Setting/					
No.	Item	display	Description				
1	Style	Display	Displays the unit style.				
2	CH No.	Setting	Sets the input CH number.				
3	Details	Display	Displays the details set on the CH number.				
4	Last maintenance day	Setting/ display	Displays the last maintenance day of the connected devices. The date can be overwritten.				
5	Integral counter	Setting/ display	Displays the set value and the present value of the integral counter. The set value can be overwritten. When the value exceeds the set threshold, the present value will be displayed in orange.				
6	Reset	Setting	Resets the present value of the integral counter.				
7	Rate	Display	Displays the rate.				
8	Error	Display	The displayed color varies with the error status Integral value over: orange Integral value overflow: orange Integral value underflow: orange Disconnected: red				
9	Write	Setting	Reads the item 1 to 8.				
10	Read	Setting	After writing the item 4 to 5, reads the item 1 to 8.				
Doma	rke						

- * When the Smart Active Part is reused, the unit number must be specified. If there is more than one slave unit in the DeviceNet, specify the slave unit numbers.
- Use this display in system version 5 or later.

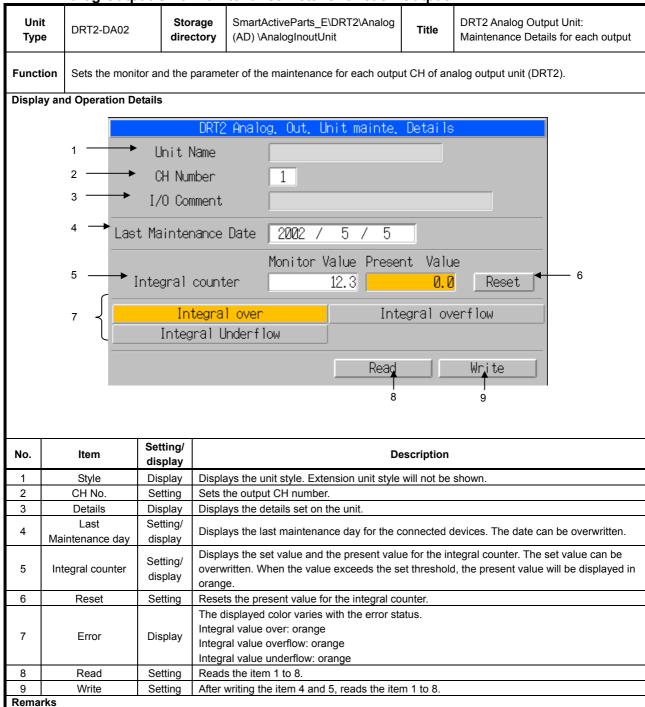
1.2.3 Analog Output Unit Maintenance Details



No.	Item	Setting/ display	Description
1	Style	Display	Displays the unit style.
2	Details	Display	Displays the details set on the unit.
3	Last maintenance day	Setting/ display	Displays the last maintenance day recorded on the unit. The date can be overwritten.
4	Unit power supply voltage	Setting/ display	Displays the set value and the present value of the unit energizing time. The set value can be overwritten.
5	Network power supply	Setting/ display	Displays the set value, present value, minimum value, and maximum value for the network power supply voltage. The set value can be overwritten. When the value exceeds the set threshold, the displayed color for the present value will change to one of the following colors. Unit energizing time (present value): orange Network power supply voltage (present value): red
6	Error	Display	The display color changes when an error occurs. Unit error: red
7	Read	Setting	Reads the item 1 to 6.
8	Write	Setting	After writing the item 3 to 5, reads the item 1 to 6.

