# CJ2H-CPU6□

CSM CJ2H-CPU DS F 10 1

# Setting new standards in high-speed machine control

Small, Fast, Flexible:
 Inheriting and improving CJ1 features, the CJ2 CPU Units is the best choice for the machine control with high-speed and high-capacity.



CJ2H-CPU64

# **Features**

- Even more program memory and data memory.
- Superior high-speed control performance: LOAD instructions execute in 16 ns, SINE instructions in 0.59 µs.
- Maximum throughputs with High-speed interrupt function
- Efficient debugging through highly improved Data tracing
- Secure system from memory error brought by Memory Self-restoration Function
- The more advanced motion control by the lower cost: Synchronous Unit Operation
- Increased I/O throughput speed by Immediate refreshing instructions with direct processing.

# **Ordering Information**

#### Applicable standards

Refer to the OMRON website (www.ia.omron.com) or ask your OMRON representative for the most recent applicable standards for each model.

# **CJ2H CPU Units**

		Specifications					
Product name	I/O capacity/Mountable Units (Expansion Racks)	Program capacity	Data memory capacity	LD instruction execution time	5 V	24 V	Model
	2,560 points / 40 Units (3 Expansion Racks max.)	400K steps	832K words DM: 32K words EM: 32K words × 25 banks	0.016 μs	0.42*	-	CJ2H-CPU68
CJ2H CPU Units		250K steps	512K words DM: 32K words EM: 32K words × 15 banks				CJ2H-CPU67
		150K steps	352K words DM: 32K words EM: 32K words × 10 banks				CJ2H-CPU66
		100K steps	160K words DM: 32K words EM: 32K words × 4 banks				CJ2H-CPU65
		50K steps	160K words DM: 32K words EM: 32K words × 4 banks				CJ2H-CPU64

<sup>\*</sup>Add 0.15 A per Adapter when using NT-AL001 RS-232C/RS-422A Adapters. Add 0.04 A per Adapter when using CJ1W-CIF11 RS-422A Adapters.

# **Accessories**

The following accessories come with CPU Unit:

Item	Specification
Battery	CJ1W-BAT01
End Cover	CJ1W-TER01 (necessary to be mounted at the right end of CPU Rack)
End Plate	PFP-M (2 pcs)

Note: A serial port (RS-232C) connector is not provided. Purchase a connector separately for serial port connection.

Plug: XM3A-0921 (manufactured by OMRON) or equivalent Hood: XM2S-0911-E (manufactured by OMRON) or equivalent

# **General Specifications**

	W		CJ2H-						
	Item	CPU64	CPU65	CPU66	CPU67	CPU68			
Enclosure		Mounted in a panel							
Grounding		Less than 100 $\Omega$							
CPU Rack Dimension	ns	90 mm × 65 mm	$\times$ 49 mm (H $\times$ D $\times$ )	N)					
Weight *		190 g or less							
<b>Current Consumption</b>	on	5 VDC, 0.42 A							
	Ambient Operating Temperature	0 to 55°C							
	Ambient Operating Humidity	10% to 90% (with	10% to 90% (with no condensation)						
	Atmosphere	Must be free from corrosive gases.							
	Ambient Storage Temperature	−20 to 70°C (excluding battery)							
	Altitude	2,000 m or less							
	Pollution Degree	2 or less: Meets IEC 61010-2-201.							
Use Environment	Noise Immunity	2 kV on power supply line (Conforms to IEC 61000-4-4.)							
	Overvoltage Category	Category II: Meets IEC 61010-2-201.							
	EMC Immunity Level	Zone B							
	Vibration Resistance	Conforms to IEC60068-2-6. 5 to 8.4 Hz with 3.5-mm amplitude, 8.4 to 150 Hz Acceleration of 9.8 m/s² for 100 min in X, Y, and Z directions (10 sweeps of 10 m 100 min total)				of 10 min each =			
	Shock Resistance		Conforms to IEC60068-2-27. 147 m/s², 3 times in X, Y, and Z directions (100 m/s² for Relay Output Units)						
	Life	5 years at 25°C							
Battery	Weight	Approx. 10 g							
	Model	CJ1W-BAT01							
Applicable Standard	ls	Conforms to cULus, NK, LR and EC Directives.							

<sup>\*</sup> Includes wight of end covers and battery.