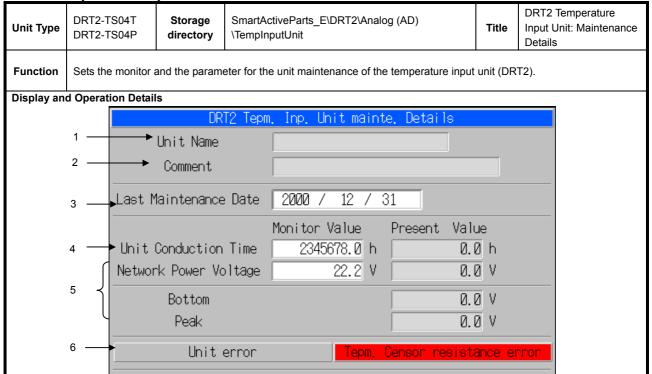
- * When the Smart Active Part is reused, the unit number must be specified. If there is more than one slave unit in the DeviceNet, specify the slave unit numbers.
- Use this display in system version 5 or later.

1.2.4 Analog Output Unit: Maintenance Details for each Output



- When the Smart Active Part is reused, the unit number must be specified. If there is more than one slave unit in the DeviceNet, specify the slave unit numbers.
- Use this display in system version 5 or later.

1.2.5 Temperature Input Unit: Maintenance Details



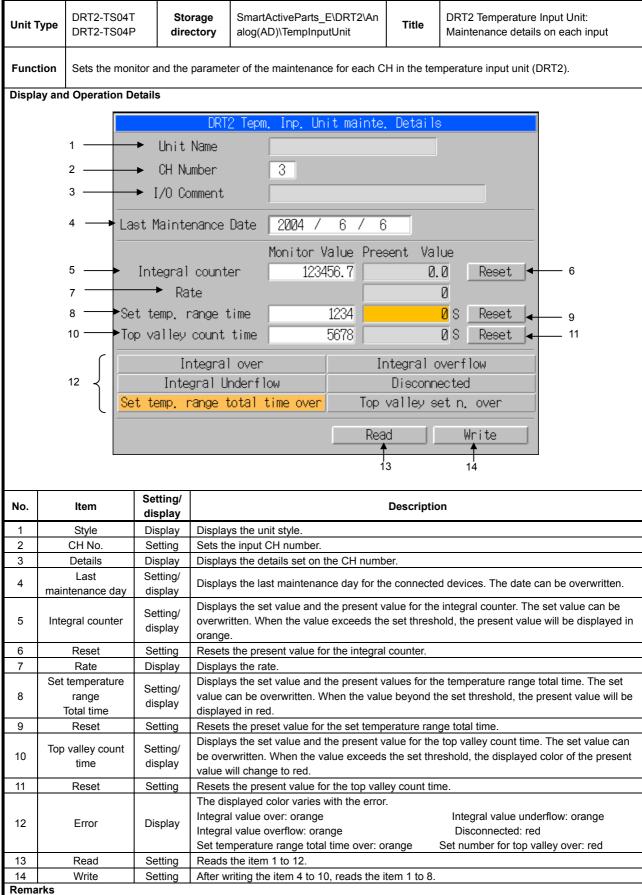
Read

Write

No.	Item	Setting/ display	Description
1	Style	Display	Displays the unit style.
2	Details	Display	Displays the details set on the unit.
3	Last maintenance day	Setting/ display	Displays the last maintenance day recorded on the unit. The date can be overwritten.
4	Unit power distribution time	Setting/ display	Displays the set value and the present value of the unit energizing time. The set value can be overwritten.
5	Network power supply voltage	Setting/ display	Displays the set value, the present value, the minimum value, and the maximum value for the network power supply voltage. The set value can be overwritten. When the value exceeds the set threshold, the displayed color for the present value will change to one of the following colors. Unit energizing time (present value): orange Network power supply voltage (present value): red
6	Error	Display	A display color changes depending on the error that has occurred. Unit error: red Temperature censor resistance error: red
7	Read	Setting	Reads the item 1 to 6.
8	Write	Setting	After writing the item 3 to 5, reads the item 1 to 6.

- * When the Smart Active Part is reused, the unit number must be specified. If there is more than one slave unit in the DeviceNet, specify the slave unit numbers.
- Use this display in system version 5 or later.

1.2.6 Temperature Input Unit: Maintenance Details for each Input



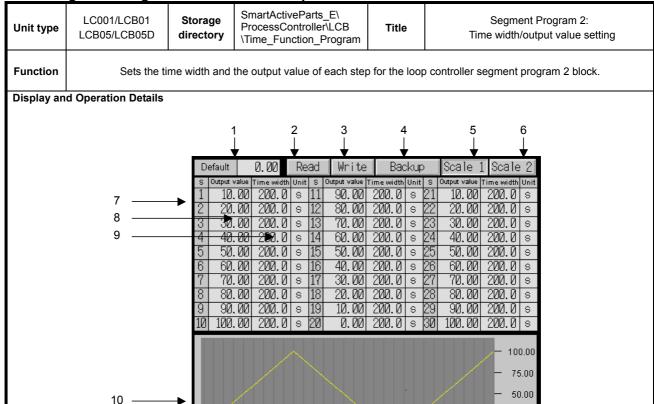
- When the Smart Active Part is reused, the unit number must be specified. If there is more than one slave unit in the DeviceNet, specify the slave unit numbers.
- Use this display in system version 5 or later. B

Process Controller

Process Controller

1.1 Loop Controller Unit

1.1.1 Segment Program 2 Time Width/Output Value



25.00 0.00

No.	Item	Setting/ display	Description
1	Default	Setting/ display	Sets and displays the default (step 0).
2	Read	Setting	Reads all the target data (output value, time width and time unit) from the target block.
3	Write	Setting	Writes all the target data (output value, time width and time unit) to the target block.
4	Backup	Setting	Backups the written data to FROM in the loop controller. This function is only available for LCB01/05 of the system version 1.5 or later, and LCB05D.
5	Scale 1	Setting	Sets the vertical axis for the output value to be displayed in the graph in the range of -15% and 115%.
6	Scale 2	Setting	Sets the vertical axis for the output value to be displayed in the graph in the range of ± 320%.
7	Output Value (1 to 30 step)	Setting/ display	Sets the output value for each step in the range of ± 320.00%.
8	Time Width (1 to 30 step)	Setting/ display	Sets the output time width for each step in the range of 0 to 3200.0. The unit will be set in the item 9.
9	Time Unit (1to 30 step)	Setting/ display	Sets the output time unit for each step to hour, minute or second.
10	Graph erea	Display	Displays the output values for the target segment program 2 as a continuous graph for each step. Please be advised that the time width will not be applied to the horizontal axis. The step wil be displayed in red when the scale 1 is set and the output value is out of the range between -15% and 115%.

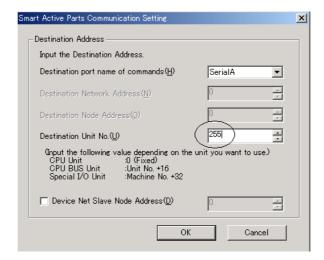
S10

S15

S20

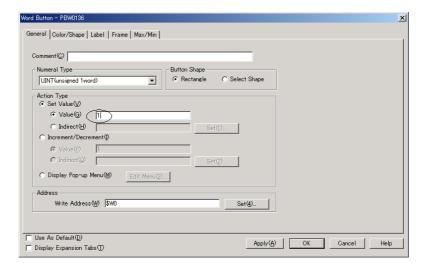
Remarks

- * When using the Smart Active Parts, please follow the settings below.
- 1. Setting the unit number: double click the Smart Active Parts pasted on the project to dispay the following screen. (This screen shows when deselecting the Edit SAP Library" in the option.)



Set the intelligent CPU unit number +16 in the transfer direction number of the LC001 and 225 for LCB01/05/05D.