# **Performance Specifications**

					CJ2H-		
	Items		CPU64	CPU65	CPU66	CPU67	CPU68
User Memor	у		50K steps	100K steps	150K steps	250K steps	400K steps
I/O Bits	T		2,560 bits				
	Overhead Pro	cessing Time	Normal Mode: 100 μs				
	Execution Tim	e	Basic Instructions: 0. Special Instructions:				
Processing Speed	I/O Interrupts and External Interrupts		Return time to cyclic	time: 26 μs or 17 μs task: 11 μs or 8 μs * interrupt function is us			
	Interrupts			time : 22 μs or 13 μs			
		Scheduled Interrupts	Return time to cyclic	task: 11 μs or 8 μs * interrupt function is us			
Maximum N	umber of Conne	ectable Units	Total per CPU Rack Total per PLC: 40 Ur	or Expansion Rack: 10 nits max.	0 Units max.;		
Maximum No	umber of Expan	sion Racks	3 max.				
	I/O Area		2,560 bits (160 word	s): Words CIO 0000 to	CIO 0159		
	Link Area		3,200 bits (200 word	s): Words CIO 1000 to	CIO 1199		
	Synchronous	Data Refresh Area	1,536 bits (96 words)	): Words CIO 1200 to	CIO 1295		
CIO Area	CPU Bus Unit	Area	· · · · · · · · · · · · · · · · · · ·	s): Words CIO 1500 to			
CIO Alea	Special I/O Un		15,360 bits (960 wor	ds): Words CIO 2000	to CIO 2959		
	DeviceNet Are	a	` `	s): Words CIO 3200 to			
	Internal I/O Ar	ea		s): Words CIO 1300 to ords): Words CIO 380 external I/O.			
Work Area			8,192 bits (512 word Cannot be used for e	s): Words W000 to W5	511		
Holding Are	Holding Area			8,192 bits (512 words): Words H000 to H511  Bits in this area maintain their ON/OFF status when PLC is turned OFF or operating mode is changed.  Words H512 to H1535: These words can be used only for function blocks. They can be used only for function block instances (i.e., they are allocated only for internal variables in function blocks).			
Auxiliary Ard	ea		Read-only: 31,744 bits (1,984 words)  • 7,168 bits (448 words): Words A0 to A447  • 24,576 bits (1,536 words): Words A10000 to A11535 * Read/write: 16,384 bits (1,024 words) in words A448 to A1471 *  * A960 to A1471 and A10000 to A11535 cannot be accessed by CPU Bus Units, Special I/O Units, PTs, and Support Software that do not specifically support the CJ2 CPU Units.				
Temporary A	Area		16 bits: TR0 to TR15				
Timer Area			4,096 timer numbers (T0000 to T4095 (separate from counters))				
Counter Are	a			ers (C0000 to C4095 (	separate from timers)	)	
DM Area			DM Area words for C * Bits in the EM Area	Special I/O Units: D200 CPU Bus Units: D3000 a can be addressed eit Units, PTs, and Suppo	0 to D31599 (100 worker by bit or by word.	rds × 16 Units) These bits cannot be a	addressed by CPU Bus the CJ2 CPU Units.
			*1. Bits in the EM A	banks max.: E00_000 rea can be addressed ial I/O Units, PTs, and	either by bit or by wo	rd. These bits cannot	be addressed by CPU upport the CJ2 CPU
EM Area			<ul> <li>*2. EM banks D to 18 cannot be accessed by CPU Bus Units, Special I/O Units, PTs, and Support Software that do not specifically support the CJ2 CPU Units.</li> <li>*3. Force-set/reset to the EM Area is enabled by specifying a start bank in parameter settings. (unit version 1.2 or higher)</li> </ul>				
			32K words × 4 banks	32K words × 4 banks	32K words × 10 banks	32K words × 15 banks	32K words × 25 banks
	Force-S/R	When EM force-S/R function is used *3	Bank 0 to 3	Bank 0 to 3	Bank 0 to 9	Bank 0 to E	Bank 0 to 18
	Enabled Banks	When automatic address allocation is specified	Bank 3	Bank 3	Bank 6 to 9	Bank 7 to E	Bank 11 to 18
Index Regist	ters		IR0 to IR15 These are special registers for storing PLC memory addresses for indirect addressing. (Index Registers can be set so that they are unique in each task or so that they are shared by all tasks.)				
Cyclic Task	Flag Area		128 flags				
Memory Car	d		128 MB, 256 MB, or	512 MB			
					uted. Preparations car	n be executed prior to	program execution in
Operating M	odes		MONITOR Mode: P	nis mode.  rograms are executed resent values in I/O m	emory, are enabled in	this mode.	ing, and changes to
Evocution 14	odo			rograms are executed	i. This is the normal o	peraung mode.	
Execution Mode			Normal Mode				