2. Setting the target Function block address: double click the *Read* button of the Smart Active Parts pasted on the project to dispay the following screen. (This screen shows when deselecting the *Edit SAP Library*" in the option.)



Specify the block address in the setting value for the loop controller of the Function block. Please check the address for the Function block on the CX-Process Tool.

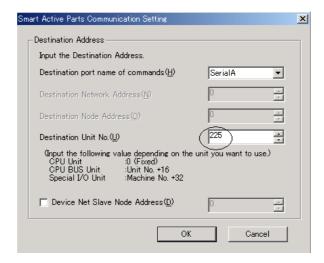
- * When using this Smart Active Parts, be sure to select **Setting Unit/Scale Setting** in the menu bar and set the scale for number 1000 to 0.1 and for number 999 to 0.01
- * The above item 1, 7, 8, and 9 set on the NS will be applied to the loop controller only after writing these settings to the loop controller. After editing the item, wirte it to the loop controller with the Write button. Please be advised that the edited item will be lost if you go to another screen without writing it with the Write button.

1.1.2 Segment Program 2 Wait Setting

1.1.2	Segment Pro	gram 2 v	wait S	etting							
Unit ty	LC001/LCB0		age	SmartActiveParts_E\ ProcessController\LCB \Time_Function_Program		Title		Segment program 2: Wait setting			
Funct	ion Sets th	e wait width a	and the v	wait time o	f eac	h step for th	ne segmen	prog	gram 2 block	k in the Loop	Controller.
Displa	y and Operation De	tails									
							1		2 3		
							Read			Backup	
			t width 2.00	Wait time	11	Wait width 0.00	Wait time	21	Wait width 0.00	Wait time	
	4 –		<u> </u>	0.0	12	0.00	0.0	22	0.00	0.0	
	5 –		7.00 P	0.0	13	0.00	0.0	23	0.00	0.0	
			a. 00	0.0	14	0.00	0.0	24	0.00	0.0	
			<u> </u>	0.0	15	0.00	0.0	25	0.00	0.0	
			<u> 2. 00 </u>	0.0	16	0.00	0.0	26	0.00	0.0	
		7 0	2.00	0.0	17	0.00	0.0	27	0.00	0.0	
		8 0	2.00	0.0	18	0.00	0.0	28	0.00	0.0	
			2.00	0.0	19	0.00	0.0	29	0.00	0.0	
		10 0	2.00	0.0	20	0.00	0.0	30	0.00	0.0	
No.	Item	Setting/ display					Desc	ripti	on		
1	Read	Setting	Rea	ds all the ta	arget	data (outp	ut value, tin	ne wi	dth and time	e unit) from	the target block.
2	Write	Setting	Writes all the target data (output value, time width and time unit) to the target block.								
3	Backup	Setting	Backups the written data to FROM in the loop controller. This function is only available for LCB01/05 of the system version 1.5 or later, and LCB05D.								
4	Wait width	Setting/ display	Sets the waite width for each step in the range of 0 to 320.00%.								
5	Wait time	Setting/ display	Sets					_		nd 3200.00% for each st	6. Time units are ep.

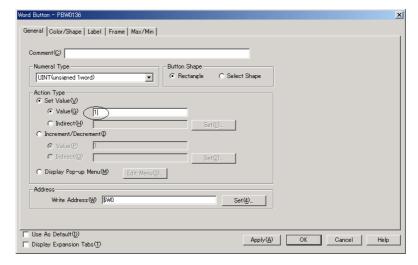
Remarks

- * When using this Smart Active Parts, please follow the settings below.
- 3. Setting the unit number: double click the Smart Active Parts pasted on the project to dispay the following sreen. (This screen shows when deselecting the Edit SAP Library" in the option.)



Set the intelligent CPU unit number +16 in the transfer direction number of the LC001 and 225 for LCB01/05/05D.

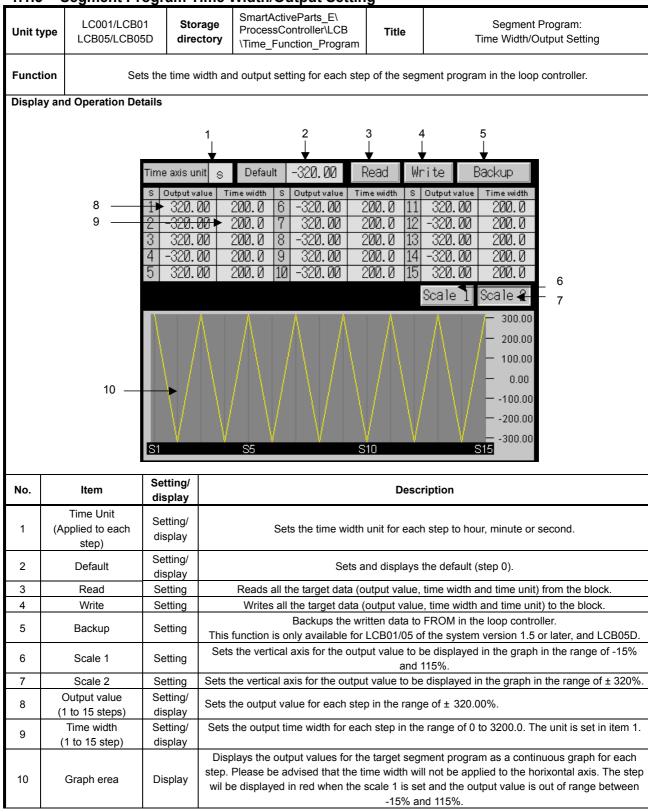
4. Setting the target Function block address: double click the *Read* button of the Smart Active Parts pasted on the project to dispay the following screen. (This screen shows when selecting the *Edit SAP Library*" in the option.)



Specify the block address in the setting value for the loop controller of the Function block. Please check the address for the Function block on the CX-Process Tool.

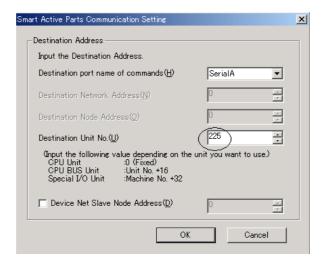
- * When using this Smart Active Parts, be sure to select **Setting Unit/Scale Setting** in the menu bar and set the scale for number 1000 to 0.1 and for number 999 to 0.01
- * The above item 4 and 5 set on the NS will be applied to the loop controller only after writing these settings to the loop controller. After editing the item, wirte it to the loop controller with the Write button. Please be advised that the edited item will be lost if you go to another screen without writing it with the Write button.

1.1.3 Segment Program Time Width/Output Setting



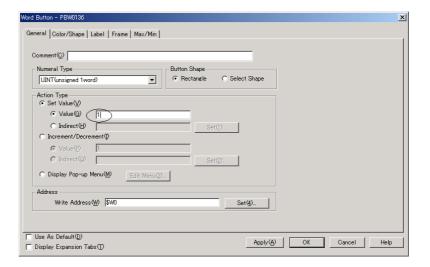
Remarks

- * When using this Smart Ative Parts, please follow the settings below.
- 5. Setting the unit number: double click the Smart Active Parts pasted on the project to dispay the following sreen. (This screen shows when deselecting the Edit SAP Library" in the option.)



Set the intelligent CPU unit number +16 in the transfer direction number of the LC001 and 225 for LCB01/05/05D.

6. Setting the target Function block address: double click the *Read* button of the Smart Active Parts pasted on the project to dispay the following screen. (This screen shows when selecting the *Edit SAP Library*" in the option.)



Specify the block address in the setting value for the loop controller of the Function block. Please check the address for the Function block on the CX-Process Tool.