						C	J2H-			
	lt	ems		CPU64	CPU65	С	PU66	CPU67	CPU68	
Programmin	ıg Languag	es		Ladder Logic (LD), Sequential Function Charts (SFC), Structured Text (ST), and Instruction Lists (IL)						
Function	Maximum	num	nber of definitions	2,048						
Blocks	Maximum	nun	nber of instances	2,048						
	Type of Ta	asks		Cyclic tasks Interrupt tasks (Power tasks)	er OFF interrupt task	s, scheduled	interrupt ta	sks, I/O interrupt task	ks, and external interru	
Tasks	Number of Tasks			Cyclic tasks: 128 Interrupt tasks: 256 (Interrupt tasks can be tasks is actually 384		asks to crea	e extra cycl	ic tasks. Therefore, t	he total number of cycl	
	Type of S	ymb	ols		an be used only with Can be used in all tas			_C.		
Symbols (Variables)	Data Type		Symbols e of Symbol	BOOL (bit) UINT (one-word unsigned binary) UDINT (two-word unsigned binary) ULINT (four-word unsigned binary) INT (one-word signed binary) INT (two-word signed binary) LINT (four-word signed binary) UINT BCD (one-word unsigned BCD) *1 UDINT BCD (two-word unsigned BCD) *1 ULINT BCD (four-word unsigned BCD) *1 ULINT BCD (four-word unsigned BCD) *1 REAL (two-word floating-point) REAL (four-word floating-point) CHANNEL (word) *1 NUMBER (constant or number) *1 WORD (one-word hexadecimal) DWORD (two-word hexadecimal) STRING (1 to 255 ASCII characters) TIMER (timer) *2 COUNTER (counter) *2 User defined data types (data structures) *3 *1. Cannot be used in Function blocks *2. Can be used only in Function blocks *3. Supported only when CX-Programmer version 9.0 or later is used						
			s (Array Variables)	32k words One-dimensional arrays						
			` '	32.000 elements max.						
	Number of Array Elements  Memory Capacity			8,000 words	e specified from the			32,000 words up to 32K words mu	Itiplied by the number of	
	Number o	f Saı	mplings	Bits = 31, one-word data = 16, two-word data = 8, four-word data = 4						
Data	Sampling	Cyc	le	1 to 2,550 ms (Unit: 1 ms)						
Data Tracing	Trigger Conditions			ON/OFF of specified Data comparison of Data size: 1 word, 2	specified word words, 4 words		`vootov Thou	n or Equals (≥), Less	: Than (<) Less Than (	
				Equals (≤), Not Equa		r Than (>), (	irealer i nar		· · · · · · · · · · · · · · · · · · ·	
	Delay Val	ue			al (≠)	r Than (>), (	ireater i nar			
File Memory		ue		Equals (≤), Not Equal -32,768 to +32,767 Memory Card (128,	al (≠) ms 256, or 512 Mbytes)	(Use the M	emory Card		. , , .	
Source/ Comment	Program	sour	ces, comments, ces, symbol tables	Equals (≤), Not Equal -32,768 to +32,767	al (≠) ms 256, or 512 Mbytes) rt of the EM Area car	(Use the M	emory Card		. , , .	
Source/	Program s	sour	ces, comments,	Equals (≤), Not Equal -32,768 to +32,767 Memory Card (128, EM file memory (Par	al (≠) ms 256, or 512 Mbytes) rt of the EM Area can	(Use the M	emory Cards ed for use a	s file memory.)	. , , .	
Source/ Comment	Program	sourdindex	ces, comments, ces, symbol tables	Equals (≤), Not Equals (≤), Not Equals (32,768 to +32,767 Memory Card (128, EM file memory (Particular) (Particular) (Particular) (20,000 to 10,000 to 10,0	al (≠) ms 256, or 512 Mbytes) rt of the EM Area car s ND, RECV, CMND,	(Use the Mn be conver	emory Cards ed for use a	DU instructions.)	. , , .	
Source/ Comment	Program s program i Logical Po	sourd index orts nu-	ces, comments, ces, symbol tables Logical Ports Extended Logical	Equals (≤), Not Equals (≤), Not Equals (32,768 to +32,767 Memory Card (128, EM file memory (Particular) (Par	al (≠) ms 256, or 512 Mbytes) rt of the EM Area car s ND, RECV, CMND, END2, RECV2, CMI	(Use the Mn be conver	emory Cards ed for use a	DU instructions.)	. , , .	
Source/ Comment	Program s program i Logical Po for Comm nications	sourd index orts nu-	ces, comments, ces, symbol tables  Logical Ports  Extended Logical Ports  Class 3 Connection	Equals (≤), Not Equals (≤), Not Equals (32,768 to +32,767 Memory Card (128, EM file memory (Part Capacity: 3.5 Mbyte 8 ports (Used for SE 64 ports (Used for S	al (≠) ms 256, or 512 Mbytes) rt of the EM Area car s ND, RECV, CMND, END2, RECV2, CMI ons: 64 f clients that can con	(Use the Mn be conver	emory Carded for use a DU, and RXI	DU instructions.) ctions.)	. , , .	
Source/ Comment Memory	Program s program i Logical Po for Comm nications	sourdindex orts nu- mu-	ces, comments, ces, symbol tables  Logical Ports  Extended Logical Ports  Class 3 Connection Type  UCMM (Non-connection Type)	Equals (≤), Not Equals (≤), Not Equals (32,768 to +32,767 Memory Card (128, EM file memory (Paracapacity: 3.5 Mbyte 8 ports (Used for SE 64 ports (Used for S Number of connection Maximum number of	al (≠) ms 256, or 512 Mbytes) t of the EM Area car s ND, RECV, CMND, END2, RECV2, CMI ons: 64 f clients that can con f servers that can con	(Use the Mn be conver	emory Carded for use a DU, and RXI	DU instructions.) ctions.)	. , , .	
Source/ Comment Memory	Program s program i Logical Po for Comm nications CIP Comm nications Specificat	sourdindex orts nu- mu-	ces, comments, tes, symbol tables  Logical Ports  Extended Logical Ports  Class 3 Connection Type  UCMM (Non-connection Type)  B) Port	Equals (≤), Not Equals (≤), Not Equals (32,768 to +32,767 Memory Card (128, EM file memory (Parcapacity: 3.5 Mbyte 8 ports (Used for SE 64 ports (Used for S Number of connection Maximum number of Maximum number of Maximum number of significant (128, 128, 129).	al (≠) ms 256, or 512 Mbytes) t of the EM Area car s ND, RECV, CMND, END2, RECV2, CMI ons: 64 f clients that can con f servers that can con	(Use the Mn be conver	emory Carded for use a DU, and RXI	DU instructions.) ctions.)	. , , .	
Source/ Comment Memory	Program s program i Logical Po for Comm nications CIP Comm nications Specificat	sourd index oorts nu- mu- tion	ces, comments, tes, symbol tables  Logical Ports  Extended Logical Ports  Class 3 Connection Type  UCMM (Non-connection Type)  B) Port	Equals (≤), Not Equals (≤), Not Equals (32,768 to +32,767 Memory Card (128, EM file memory (Part Capacity: 3.5 Mbyte 8 ports (Used for SE 64 ports (Used for S Number of connection Maximum number of Maximum number of USB 2.0-compliant E	al (≠) ms 256, or 512 Mbytes) t of the EM Area car s ND, RECV, CMND, END2, RECV2, CMI ons: 64 f clients that can con f servers that can con	(Use the Mn be conver	emory Carded for use a DU, and RXI	DU instructions.) ctions.)	. , , .	
Source/ Comment Memory	Program s program i Logical Po for Comm nications CIP Comm nications Specificat	sourd index orts nu- nu- tion Il (US	ces, comments, tes, symbol tables  Logical Ports  Extended Logical Ports  Class 3 Connection Type  UCMM (Non-connection Type)  BB) Port	Equals (≤), Not Equals (≤), Not Equals (32,768 to +32,767 Memory Card (128, EM file memory (Part Capacity: 3.5 Mbyte 8 ports (Used for SE 64 ports (Used for SE Number of connected Maximum number of Maximum number of USB 2.0-compliant E 12 Mbps max.	al (≠) ms 256, or 512 Mbytes) rt of the EM Area car s ND, RECV, CMND, END2, RECV2, CMI ons: 64 f clients that can con f servers that can co	(Use the Mn be conver	emory Carded for use a DU, and RXI	DU instructions.) ctions.)	. , , .	
Source/ Comment Memory	Program i program i Logical Pofor Commications  CIP Commications Specificat  Periphera  Ba Tr  Serial Por	sourd index orts nu- mu- il (US aud f 'ansr	ces, comments, tes, symbol tables  Logical Ports  Extended Logical Ports  Class 3 Connection Type  UCMM (Non-connection Type)  BB) Port	Equals (≤), Not Equals (≤), Not Equals (32,768 to +32,767 Memory Card (128, EM file memory (Part Capacity: 3.5 Mbyte 8 ports (Used for SE 64 ports (Used for SE Number of connection Maximum number of Maximum number of USB 2.0-compliant E 12 Mbps max.  5 m max.  Interface: Conforms	al (≠) ms 256, or 512 Mbytes) rt of the EM Area car s ND, RECV, CMND, END2, RECV2, CMI ons: 64 f clients that can con f servers that can co	(Use the Mn be conver	emory Carded for use a DU, and RXI	DU instructions.) ctions.)	. , , .	
Source/ Comment Memory	Program i program i Logical Perfor Commications  CIP Commications  Specificat  Periphera  Ba  Tr  Serial Por	sourdindex orts nu- nu- tion I (US aud F ransr	ces, comments, tes, symbol tables  Logical Ports  Extended Logical Ports  Class 3 Connection Type  UCMM (Non-connection Type)  B) Port  Rate mission Distance	Equals (≤), Not Equals (≤), Not Equals (32,768 to +32,767 Memory Card (128, EM file memory (Part Capacity: 3.5 Mbyte 8 ports (Used for SE 64 ports (Used for SE Number of connection Maximum number of Maximum number of USB 2.0-compliant E 12 Mbps max.  5 m max.  Interface: Conforms Half-duplex	al (≠) ms 256, or 512 Mbytes) rt of the EM Area car s ND, RECV, CMND, END2, RECV2, CMI ons: 64 f clients that can con f servers that can co	(Use the Mn be conver	emory Carded for use a DU, and RXI	DU instructions.) ctions.)	. , , .	
Source/ Comment Memory	Program s program i Logical Perfor Commications  CIP Commications Specificat  Periphera  Ba Tr  Serial Por	sourdindex orts nu- nu- tion I (US aud F ransr rt	ces, comments, ces, symbol tables  Logical Ports  Extended Logical Ports  Class 3 Connection Type  UCMM (Non-connection Type) B) Port Rate mission Distance  unications Method ronization Method	Equals (≤), Not Equals (≤), Not Equals (32,768 to +32,767 Memory Card (128, EM file memory (Part Capacity: 3.5 Mbyte 8 ports (Used for SE 64 ports (Used for SE Number of connection Maximum number of Maximum number of USB 2.0-compliant E 12 Mbps max.  5 m max.  Interface: Conforms	al (≠) ms  256, or 512 Mbytes) rt of the EM Area can s  ND, RECV, CMND, END2, RECV2, CMI ons: 64  f clients that can con f servers that can co 3-type connector  to EIA RS-232C.	(Use the Mn be conver	emory Carded for use a	DU instructions.) ctions.)	. , , .	

# **Function Specifications**

	ı	unctions		Description		
	Minimum Cycle Time			A minimum cycle time can be set. (0.2 to 32,000 ms; Unit: 0.1 ms) The minimum cycle time setting can be changed in MONITOR mode.		
Cycle Time Management	Cycle Time Mo	nitoring		The cycle time is monitored. (0.01 to 40,000 ms; Unit: 0.01 ms)		
	Background Processing			Instructions with long execution times can be executed over multiple cycles to prevent fluctuations in the cycle time.		
	Basic I/O		Cyclic Refreshing	Cyclic refreshing of Basic I/O Units, Special I/O Units, and CPU Bus Units		
	Units, Special I/O Units, and	I/O Refreshing	Immediate Refreshing	I/O refreshing by immediate refreshing instructions		
	CPU Bus	rioncoming	Refreshing by IORF	I/O refreshing by IORF instruction		
	Units	Unit Recogn	ition at Startup	The number of units recognized when the power is turned ON is displayed.		
	D	Input Respo	nse Time Setting	The input response times can be set for Basic I/O Units. The response time can be increased to reduce the effects of chattering and noise at input contacts. The response time can be decreased to enable detecting shorter input pulses.		
	Basic I/O Units	Load OFF Function		All of the outputs on Basic I/O Units can be turned OFF when an error occurs in RUN or MONITOR mode.		
Unit (I/O)		Basic I/O Unit Status Monitoring		Alarm information can be read from Basic I/O Units and the number of Units recognized can be read.		
Management		Unit Restart Bits to Restart Units		A Special I/O Unit or CPU Bus Unit can be restarted.		
	Special I/O Units and CPU Bus Units	Synchronous Unit Operation		The start of processing for all the specified Units can be synchronized at a fixed interval Maximum number of Units: 10 Units (Only Units that support Synchronous Operation Mode can be used.) Synchronous operation cycle: 0.5 to 10ms (default: 2 ms) Maximum number of words for synchronous data refreshing: 96 words (total of all Unit		
		Automatic I/O Allocation at Startup		I/O words can be automatically allocated to the Basic I/O Units that are connected in the PLC to start operation automatically without registering Units into I/O tables.		
	Configuration Management	I/O Table Creation		The current unit configuration can be registered in I/O tables to prevent it from being changed, to reserve words, and to set words.		
		Rack/Slot First Word Settings		The first words allocated to a Units on the Racks can be set.		
	Holding I/O Memory when Changing Operating Modes		hanging Operating Modes	The status of I/O memory can be held when the operating mode is changed or pow turned ON. The forced-set/reset status can be held when the operating mode is changed or power is turned ON.		
	File Memory			Files (such as program files, data files, and symbol table files) can be stored in Memory Card, EM File Memory, or Comment Memory.		
Memory Management	Built-in Flash N	<b>l</b> emory		The user program and Parameter Area can be backed up to an internal flash memory when they are transferred to the CPU Unit.		
	EM File Function	on		Parts of the EM Area can be treated as file memory.		
	Storing Comm	ents		I/O comments can be stored as symbol table files in a Memory Card, EM file memory, or comment memory.		
	EM Configurati	on		EM Area can be set as trace memory or EM file memory.		
	Automatic File	Transfer at S	tartup	A program file and parameter files can be read from a Memory Card when the power is turned ON.		
Memory Cards	Program Repla	cement durin	g PLC Operation	The whole user program can be read from a Memory Card to CPU Unit during operation.		
Carus	Function for Re	eading and W	riting Data from a Memory	Data in I/O memory in the CPU Unit can be written to a Memory Card in CSV/TXT format. Data in CSV/TXT format in the Memory Card can be read to I/O memory in the CPU Unit.		

	Funct	tion	Description		
Communicati	ons		-		
	Peripheral (USB) Port	Peripheral Bus	Bus for communications with various kinds of Support Software running on a personal computer. High-speed communications are supported.		
	Serial Port		-		
	Host Link (SYSWAY) Communications		Host Link commands or FINS commands placed between Host Link headers and terminators can be sent from a host computer or PT to read/write I/O memory, read/control the operating mode, and perform other operations for PLC.		
	No-protocol Co	ommunications	I/O instructions for communications ports (such as TXD/RXD instructions) can be used for data transfer with peripheral devices such as bar code readers and printers.		
	NT Link Comm	unications	I/O memory in the PLC can be allocated and directly linked to various PT functions, including status control areas, status notification areas, touch switches, lamps, memory tables, and other objects.		
	Peripheral Bus		Bus for communications with various kinds of Support Software running on a personal computer. High-speed communications are supported.		
	Serial Gateway		This gateway enables receiving and automatically converting FINS to the CompoWay/F.		
	Scheduled Interru	pts	Tasks can be executed at a specified interval (minimum of 0.2 ms or 0.1 ms *, Unit: 0.1 ms). * When High-speed interrupt function is used.		
	Power OFF Interru	ıpts	A task can be executed when CPU Unit's power turns OFF.		
Interrupt	I/O Interrupt Tasks	3	A task can be executed when an input signal is input to an Interrupt Input Unit.		
•	External Interrupt	Tasks	A task can be executed when interrupts are requested from a Special I/O Unit or a CPU Bus Unit.		
	High-speed Interru	upt Function	Improves performance for executing interrupt tasks with certain restrictions. (Unit version 1.1 or later.)		
	Clock Function		Clock data is stored in memory.  Accuracy (Accuracy depends on the temperature.)  Ambient temperature of 55°C: -3.5 to +0.5 min error per month  Ambient temperature of 25°C: -1.5 to +1.5 min error per month  Ambient temperature of 0°C: -3 to +1 min error per month		
	Operation Start Tir	me Storage	The time when operating mode was last changed to RUN mode or MONITOR mode is stored.		
Clock	Operation Stop Tir	me Storage	The last time a fatal error occurred or the last time the operating mode was changed to PROGRAM mode is stored.		
	Startup Time Stora	age	The time when the power was turned ON is stored.		
	Power Interruption	n Time Storage	The time when the power is turned OFF is stored.		
	Total Power ON Ti	me Calculation	The total time that the PLC has been ON is stored in increments of 10 hours.		
	Power ON Clock D	ata Storage	A history of the times when the power was turned ON is stored.		
	User Program Ove	erwritten Time Storage	The time that the user program was last overwritten is stored.		
	Parameter Date St	orage	The time when the Parameter Area was overwritten is stored.		
Damas	Memory Protection	n	Holding Area data, DM Area data, EM Area data, Counter Completion Flags, and counter present values are held even when power is turned OFF. CIO Area, Work Area, some Auxiliary Area data, and Timer Completion Flags, timer present values, index registers, and data registers can be protected by turning ON the IOM Hold Bit in the Auxiliary Area, and by also setting the IOM Hold Bit to "Hold" in the PLC Setup.		
Power Supply Management	Power OFF Detect	ion Time Setting	The detection time for power interruptions can be set.  AC power supply: 10 to 25 ms (variable)  DC power supply: 2 to 5 ms (CJ1W-PD022) or 2 to 20 ms (CJ1W-PD025)		
	Power OFF Detect	ion Delay Time	The detection of power interruptions can be delayed: 0 to 10 ms (Not supported by the CJ1W-PD022.)		
	Number of Power	Interruptions Counter	The number of times power has been interrupted is counted.		
Function Bloc	ks		Standard programming can be encapsulated as function blocks.		
	Languages in Fund	ction Block Definitions	Ladder programming or structured text		
	Online Editing		The program can be changed during operation (in MONITOR or PROGRAM mode), except for block programming areas.		
	Force-Set/Reset		Specified bits can be set or reset.  Force-set/reset to the EM Area is enabled by specifying a start bank in parameter setting.  (unit version 1.2 or higher)		
	Differentiate Monit	toring	ON/OFF changes in specified bits can be monitored.		
Debugging	Data Tracing		The specified I/O memory data can be stored in the trace memory in the CPU Unit. The triggers can be set.  • The trace data can be uploaded during data tracing using CX-Programmer, which enables continuously logging the data by constantly uploading the trace data (trace data uploading during tracing).  • Data tracing can be automatically started when operation is started (i.e., when the operating mode is changed from PROGRAM mode to MONITOR or RUN mode).		
	Storing Location of	of Error when an Error Occurs	The location and task number where execution stopped for a program error is recorded.		
	Program Check		The programs can be checked for items such as no END instruction and FALS/FAL errors at		
			startup.		

	Funct	ion		Description	
	Error Log			A function is provided to store predefined error codes in CPU Unit, error information, and time at which the error occurred.	
	CPU Error Detection	on		CPU Unit WDT errors are detected.	
	User-defined Failure Diagnosis		iagnosis	Errors can be generated for user-specified conditions: Non-fatal errors (FAL) and fatal errors (FALS).	
			<b>-</b>	Program section time diagnosis and program section logic diagnosis are supported (FPD instruction).	
	Load OFF Function			This function turns OFF all outputs from Output Units when an error occurs.	
	RUN Output			The RUN output from the CJ1W-PA205R turns ON while CPU Unit is in RUN mode or MONITOR mode.	
	Basic I/O Load Sho	ort-c	ircuit Detection	This function provides alarm information from Basic I/O Units that have load short-circuit protection.	
	Failure Point Detection		ļ	The time and logic of an instruction block can be analyzes using the FPD instruction.	
	CPU Standby Detection			This function indicates when the CPU Unit is on standby because all Special I/O Units and CPU Bus Units have not been recognized at the startup in RUN or MONITOR mode.	
	System FAL Error Detection (User-defined non-fatal error)		stem FAL Error Detection ser-defined non-fatal error)	This function generates a non-fatal (FAL) error when the user-defined conditions are met in program.	
			plicate Refreshing Error tection	This function detects an error when an immediate refreshing Instruction in an interrupt task is competing with I/O refreshing of a cyclic task.	
			sic I/O Unit Error Detection	This function detects the errors in Basic I/O Units.	
			ckup Memory Error tection	This function detects errors in the memory backup of the user programs and parameter area (backup memory).	
	Non-fatal Error	PL	C Setup Error Detection	This function detects setting errors in the PLC Setup.	
	Detection		U Bus Unit Error Detection	This function detects an error when there is an error in data exchange between the CPU Unit and a CPU Bus Unit.	
		Special I/O Unit Error Detection		This function detects an error when there is an error in data exchange between the CPU Unit and a Special I/O Unit.	
		Battery Error Detection		This function detects an error when a battery is not connected to the CPU Unit or when the battery voltage drops.	
		CPU Bus Unit Setting Error Detection		This function detects an error when the model of a CPU Bus Unit in the registered I/O tables does not agree with the model that is actually mounted in the PLC.	
Self-	Special I/O Unit Setting Error Detection			This function detects an error when the model of a Special I/O Unit in the registered I/O tables does not agree with the model of Unit that is actually mounted.	
	Memory Error Detection  I/O Bus Error Detection  Unit/Rack Number Duplication Error  Too Many I/O Points Error Detection		mory Error Detection	This function detects errors that occur in memory of the CPU Unit.	
diagnosis and Restoration			Bus Error Detection	This function detects when an error occurs in data transfers between the Units mounted in Rack slots and the CPU Unit and detects when the End Cover is not connected to the CPU Rack or an Expansion Rack.	
				This function detects an error when the same unit number is set for two or more Units, the same word is allocated to two or more Basic I/O Units, or the same rack number is set for two or more Racks.	
				This function detects an error when the total number of I/O points set in the I/O tables or the number of Units per Rack exceeds the specified range.	
		I/O Setting Error Detection		This function detects an error when the number of Units in the registered I/O tables does not agree with the actual number of Units that is mounted, or an Interrupt Unit has been connected in the wrong position, i.e., not in slot 0 to 4.	
		Program Error Detection		This function detects errors in programs.	
			Instruction Processing Error Detection	This function detects an error when the given data value is invalid when executing an instruction, or execution of instruction between tasks was attempted.	
	Fatal Error Detection		Indirect DM/EM BCD Error Detection	This function detects an error when an indirect DM/EM address in BCD mode is not BCD.	
			Illegal Area Access Error Detection	This function detects an error when an attempt is made to access an illegal area with an instruction operand.	
			No END Error Detection	This function detects an error when there is no END instruction at the end of the program.	
			Task Error Detection	This function detects an error when there are no tasks that can be executed in a cycle, there is no program for a task, or the execution condition for an interrupt task was met but there is no interrupt task with the specified number.	
			Differentiation Overflow Error Detection	This function detects an error when too many differentiated instructions are entered or deleted during online editing (131,072 times or more).	
			Invalid Instruction Error Detection	This function detects an error when an attempt is made to execute an instruction that is not defined in the system.	
			User Program Area Overflow Error Detection	This function detects an error when instruction data is stored after the last address in user program area.	
			cle Time Exceeded Error	This function monitors the cycle time (10 to 40,000 ms) and stops the operation when the set value is exceeded.	
		Sy	stem FALS Error Detection ser-defined Fatal Error)	This function generates a fatal (FALS) error when the user-defined conditions are met in program.	
	Fatal Error Detection (Continued from	Ť	rsion Error Detection	This function detects an error when a user program includes a function that is not supported by the current unit version.	
	previous page)		emory Card Transfer Error	This function detects an error when the automatic file transfer from Memory Card fails at startup.	
	Memory Self-resto	1		This function performs a parity check on the user program area and self-restoration data.	
	memory dentestoration function				

	Function		Description
	Simple Backup Function		This function collectively backs up the data in CPU Unit (user programs, parameters, and I/O memory) and internal backup data in the I/O Units.
	Unsolicited Communications		A function that allows the PLC to use Network Communications Instruction to send required FINS commands to a computer connected via a Host Link
Maintenance	Remote Programming and Monitoring		Host Link communications can be used for remote programming and remote monitoring through a Controller Link, Ethernet, DeviceNet, or SYSMAC LINK Network. Communications across network layers can be performed.  Controller Link or Ethernet: 8 layers  DeviceNet or SYSMAC LINK: 3 layers
	Automatic Online Connection via Network Direct Serial Connection		This function enables automatically connecting to the PLC online when the CX-Programmer is directly connected by a serial connection (peripheral (USB) port or serial port).
	Read Protection using Password	•	This function protects reading and displaying programs and tasks using passwords. Write protection: Set using the DIP switch. Read protection: Set a password using the CX-Programmer.
Casumitus	FINS Write Protection		This function prohibits writing by using FINS commands sent over the network.
Security	Unit Name Function		This function allows the users to give any names to the Units. Names are verified at online connection to prevent wrong connection
	Hardware ID Using Lot Numbers		This function sets operation protection by identifying hardware using the user programs according to lot numbers stored in the Auxiliary Area.

# **Unit Versions**

Units	Models	Unit version
		Unit version 1.4
CJ2H CPU Units	CJ2H-CPU6□	Unit version 1.3
CJZH CPO OTIIIS	C32H-CF06	Unit version 1.2
		Unit version 1.1 *

<sup>\*</sup>Although the product of unit version 1.0 does not exist for the CJ2H CPU unit (CJ2H-CPU6□), this unit version 1.1 means that the functions are added based on the same functionality as CJ2H-CPU6□-EIP unit version 1.0.

# **Function Support by Unit Version**

## **Unit Version 1.4 or Later**

CX-Programmer version 9.3 or higher must be used to enable using the functions added for unit version 1.4.

Unit	CJ2H CPU Unit		
Model	CJ2H-CPU6□		
Unit version Item	Unit version 1.4 or higher	Unit version 1.3 or earlier	
Synchronous unit operation function Position Control Units with EtherCAT interface CJ1W-NC□82 work for synchronous unit operation.	Supported.	Not supported.	

## **Unit Version 1.3 or Later**

CX-Programmer version 9.1 or higher must be used to enable using the functions added for unit version 1.3.

	Unit	CJ2H CPU Unit		
	Model	CJ2H-CPU6□		
Item	Unit version	Unit version 1.3 or later	Unit version 1.2 or earlier	
Special instructions for certain	CJ1W-NC281/NC481/NC881 Position Control Units: PCU HIGH-SPEED POSITIONING (NCDMV(218))	Supported.	Not supported.	
Special I/O Units	CJ1W-NC281/NC481/NC881 Position Control Units: PCU POSITIONING TRIGGER (NCDTR(219))	Supported.	Not supported.	
New special instructions	SIGNED AREA RANGE COMPARE: ZCPS(088)	Supported.	Not supported.	
New special instructions	DOUBLE SIGNED AREA RANGE COMPARE: ZCPSL(116)	Supported.	Not supported.	

## **Unit Version 1.2 or Later**

CX-Programmer version 8.3 or higher must be used to enable using the functions added for unit version 1.2.

Unit	CJ2H CPU Unit		
Model	CJ2H-CPU6□		
Unit version	Unit version 1.2 or higher	Unit version 1.1 or earlier	
EM force-set/reset function	Supported.	Not supported.	

Note: User programs that use functions of CJ2H CPU Units with unit version 1.2 or later cannot be used with CJ2H CPU Units with unit version 1.1 or earlier. If an attempt is made to transfer a program that uses any of these functions from the CX-Programmer to a CPU Unit with unit version 1.1 or earlier, an error will be displayed and it will not be possible to download to the CPU Unit.

### **Unit Version 1.1 or Later**

CX-Programmer version 8.1 or higher must be used to enable using the functions added for unit version 1.1.

Note: Although the product of unit version 1.0 does not exist for the CJ2H CPU unit (CJ2H-CPU6□), it describes here assuming that the functions are added with unit version 1.1 to the unit version 1.0 functions as well as CJ2H-CPU6□-EIP.

Unit	CJ2H CPU Unit	
Model	CJ2H-CPU6□	
Unit version Item	Unit version 1.1 or higher	
High-speed interrupt function Decreased overhead time for interrupt tasks Minimum interval setting of 0.1 ms for Scheduled Interrupt Task	Supported.	
Changing the minimum cycle time setting in MONITOR mode	Supported.	
Synchronous unit operation function Position Control Units (High-speed type) CJ1W-NC□□4 work for synchronous unit operation.	Supported.	
Addition of Immediate refreshing instruction only for specific Special I/O Units and CPU Bus Units For CJ1W-AD042: Analog Input Direct Convert AIDC (216) For CJ1W-DA042V: Analog Output Direct Convert AODC (217) For CJ1W-SCU22/32/42: Direct Receive Via Serial Communications Unit DRXDU (261) Direct Transmit Via Serial Communications Unit DTXDU (262)	Supported.	

# **Unit Versions and Programming Devices**

The following tables show the relationship between unit versions and CX-Programmer versions.

#### **Unit Versions and Programming Devices**

	Functions		Required Programming Device						
CPU Unit			CX-Programmer					D	
Or O Onne			Ver. 7.1 or lower	Ver.8.0	Ver.8.1/ Ver.8.2	Ver. 8.3	Ver. 9.1/9.2	Ver. 9.3 or higher	Programming Console
O IOLI ODLIG	Functions	Using new functions	_	-	-	-	-	OK	
Unit version 1.4 CJ2H-CPU6□ added for ur version 1.4	added for unit version 1.4	Not using new functions	_	OK <b>*</b> 1	OK *1	ОК	ОК	ОК	
Unit version 1.3 added for		Using new functions	-	-	-	_	OK	OK	
		Not using new functions	_	OK *1	OK <b>*</b> 1	OK	ОК	ОК	de O
Unit version 1.2 added for	Functions	Using new functions	-	-	-	OK	OK	OK	<b>- *</b> 3
	added for unit version 1.2	Not using new functions	_	OK *1	OK *1	ОК	ОК	ОК	
CJ2H-CPU6□ Unit version 1.1	Functions added for unit version 1.1	Using new functions	-	-	OK <b>*</b> 2	OK	OK	OK	
		Not using new functions	-	-	ок	ОК	ОК	ОК	

<sup>\*1.</sup> It is not necessary to upgrade the version of the CX-Programmer if functionality that was enhanced for the upgrade of the CPU Unit will not be used.
\*2. CX-Programmer version 8.2 or higher is required to use CJ2 CPU Units (CJ2H-CPU6□). However the functions of unit version 1.0 and only High-speed interrupt function and Changing the minimum cycle time setting in MONITOR mode are supported in CX-Programmer version 8.02.
\*3. A Programming Console cannot be used with a CJ2H CPU Unit.

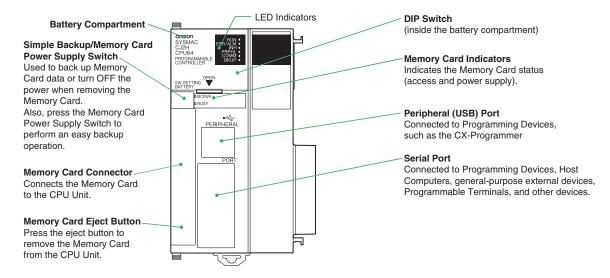
# **Device Type Setting**

The unit version does not affect the setting made for the device type on the CX-Programmer. Select the device type as shown in the following table regardless of the unit version of the CPU Unit.

Series	CPU Unit group	CPU Unit model	Device type setting on CX-Programmer Ver. 8.0 or higher
CJ Series	CJ2H CPU Units	CJ2H-CPU6□	CJ2H

# **External Interface**

A CJ2H CPU Unit (CJ2H-CPU6 ) provides two communications ports for external interfaces: a peripheral (USB) port and a serial port.



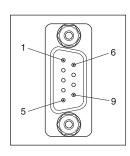
### Peripheral (USB) Port

Item	Specification		
Baud Rate	12 Mbps max.		
Transmission Distance	5 m max.		
Interface	USB 2.0-compliant B-type connector		
Protocol	Peripheral Bus		

#### Serial Port

Item	Specification
Communications method Half duplex	
Synchronization Start-stop	
Baud rate 0.3/0.6/1.2/2.4/4.8/9.6/19.2/38.4/57.6/115.2 kbps *	
Transmission distance 15 m max.	
Interface EIA RS-232C	
Protocol Host Link, NT Link, 1:N, No-protocol, or Peripheral Bus	

<sup>\*</sup>Baud rates for the RS-232C are specified only up to 19.2 kbps. The CJ Series supports serial communications from 38.4 kbps to 115.2 kbps, but some computers cannot support these speeds. Lower the baud rate if necessary.



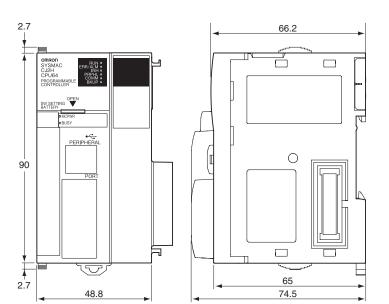
Pin No.	Signal	Name	Direction
1	FG	Protection earth	_
2	SD (TXD)	Send data	Output
3	RD (RXD)	Receive data	Input
4	RS (RTS)	Request to send	Output
5	CS (CTS)	Clear to send	Input
6	5 V	Power supply	_
7	DR (DSR)	Data set ready	Input
8	ER (DTR)	Data terminal ready	Output
9	SG (0 V)	Signal ground	_
Connector hood	FG	Protection earth	-

Note: Do not use the 5-V power from pin 6 of the RS-232C port for anything but CJ1W-CIF11 RS-422A Conversion Adapter, NT-AL001 RS-232C/RS-422A Conversion Adapter and NV3W-M□20L(-V1) Programmable Terminal. The external device or the CPU Unit may be damaged.

Dimensions (Unit: mm)

CJ2H CPU Unit CJ2H-CPU6□





# **Related Manuals**

Cat. No.	Model	Manual	Application	Description
W472	CJ2H-CPU6□-EIP CJ2H-CPU6□ CJ2M-CPU□□	CJ-series CJ2 CPU Unit Hardware User's Manual	Hardware specifications for CJ2 CPU Units	Describes the following for CJ2 CPU Units:  Overview and features Basic system configuration Part nomenclature and functions Mounting and setting procedure Remedies for errors Also refer to the Software User's Manual (W473).
W473	CJ2H-CPU6□-EIP CJ2H-CPU6□ CJ2M-CPU□□	CJ-series CJ2 CPU Unit Software User's Manual	Software specifications for CJ2 CPU Units	Describes the following for CJ2 CPU Units:  • CPU Unit operation  • Internal memory  • Programming  • Settings  • Functions built into the CPU Unit  Also refer to the Hardware User's Manual (W472)
W474	CJ2H-CPU6  -EIP CJ2H-CPU6   CJ2M-CPU3   CS1G/H-CPU  -  CS1G/H-CPU  -  CJ1G/H-CPU  -  CJ1G-CPU  -  CJ1M-CPU  -  CS1D-CPU  -	CS/CJ/NSJ-series Instructions Reference Manual	Information on instructions	Describes each programming instruction in detail. Also refer to the <i>Software User's Manual</i> (W473) when you do programming.
W342	CJ2H-CPU6 - EIP CJ2H-CPU6 - CJ2M-CPU - CJ2M-CPU - CS1G/H-CPU - H CS1G/H-CPU - HA CS1D-CPU - HA CS1D-CPU - SA CS1D-CPU - S CS1W-SCU - V1 CS1W-SCB - V1 CJ1H-CPU - H-R CJ1G/H-CPU - H-R CJ1G/H-CPU - H CJ1G-CPU - CJ1W-CPU - C	CS/CJ/CP/NSJ-series Communications Command Reference Manual	Information on communications for CS/CJ/CP-series CPU Units and NSJ-series Controllers	Describes C-mode commands and FINS commands Refer to this manual for a detailed description of commands for communications with the CPU Unit using C mode commands or FINS commands.  Note: This manual describes the communications commands that are addressed to CPU Units. The communications path that is used is not relevant and can include any of the following: serial ports on CPU Units, communications ports on Serial Communications Units/Boards, and Communications Units. For communications commands addressed to Special I/O Units or CPU Bus Units, refer to the operation manual for the related Unit.
W463	CXONE-AL D-V	CX-One Setup Manual	Installing software from the CX- One	Provides an overview of the CX-One FA Integrated Tool Package and describes the installation procedure.
W446		CX-Programmer Operation Manual		
W447	WS02-CXPC□-V□	CX-Programmer Operation Manual Functions Blocks/ Structured Text	Support Software for Windows computers  CX-Programmer operating	Describes operating procedures for the CX-Programmer. Also refer to the <i>Software User's Manual</i> (W473) and <i>Instructions Reference Manual</i> (W474) when you do programming.
W469		CX-Programmer Operation Manual SFC Programming	procedure	programming.
W366	WS02-SIMC1-E	CS/CJ/CP/NSJ-series CX-Simulator Operation Manual	Operating procedures for CX- Simulator Simulation Support Software for Windows computers Using simulation in the CX- Programmer with CX- Programmer version 6.1 or higher	Describes the operating procedures for the CX-Simulator. When you do simulation, also refer to the CX-Programmer Operation Manual (W446), Software User's Manual (W473), and CS/CJ/NSJ series Instructions Reference Manual (W474).
W464	CXONE-AL□□D-V□	CS/CJ/CP/NSJ-series CX-Integrator Network Configuration Software Operation Manual	Network setup and monitoring	Describes the operating procedures for the CX-Integrator.

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