- * When using this Smart Active Parts, be sure to select **Setting Unit/Scale Setting** in the menu bar and set the scale for number 1000 to 0.1 and for number 999 to 0.01
- * The above item 1, 2, 8, and 9 set on the NS will be applied to the loop controller only after writing these settings to the loop controller. After editing the item, wirte it to the loop controller with the Write button. Please be advised that the edited item will be lost if you go to another screen without writing it with the Write button.

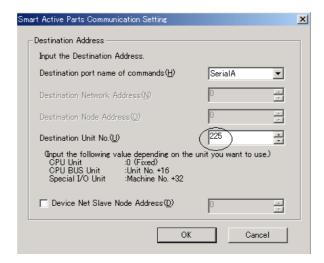
1.1.4	Ramp Progi	ram Para	meter Setting						
Unit ty	ype LC001/LCB0		- Flocesscontioner/ECD	Title	Segment paragram: Paramter setting				
Funct	ion Se	ets the ramp	rate and the soak value for each st	ep on the ra	mp program in the loop controller.				
Displa	Display and Operation Details								
	6 7 9 10 11 12 13	1 D 2 3 3 4 - 5 - 6 - 7 -	prate Unit Soak value Soak time Unit S 1.00 S 100.00 100.0 S 9 1.00 S 200.00 100.0 S 10 1.00 S 300.00 100.0 S 11 1.00 S 150.00 100.0 S 12 1.00 S 0.00 10.0 S 12 1.00 S 0.00 10.0 S 13 1.00 S 0.00 10.0 S 14 1.00 S -300.00 10.0 S 15 0.00 S -300.00 10.0 S	Wait time	8				
No.	Item	Setting/		Descr	iption				
1	Read	display Setting	Reads all the target data (output v		idth and time unit) from the target block.				
2	Write	Setting			dth and time unit) to the target block.				
3	Backup	Setting	Backups the written data to FROM This function is only available for I	•	controller. the system version 1.5 or later, and LCB05D.				
4	Scale 1	Setting	Sets the vertical axis for the outpound 115%.	ut value to b	e displayed in the graph in the range of -15%				
5	Scale 2	Setting	Sets the vertical axis for the ou ±320%.	tput value to	be displayed in the graph in the range of				
6	Default	Setting/ display	Sets and displays the default (step	0).					
7	Wait Width								
	(Applied all each step)	Setting/ display	Sets the wait width for each step i	n the range o	of 0 to 320.00%.				
8	step) Wait Time (Applied to each step)		Sets the wait time width for each for each step, and the time unit wi	step in the r	range of 0 to 3200.0. The set value is applied each step ramp rate in item 10.				
8	step) Wait Time (Applied to each	display Setting/	Sets the wait time width for each for each step, and the time unit wi	step in the rill be set for e	range of 0 to 3200.0. The set value is applied				
	step) Wait Time (Applied to each step) Ramp rate	display Setting/ display Setting/	Sets the wait time width for each for each step, and the time unit wi	step in the r Il be set for e p as a rate p	range of 0 to 3200.0. The set value is applied each step ramp rate in item 10. Deer time unit. Sets in the range of \pm 115.00%.				
9	step) Wait Time (Applied to each step) Ramp rate (1 to 15 steps) Ramp rate unit time (1 to 15 Steps) Soak value	display Setting/display Setting/display Setting/display Setting/display Setting/	Sets the wait time width for each for each step, and the time unit wind inputs the ramp rate for each step. The unit time will be set in item 10. Sets the ramp rate for each step to Sets the soak value for each step.	step in the relationship step in the relations	range of 0 to 3200.0. The set value is applied each step ramp rate in item 10. Deer time unit. Sets in the range of \pm 115.00%.				
9	step) Wait Time (Applied to each step) Ramp rate (1 to 15 steps) Ramp rate unit time (1 to 15 Steps) Soak value (1 to 15 Steps) Soak time	display Setting/ display Setting/ display Setting/ display Setting/ display Setting/ Setting/ Setting/	Sets the wait time width for each for each step, and the time unit will inputs the ramp rate for each step. The unit time will be set in item 10. Sets the ramp rate for each step to the soak value for each step the range of ± 320.00%. Sets the soak time for each step.	step in the relation of the set for each pas a rate pass. The object of the set of the	range of 0 to 3200.0. The set value is applied each step ramp rate in item 10. Deer time unit. Sets in the range of ± 115.00%. The set value is applied to the range of ± 115.00%.				
9 10 11	step) Wait Time (Applied to each step) Ramp rate (1 to 15 steps) Ramp rate unit time (1 to 15 Steps) Soak value (1 to 15 Steps)	Setting/ display Setting/ display Setting/ display Setting/ display Setting/ display	Sets the wait time width for each for each step, and the time unit will inputs the ramp rate for each step. The unit time will be set in item 10. Sets the ramp rate for each step to Sets the soak value for each step the range of ± 320.00%.	step in the rill be set for exp as a rate poly. o hour, minute, which is on in the range	range of 0 to 3200.0. The set value is applied each step ramp rate in item 10. Der time unit. Sets in the range of ± 115.00%. The terms of 0~3200.0. The time unit will be set in item of 0~3200.0. The time unit will be set in item				

			Process Controller
14	Graph erea	Display	Displays the output values for the ramp program as a continuous graph for each step. Please be advised that the soak time and its time will not be applied to the horixontal axis. The step wil be displayed in red when the scale 1 is set and the output value is out of range between -15% and 115%.

Process Controller

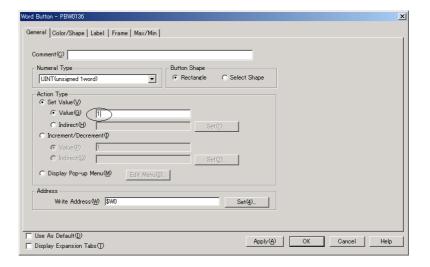
Remarks

- * When using the Smart Active Parts, please follow the settings below.
- 7. Setting the unit number: double click the Smart Active Parts pasted on the project to dispay the following sreen. (This screen shows when deselecting the Edit SAP Library" in the option.)



Set the intelligent CPU unit number +16 in the transfer direction number of the LC001 and 225 for LCB01/05/05D.

8. Setting the target Function block address: double click the *Read* button of the Smart Active Parts pasted on the project to dispay the following screen. (This screen shows when selecting the *Edit SAP Library*" in the option.)



Specify the block address in the setting value for the loop controller of the Function block. Please check the address for the Function block on the CX-Process Tool.

- * When using this Smart Active Parts, be sure to select **Setting Unit/Scale Setting** in the menu bar and set the scale for number 1000 to 0.1 and for number 999 to 0.01
- * The above item 6 to 13 set on the NS will be applied to the loop controller only after writing these settings to the loop controller. After editing the item, wirte it to the loop controller with the Write button. Please be advised that the edited item will be lost if you go to another screen without writing it with the Write button.

OMRON CORPORATION

FA Systems Division H.Q. 66 Matsumoto Mishima-city, Shizuoka 411-8511 Japan Tel: (81)559-77-9181/Fax: (81)559-77-9045

Regional Headquarters

OMRON EUROPE B.V.

Wegalaan 67-69, NL-2132 JD Hoofddorp The Netherlands

Tel: (31)2356-81-300/Fax: (31)2356-81-388

OMRON ELECTRONICS LLC

1 East Commerce Drive, Schaumburg, IL 60173 U.S.A.

Tel: (1)847-843-7900/Fax: (1)847-843-8568

OMRON ASIA PACIFIC PTE. LTD.

83 Clemenceau Avenue, #11-01, UE Square, Singapore 239920 SINGAPORE

Tel: (65)835-3011/Fax: (65)835-2711

OMRON Authorized Distributor: